

Example 7.8 (Linearity property of the Laplace transform). Find the Laplace transform of the function

$$x = x_1 + x_2,$$

where

$$x_1(t) = e^{-t}u(t) \quad \text{and} \quad x_2(t) = e^{-t}u(t) - e^{-2t}u(t).$$

Solution. Using Laplace transform pairs from Table 7.2, we have

$$\begin{aligned} \textcircled{1} \quad X_1(s) &= \mathcal{L}\{e^{-t}u(t)\}(s) \quad \text{from LT table} \\ &= \frac{1}{s+1} \quad \text{for } \operatorname{Re}(s) > -1 \quad \text{and} \\ \textcircled{2} \quad X_2(s) &= \mathcal{L}\{e^{-t}u(t) - e^{-2t}u(t)\}(s) \quad \text{linearity} \\ &= \mathcal{L}\{e^{-t}u(t)\}(s) - \mathcal{L}\{e^{-2t}u(t)\}(s) \quad \text{from LT table and } \textcircled{*} \\ &= \frac{1}{s+1} - \frac{1}{s+2} \quad \text{for } \operatorname{Re}(s) > -1 \\ &= \frac{1}{(s+1)(s+2)} \quad \text{for } \operatorname{Re}(s) > -1. \quad \text{common denominator} \end{aligned}$$

So, from the definition of X , we can write

$$\begin{aligned} X(s) &= \mathcal{L}\{x_1 + x_2\}(s) \\ &= X_1(s) + X_2(s) \quad \text{linearity} \\ &= \frac{1}{s+1} + \frac{1}{(s+1)(s+2)} \quad \text{substitute expressions for } x_1 \text{ and } x_2 \text{ in } \textcircled{1} \text{ and } \textcircled{2} \\ &= \frac{s+2+1}{(s+1)(s+2)} \quad \text{common denominator} \\ &= \frac{s+3}{(s+1)(s+2)}. \quad \text{simplify} \end{aligned}$$

$\textcircled{*} [\operatorname{Re}(s) > -2] \cap [\operatorname{Re}(s) > -1] = \operatorname{Re}(s) > -1$
 but is it larger than the intersection?

Now, we must determine the ROC of X . We know that the ROC of X must contain the intersection of the ROCs of X_1 and X_2 . So, the ROC must contain $\operatorname{Re}(s) > -1$. Furthermore, the ROC cannot be larger than this intersection, since X has a pole at -1 . Therefore, the ROC of X is $\operatorname{Re}(s) > -1$. The various ROCs are illustrated in Figure 7.9. So, in conclusion, we have

$$X(s) = \frac{s+3}{(s+1)(s+2)} \quad \text{for } \operatorname{Re}(s) > -1. \quad \blacksquare$$

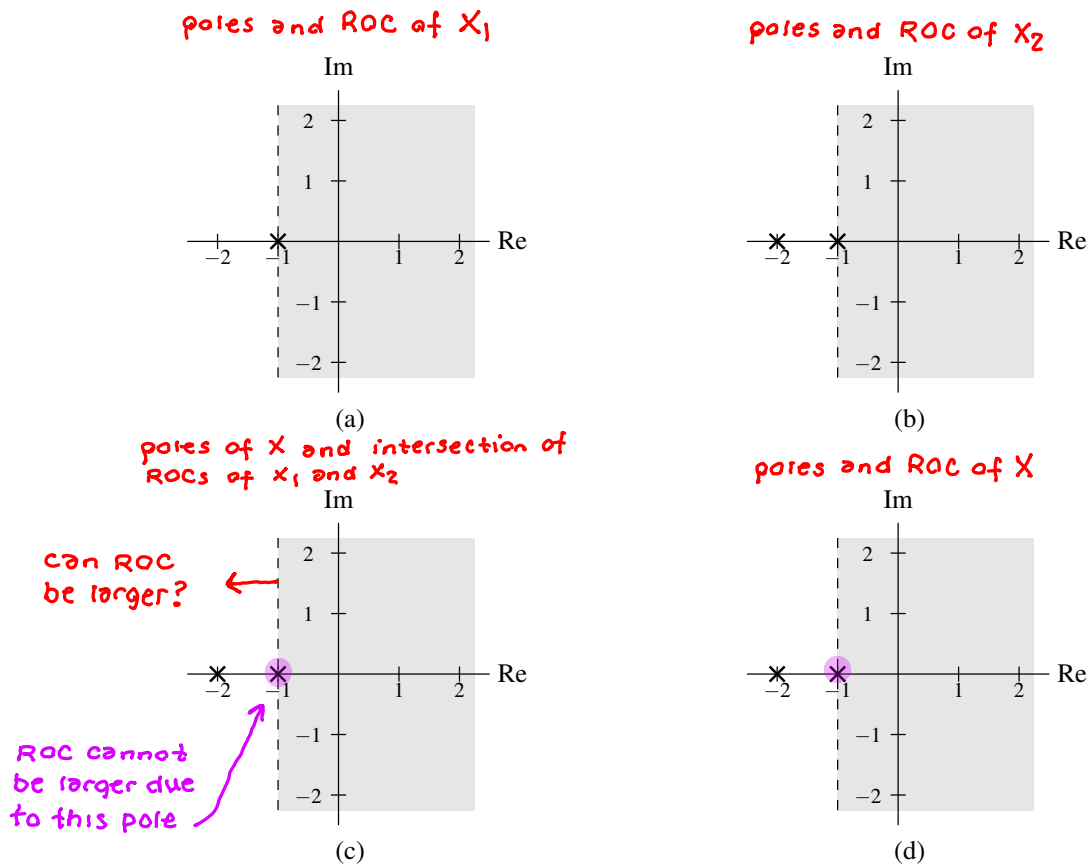


Figure 7.9: ROCs for the linearity example. The (a) ROC of X_1 , (b) ROC of X_2 , (c) ROC associated with the intersection of the ROCs of X_1 and X_2 , and (d) ROC of X .