

Storage-Efficient Quasi-Newton Algorithms for Image Super-Resolution

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- Conclusions

Motivation

- In our ISCAS 2008 and CCECE 2009 papers, we have shown that efficient quasi-Newton implementations of the Farsiu et al. grayscale and color super-resolution algorithms based on the Broyden, Fletcher, Goldfarb, and Shanno (BFGS) method lead to *improved speed and reconstruction quality*.

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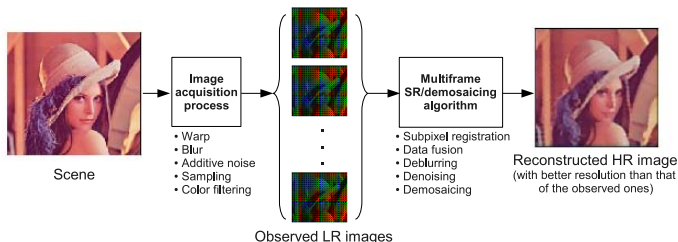
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- As will be demonstrated, these algorithms require *reduced and controllable storage* while retaining the *speed advantage* as well as the *improved reconstruction quality* associated with the BFGS algorithm.

Super-Resolution

- Super-resolution can be used to fuse several blurry, undersampled, and noisy low-resolution images of a scene, referred to as *frames*, into a high-quality high-resolution image.



Frame Acquisition Models

- After lexicographical reordering, grayscale and color low-resolution frame sets can be represented by

$$\mathbf{y}_k = \mathbf{D}\mathbf{H}\mathbf{F}_k\mathbf{x} + \boldsymbol{\nu}_k, \quad k = 1, \dots, N$$

and

$$\mathbf{y}_{i,k} = \mathbf{D}_i\mathbf{H}\mathbf{F}_k\mathbf{x}_i + \boldsymbol{\nu}_{i,k}, \quad k = 1, \dots, N \quad i = R, G, B$$

respectively, where

$\mathbf{F}_k$ is the warp matrix

$\mathbf{H}$ is the blur matrix

$\mathbf{D}$ is the downsampling matrix

$\mathbf{D}_i$ are the downsampling plus color filtering matrices

$\boldsymbol{\nu}$, $\boldsymbol{\nu}_i$ are additive noise vectors

$\mathbf{y}_k$, $\mathbf{y}_{i,k}$ are the k th LR Frame and i th color component of the k th LR frame

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- For color SR:

$$\hat{\mathbf{x}}_C = \underset{\mathbf{x}}{\text{ArgMin}} [f_C(\mathbf{x})] = \underset{\mathbf{x}}{\text{ArgMin}} [J_0(\mathbf{x}) + \lambda J_1(\mathbf{x}) + \lambda' J_2(\mathbf{x}) + \lambda'' J_3(\mathbf{x})]$$

where

$J_0(\mathbf{x})$ is the data fidelity term (L_1 -norm distance measure)

$J_1(\mathbf{x})$ is the luminance spatial regularization (total variation-based)

$J_2(\mathbf{x})$ is the chrominance spatial regularization (Tikhonov-based)

$J_3(\mathbf{x})$ represents the intercolor dependencies (RGB edge consistency)

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 - Fast convergence (they take a more direct path to the minimizer)
 - Better performance in numerically ill-conditioned problems such as the super-resolution problem
 - The step size is adaptively recalculated by the algorithm in each iteration

Quasi-Newton-Based Reconstruction

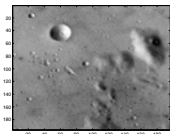
■ Quasi-Newton algorithms involve the following basic steps:

- $\hat{\mathbf{x}}_{n+1} = \hat{\mathbf{x}}_n + \beta_n \mathbf{d}_n$
- $\mathbf{d}_n = -\mathbf{S}_n \mathbf{g}_n$
- $\mathbf{g}_n = \nabla f(\mathbf{x}_n)$
- $\mathbf{S}_n \approx \mathbf{H}^{-1}(\hat{\mathbf{x}}_n)$
- $\beta_n = \text{ArgMin}_{\beta} f(\hat{\mathbf{x}}_n + \beta \mathbf{d}_n)$ is found using an inexact line search.

Algorithm	Search direction	Storage requirements
BFGS	$\mathbf{d}_{n+1}(\mathbf{x}_0, \mathbf{x}_1, \dots, \mathbf{x}_{n+1}, \mathbf{g}_0, \mathbf{g}_1, \dots, \mathbf{g}_{n+1})$	Large
LBFGS	$\mathbf{d}_{n+1}(\mathbf{x}_{n-M+1}, \dots, \mathbf{x}_{n+1}, \mathbf{g}_{n-M+1}, \dots, \mathbf{g}_{n+1})$	Moderate
MBFGS	$\mathbf{d}_{n+1}(\mathbf{x}_n, \mathbf{x}_{n+1}, \mathbf{g}_n, \mathbf{g}_{n+1})$	Low

Simulation Results

- From 3 different grayscale 192×192 -pixel images, we generated 9 LR sets with different amounts of blur and noise:



‘Moon’



‘Lena’



‘Baboon’

LR Set Type	SNR (dB)	Blur σ (pixels)
a	24	1
b	24	3
c	18	1

$N = 16$, images obtained by applying uniform translational warping, Gaussian blur, a downsample factor of 4, and additive Gaussian noise.

Simulation Results, *Cont'd*

- Also, from 3 different color 192×192 -pixel images, we generated 12 LR sets with different amounts of blur and noise:



‘House’



‘Lena’



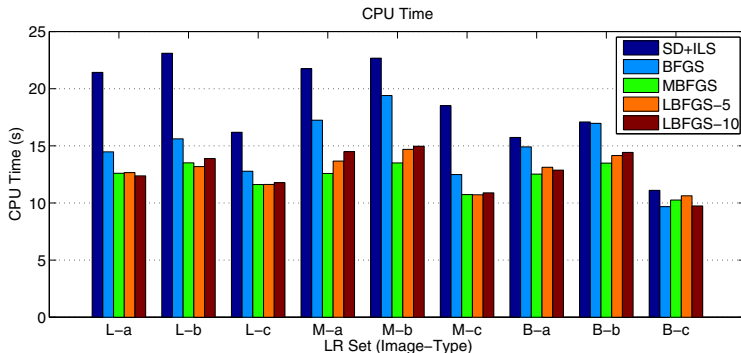
‘Baboon’

LR Set Type	SNR (dB)	Blur σ (pixels)
a	30	1
b	30	3
c	18	1
d	18	3

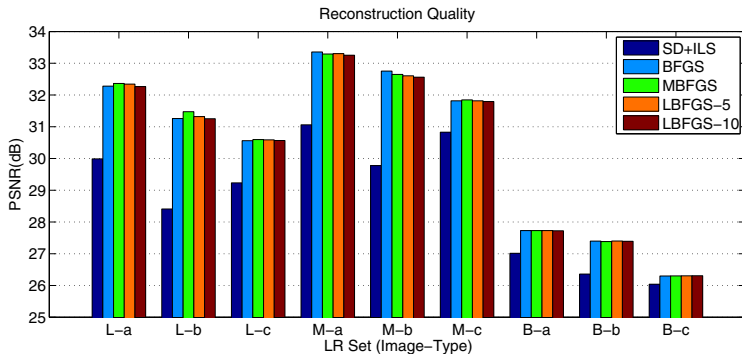
$N = 10$, images obtained by applying uniform translational warping, Gaussian blur, a downsample factor of 4, Bayer color filtering, and additive Gaussian noise.

- For each one of the 9 LR grayscale sets and the 12 LR color sets, we performed reconstruction using
 - the steepest-descent algorithm with β adaptively selected using an inexact line search.
 - the BFGS algorithm
 - the MBFGS algorithm
 - the LBFGS algorithm with $M = 5$, and another with $M = 10$

■ CPU time for grayscale super-resolution:

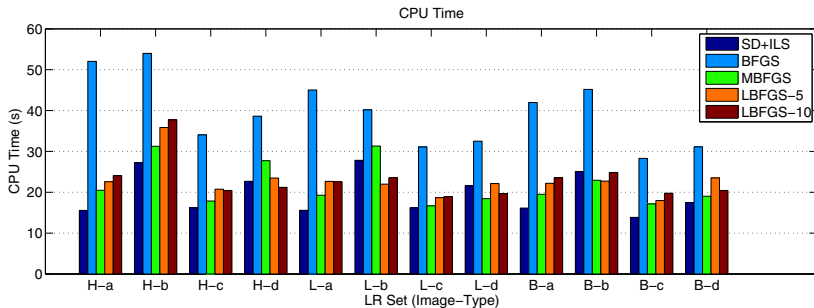


■ Reconstruction quality for grayscale super-resolution:

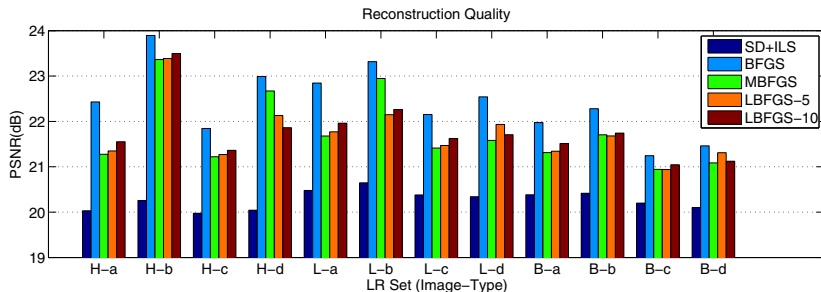


Simulation Results, *Cont'd*

■ CPU time for color super-resolution:



■ Reconstruction quality for color super-resolution:



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- The *MBFGS and LBFGS algorithms outperform the steepest-descent algorithms* while requiring negligible or limited additional storage.
- For grayscale super-resolution, the *MBFGS algorithm offers the best overall performance* in terms of speed, reconstruction quality, and storage requirements.
- For color super-resolution, the *LBFGS offers a meaningful compromise* between the amount of storage and computational effort required and the quality of the reconstruction.

Thank you for your attention.