

The Z transform (2)

Today

- Properties of the region of convergence (3.2)
- Read examples 3.7, 3.8

Announcements:

- ELEC 310 FINAL EXAM:
April 14 2010, 14:00 pm ECS 123
- Assignment 2 due tomorrow by 4:00 pm

Observations

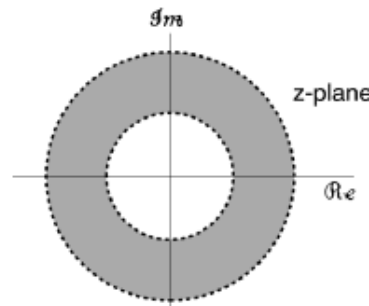
- Specification of the Z transform requires both algebraic expression and region of convergence
- Rational Z-transforms are obtained if $x[n]$ =linear combination of exponentials for $n>0$ and $n<0$

$$X(z) = \frac{N(z)}{D(z)} \begin{array}{l} \nwarrow \\ \swarrow \end{array} \text{Polynomials in } z$$

- Rational Z-transforms are completely characterized by their poles and zeros (except for the gain)

Properties of the ROC of the Z-transform

1. The ROC of $X(z)$ consists of a ring in the z -plane centered about the origin
 - Convergence is dependent only on r , not on ω
 - In some cases, the inner boundary can extend inward to the origin (ROC=disc)
 - In other cases, the outer boundary can extend outward to infinity (ROC= the exterior of a circle)



Properties of the ROC of the Z-transform

- 2. The FT of $x[n]$ is convergent if and only if the ROC of the ZT of $x[n]$ contains the unit circle
- Proof:

Properties of the ROC of the Z-transform

- **3. The ROC does not contain any poles**

Proof: At a pole $X(z)$ is infinite and therefore does not converge.

Properties 4, 5, 6, and 7 are consequences of 1 and 3.

Properties of the ROC of the Z-transform

4. If $x[n]$ is of finite duration, then the ROC is the entire z -plane, except possibly $z=0$ and/or $z=\infty$.

Proof:

As $|z| \rightarrow 0$ terms involving negative powers of z become unbounded.

As $|z| \rightarrow \infty$ terms involving positive powers of z become unbounded.

We need to explore three cases:

$$X(z) = \sum_{n=N_1}^{N_2} x[n]z^{-n}$$

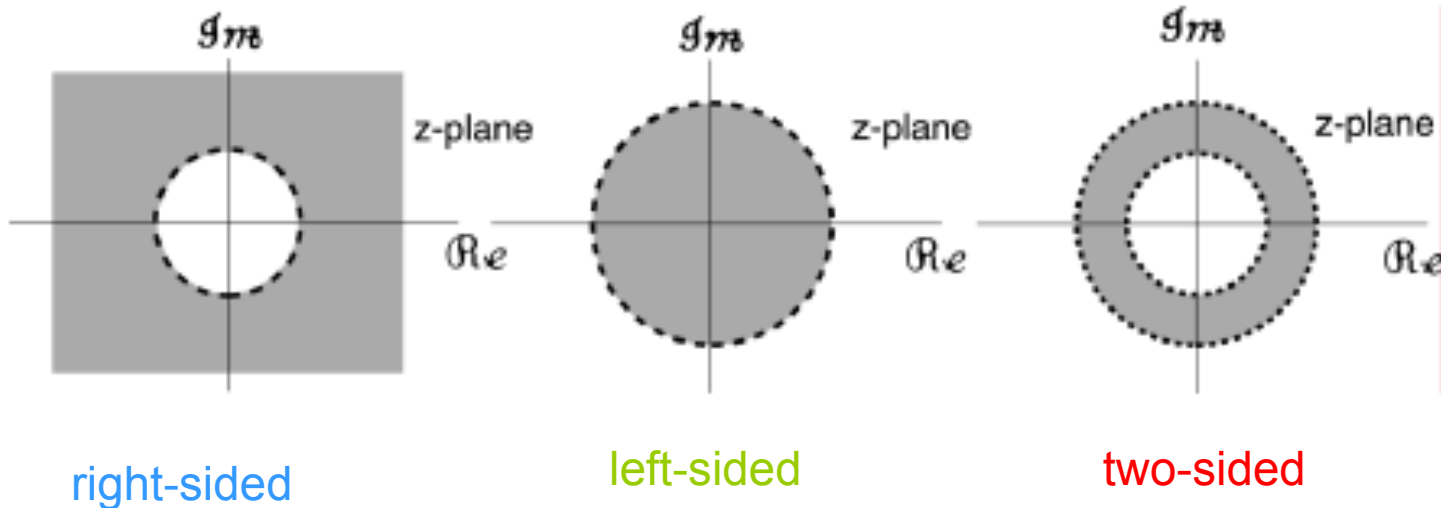
$N_1 \geq 0$ summation includes only terms with negative powers.
ROC includes $z=\infty$

$N_2 \leq 0$ summation includes only terms with positive powers.
ROC includes $z=0$

$N_1 < 0, N_2 > 0$ summation includes terms with both positive and negative powers of z . $z=0$ and $z=\infty$ are not in the ROC.

Properties of the ROC of the Z-transform

- 5. If $x[n]$ is a **right-sided** sequence, the ROC extends outward from the outermost finite pole in $X(z)$, possibly including $z=\infty$
- 6. If $x[n]$ is a **left-sided** sequence, the ROC extends inward from the innermost finite pole in $X(z)$, possibly including $z=0$
- 7. If $x[n]$ is **two-sided**, the ROC is a ring in the z -plane bounded on the interior and exterior by poles.



Properties of the ROC of the Z-transform

- **8. The ROC must be a connected region.**
 - This is a direct consequence of property 1 (which specifies three possible shapes of the ROC).
 - It is useful for evaluating the existence of ZT when $x[n]$ is a sum of two sequences, one left-sided and the other right-sided
 - See example 3.7

Stability, causality, and the ROC

- We can evaluate the stability and causality of LTI systems in the Z-domain.
- Suppose our LTI system is given by $h[n]$, by $H(e^{j\omega})$ in the frequency domain, and by $H(z)$ in the z-domain
 - The system is causal if $h[n]=0$ for $n<0$ (right-sided)
The ROC of a causal system is the exterior of a circle (property 5), and it contains $z=\infty$
 - The system is anti-causal if $h[n]=0$ for $n>0$ (left-sided)
The ROC of an anti-causal system is the interior of a circle (property 6) and it contains $z=0$.

Stability, causality, and the ROC (cont'd)

- The LTI system is stable if and only if $h[n]$ is absolutely summable (which is equivalent to the fact that $H(e^{j\omega})$ exists)
- Using Property 2 of ROC, we conclude that:

The ROC of a stable system include the unit circle ($|z|=1$)

See example 3.8

Example 1.

- Let $x[n]$ be an absolutely summable signal with rational Z-transform $X(z)$. If $X(z)$ is known to have a pole at $z=1/2$, could $x[n]$ be:
 - a) a finite-duration signal?
 - b) a left-sided signal?
 - c) a right-sided signal?
 - d) a two-sided signal?

Example 2

- Find the Z-Transform, the ROC and the Fourier Transform (if it exists) of the following signals:

$$a) x[n] = 3\delta[n-1] - \delta[n-2] + 2\delta[n-3]$$

$$b) x[n] = \begin{cases} \left(\frac{1}{3}\right)^n \cos\left(\frac{\pi}{4}n\right) & n \leq 0 \\ 0 & n > 0 \end{cases}$$

Summary

- The properties of the ROC depend on the nature of the signal. We assume the the ZT is a rational function.
- There are 8 main properties, stated on p. 111.
- Evaluation of causality and stability in the Z-domain
 - causal LTI: $H(z)$ has the ROC represented by the exterior of a circle and including $z=\infty$
 - anti-causal LTI: $H(z)$ has the ROC represented by the interior of a circle and including $z=0$
 - stable LTI: the ROC of $H(z)$ includes the unit circle.