

Structures for LTI systems (2)

Outline

Block diagrams continued

- Example 1 - 1st order difference equations
- 2nd order difference equations
- Classification of block diagrams
- examples

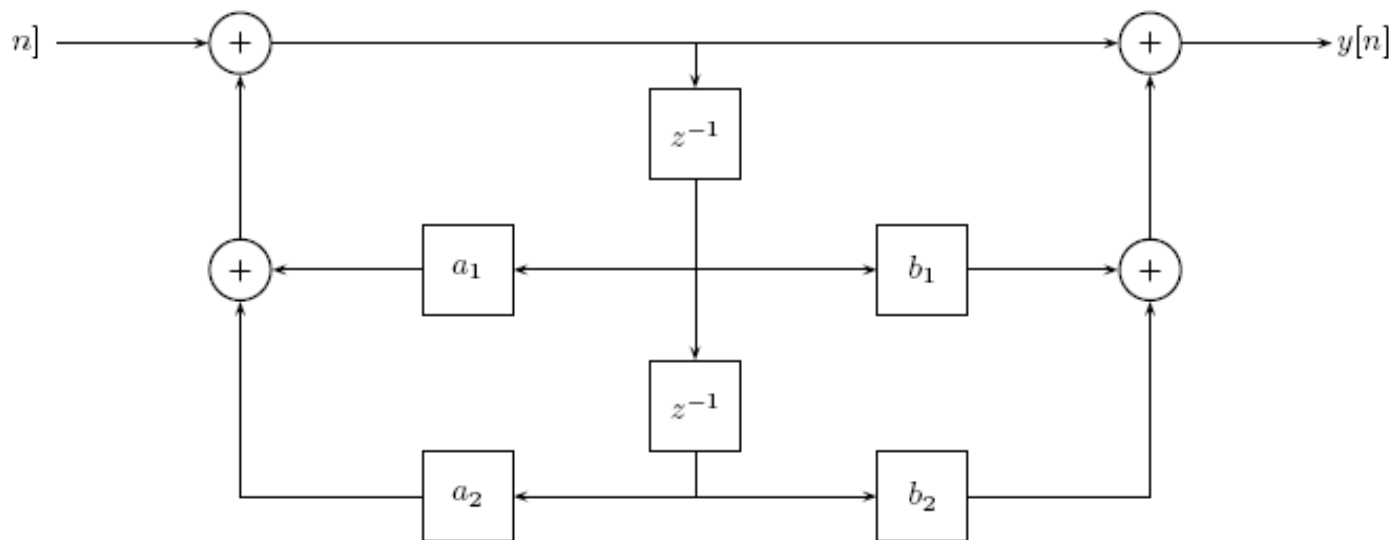
Example 1

- A causal, digital filter structure is given by a block diagram (sketched on the board).
- a) Find $H(z)$ for this causal filter. Plot the zero-pole pattern and indicate the region of convergence.
- b) For what values of K is the system stable?
- c) Determine $y[n]$ if $k=1$ and $x[n] = \left(\frac{2}{3}\right)^n$ for all n

Block diagram representations for second order systems

$$y[n] - a_1 y[n-1] - a_2 y[n-2] = x[n] + b_1 x[n-1] + b_2 x[n-2]$$

$$H(z) = \frac{Y(z)}{X(z)} = \frac{1 + b_1 z^{-1} + b_2 z^{-2}}{1 - a_1 z^{-1} - a_2 z^{-2}}$$



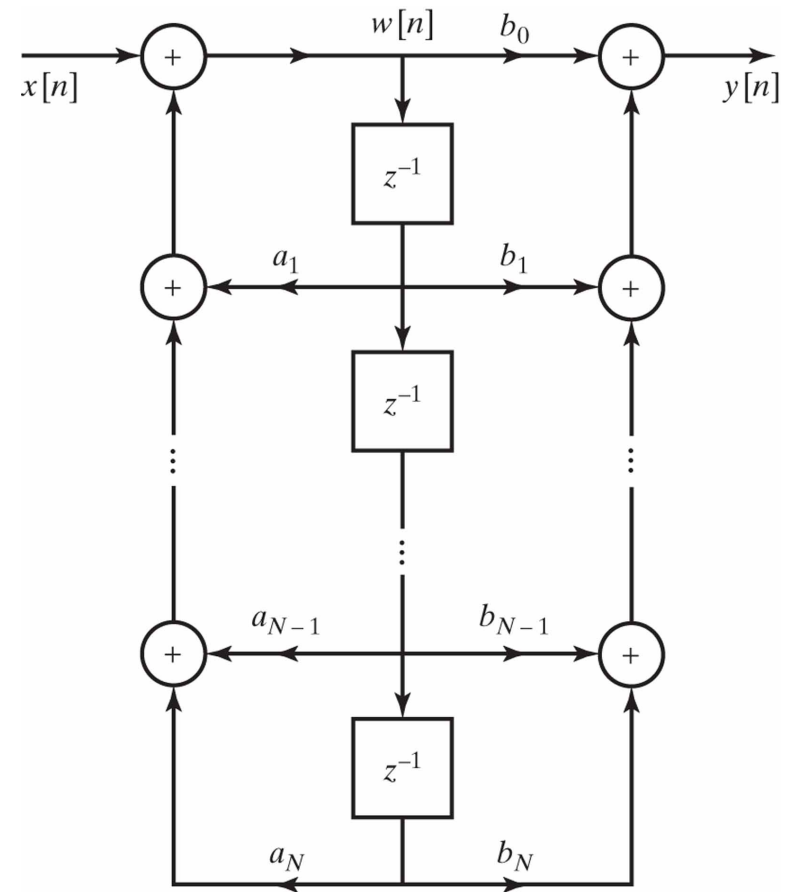
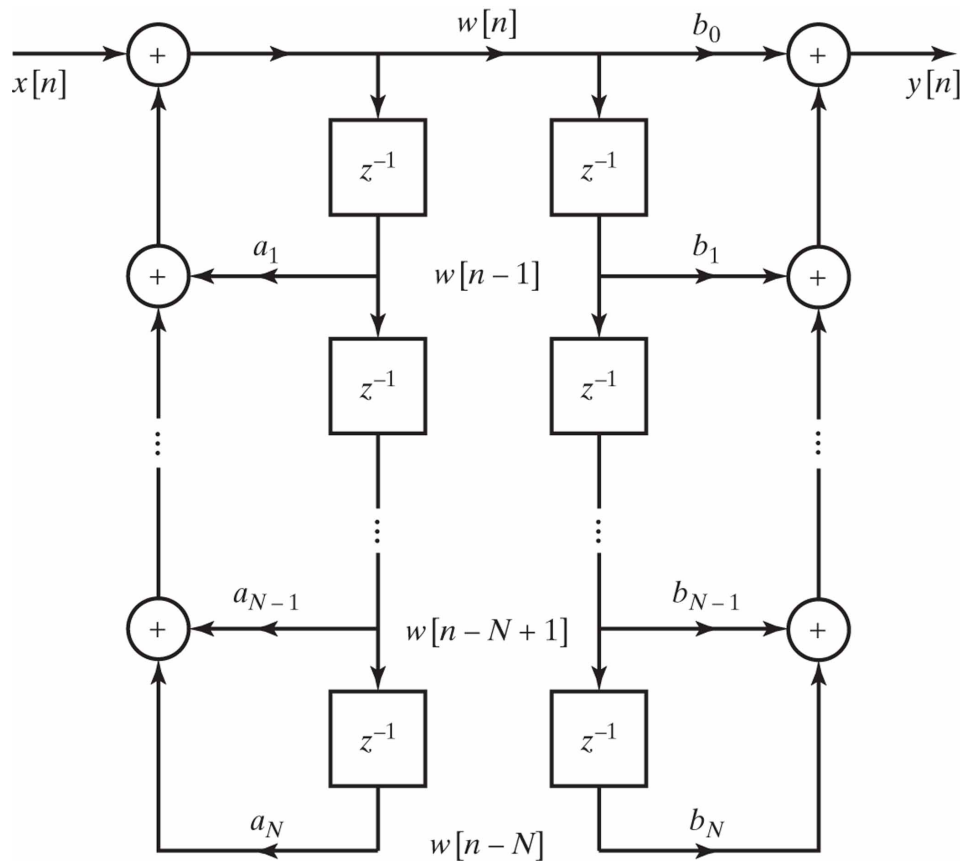
Classification of block diagram representations

- Direct form:
 - draw using $H(z)$ as expressed directly for the difference equation
 - Direct Form 1
 - Direct Form 2
- Cascade form
 - Whenever we express $H(z)$ as a **product** of simpler blocs $H_1(z)$, $H_2(z)$, $H_3(z)$ etc.
- Parallel form
 - Whenever we express $H(z)$ as a **sum** of simpler blocs $H_1(z)$, $H_2(z)$, $H_3(z)$ etc.
 - These blocs can come from partial fraction expansion

Observations

- all forms are equivalent
- Cascade and parallel forms are **not** unique

Direct Forms I and II for nth order equations



Example 2

- Consider the system function $H(z) = \frac{1 - \frac{7}{4}z^{-1} - \frac{1}{2}z^{-2}}{1 + \frac{1}{4}z^{-1} - \frac{1}{8}z^{-2}}$
- a) Draw its direct form II representation
- b) Draw its cascade form representation based on the fact that

$$H(z) = \left(\frac{1 + \frac{1}{4}z^{-1}}{1 + \frac{1}{2}z^{-1}} \right) \left(\frac{1 - 2z^{-1}}{1 - \frac{1}{4}z^{-1}} \right)$$

- c) Draw its parallel form representation based on the fact that

$$H(z) = 4 + \frac{5/3}{1 + \frac{1}{2}z^{-1}} - \frac{14/3}{1 - \frac{1}{4}z^{-1}}$$