Field Theory Design of Ferrite-Loaded Waveguide Nonreciprocal Phase Shifters with Multisection Ferrite or Dielectric Slab Impedance Transformers

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Abstract — Impedance-matched ferrite-loaded waveguide nonreciprocal phase shifters are designed using the method of field expansion into eigenmodes, which includes higher order mode interaction between the step discontinuities. Computer-optimized Ku-band ferrite stepped design examples, of 45° and 90° nonreciprocal differential phase shifts, attain typically about 2° phase error and less than -25 dB input reflection within a bandwidth of about 5 percent. Compact designs are achieved by thicker uniform ferrite slabs with dielectric transformer sections at each end. The theory is verified by comparison with available results from measurements and other methods.

I. INTRODUCTION

TONRECIPROCAL PHASE SHIFT may be realized in rectangular waveguide by placing a ferrite slab [1]-[20] in a plane (Fig. 1) where the magnetic field is nearly circularly polarized [2]-[25]. The slab is biased transversely by a dc magnetic field sufficiently below that at which ferromagnetic resonance occurs. Whereas for a similar reciprocal structure—a dielectric-slab-loaded phase shifter-solutions for the impedance matching to the unloaded waveguide sections are well known [26], [27], [32], the three-dimensional field theory problem of related stepped anisotropic ferrite slab structures of finite length asymmetrically placed in the waveguide (Fig. 1) has not yet been attacked sufficiently. Suitably optimized structures, however, may be of considerable importance for many applications, e.g., for differential phase shift circulators [28], where good overall performance depends on the requirement that the individual components have appropriate electrical characteristics. Moreover, appropriate impedance transformer sections allow compact nonreciprocal phase shifter designs, since thick slab structures may then be utilized which otherwise would cause VSWR values which are unacceptably high.

Many investigations concerning ferrite-loaded waveguides have been reported [3], [4], [7], [9]–[16], [18]–[25], [29]–[31], [34], including analyses of discontinuity prob-

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Fig. 1. Ferrite-loaded waveguide nonreciprocal phase shifter with multisection ferrite or dielectric slab impedance transformers at both ends. (a) Waveguide with the slab insert. (b) Cross section of the slab structure. (c) Wave amplitude vectors of the structures of finite length.

lems by a coupled-line model [24] and by modal expansion methods [18]–[20], [23]. These analyses, however, are limited to uniform ferrite slab structures [18], [20], [23], [24] or a structure periodically loaded by an array of diaphragms [19]. Waveguide H-plane junctions with a ferrite post have been analyzed by an integral equation

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method [29], the modal expansion method [30], and the finite-element method [34]. However, these investigations are concerned with the performance of Y-junction circulators; consequently, ferrite posts with smooth boundaries such as a circular and a triangular post, with and without depressed sides, are studied [29], [30], [34].

This paper describes a modal-S-matrix method for designing ferrite-slab-loaded nonreciprocal waveguide phase shifters with multisection impedance transformers (Fig. 1) at both ports. The transformer sections may be formed of the same ferrite material as that used for the middle section of the phase shifter, or may advantageously consist of appropriate dielectric material which can often be handled better mechanically. Moreover, dielectric impedance transformer sections fastened to the uniform ferrite slab require no addition dc magnetic field. Since good VSWR characteristics can be realized, relatively thick ferrite-slab phase-shifting structures may be included in the optimization procedure, which, consequently, leads to compact designs. The method of field expansion into incident and scattered waves at all discontinuities includes the higher order mode coupling effects along the whole three-dimensional structure. Suitably optimized geometric parameters improve the nonreciprocal phase characteristic; dielectric losses are also considered in the calculations. The computer-aided design using this theory provides low-input VSWR behavior together with a prescribed differential nonreciprocal phase shift. The theory is verified through comparison with computed and measured results available from the literature as well as with our own measurements.

II. THEORY

For each homogeneous subregion, $\nu = I$ to IV (Fig. 1(b) and (c)), the fields [7] of the resulting TE_{n0} waves, if a TE_{m0} wave is incident,

$$\nabla \times \vec{H} = j\omega\epsilon\vec{E} \qquad \nabla \cdot \left(\langle \vec{\mu} \rangle \vec{H}\right) = 0$$
$$\nabla \times \vec{E} = -j\omega\langle \vec{\mu} \rangle \vec{H} \qquad \nabla \cdot \vec{E} = 0 \tag{1}$$

are derived from the electric field component $\vec{e_y} E_y^{(v)}$. This component may be expressed as a sum of N eigenmodes [3], [23] satisfying the vector Helmholtz equation and the boundary condition at x = -d - w/2, or x = a - d - w/2, respectively:

$$E_{y}^{(\nu)} = \sum_{n=1}^{N} \begin{cases} E_{n}^{(I)} \sin \frac{n\pi}{a} \left(x + d + \frac{w}{2} \right) \\ E_{n}^{(IV)} \sin k_{xn}^{(IV)} \left(x + d + \frac{w}{2} \right) \\ E_{n}^{(II)} \sin k_{xn}^{(II)} (x) + F_{n}^{(II)} \cos k_{xn}^{(II)} (x) \\ E_{n}^{(III)} \sin k_{xn}^{(III)} \left(a - d - \frac{w}{2} - x \right) \end{cases}$$
(2)

where a z dependence of $\exp(-\gamma_n z)$ is understood. For a dc magnetic field H_0 in the y direction, the permeability

tensor takes the form [1]-[6]

$$\langle \vec{\mu} \rangle = \mu_0 \begin{pmatrix} \mu_1 & 0 & -j\kappa \\ 0 & \mu_r & 0 \\ j\kappa & 0 & \mu_1 \end{pmatrix}$$
(3)

with elements μ_1 , μ_r , and κ given in [1]–[3]. The relations for the wavenumbers in (2) are

$$k_{0}^{2} = \omega^{2} \mu_{0} \epsilon_{0} \qquad k_{0}^{2} = \left(k_{xn}^{(\text{III}),(\text{IV})}\right)^{2} - \gamma_{n}^{2}$$
$$\mu_{2} = \frac{\mu_{1}^{2} - \kappa^{2}}{\mu_{1}} \qquad k_{0}^{2} \epsilon_{r} \mu_{2} = \left(k_{xn}^{(\text{II})}\right)^{2} - \gamma_{n}^{2} \qquad (4)$$

where γ_n is determined via field matching [7] of the transverse field components along the boundaries $x = \pm w/2$. The requirement that the system determinant be zero results in a transcendental equation for γ_n , which is solved numerically. The Newton method has turned out to yield numerically stable solutions for thick slabs provided that the starting values are taken from known thin-ferrite-slab expressions [31], [23] and that the step intervals for increasing thickness are chosen to be sufficiently small.

For calculation of the modal scattering matrix of the three-dimensional structure (Fig. 1(c)), the related biorthogonality relations [7], [9], [11], [23] for anisotropic structures have to be taken into account:

$$(\gamma_n + \gamma'_m) \int \int_F \left[\left(\vec{E_n} \times \vec{H'_m} - \vec{E'_m} \times \vec{H_n} \right) \cdot \vec{e_z} \right] dF = 0. \quad (5)$$

Here, the reciprocity principle involves the fields E'_m , H'_m , and γ'_m which are solutions to the related problem with media characterized by the transposed permeability tensor [7]. Matching of the transversal field components (1), (2) at the corresponding interfaces (Fig. 1(c)) at z = 0 yields

$$\sum_{m=1}^{M} \left(A_{m}^{+} + A_{m}^{-} \right) T_{m} u_{m} = \sum_{n=1}^{N} \left(B_{n}^{+} e_{n}^{\mathrm{F}} + B_{n}^{-} e_{n}^{\mathrm{R}} \right)$$
$$\sum_{m=1}^{M} \left(A_{m}^{+} - A_{m}^{-} \right) T_{m} u_{m} Y_{m} = \sum_{n=1}^{N} \left(B_{n}^{+} h_{n}^{\mathrm{F}} - B_{n}^{-} h_{n}^{\mathrm{R}} \right)$$
(6)

where

$$u_{m} = \sin(\frac{\pi m}{a}(x+d+\frac{w}{2})),$$

$$Y_{m} = \frac{k_{zm}}{\omega\mu_{0}},$$

$$k_{zm}^{2} = k_{0}^{2} - (\frac{m\pi}{a})^{2},$$

- T_m normalization factor so that the power carried by a given wave is 1 W for a wave amplitude of $1\sqrt{W}$ [7],
- $e_n^{F,R}$ normalized eigenfunction of the E_y component of the forward (F) or reverse (R) *n*th mode in region 0 < z < l, respectively,
- $h_n^{\text{F,R}}$ normalized eigenfunction of the H_x component of the forward (F) or reverse (R) *n*th mode in region 0 < z < l, respectively.

The still unknown amplitude coefficients A_m^+ , A_m^- , B_n^+ , and B_n^- in (6) can be related to each other through the



Fig. 2. Magnitude of the reflection coefficients S_{11} and S_{22} of a ferrite slab as a function of the number N of eigenmodes considered. Slab length l = 60 mm; f = 9.36 GHz; $\mu = 0.4 - j0.06$, $\kappa = -1. - j0.06$; $\epsilon_r = 12.5 - j0.005$.

modal scattering matrix at the step discontinuity at z = 0:

$$\binom{(A)^{-}}{(B)^{+}} = \binom{(S_{11})^{0} \quad (S_{12})^{0}}{(S_{21})^{0} \quad (S_{22})^{0}} \binom{(A)^{+}}{(B)^{-}}$$
(7)

where the coefficients are given in the Appendix.

The general modal scattering matrix of a ferrite-slabloaded waveguide structure of finite length l is given by

$$\begin{pmatrix} (A)^{-} \\ (D)^{+} \end{pmatrix} = \begin{pmatrix} (S_{11})^{g} & (S_{12})^{g} \\ (S_{21})^{g} & (S_{22})^{g} \end{pmatrix} \begin{pmatrix} (A)^{+} \\ (D)^{-} \end{pmatrix}$$
(8)

where these coefficients are also given in the Appendix. The overall scattering matrix of two and more sections (Fig. 1(c)) is calculated by directly combining the appropriate single scattering matrices as shown explicitly in [32]. For computer optimization [27] of the transformer section lengths, the expansion into ten eigenmodes at each discontinuity has turned out to be sufficient. The final design data are proven through an expansion of 30 eigenmodes.

The convergence behavior of the modal expansion method used is demonstrated in Fig. 2 by showing the magnitude of the reflection coefficients S_{11} and S_{22} for a single ferrite slab as a function of the number N of eigenmodes considered in (2). Sufficient coincidence between $|S_{11}|$ and $|S_{22}|$ (according to the reciprocity relationships for gyrotropic media) and good agreement with Hoffmann's results [23] are obtained already for N = 10.

III. RESULTS

In Fig. 3, the magnitude of the reflection coefficient for a lossy dielectric obstacle of finite length in a R100 waveguide (22.860 mm \times 10.160 mm) is shown as a function of frequency. The calculated results agree well with the theoretical and measured values of Chaloupka [24].

For a uniform ferrite slab of finite length, frequencydependent results were published by Gardiol *et al.* [14] and Hoffmann *et al.* [33]. For comparison, computations were carried out for these geometries and materials. The results are presented in Fig. 4, showing good agreement between our theory and the experimental and theoretical values of [14] and [33]. For a slab of polycrystalline YIG on a



Fig. 3. Lossy dielectric obstacle of finite length in a R100 waveguide $(22.860 \text{ mm} \times 10.160 \text{ mm})$. Magnitude of the input reflection coefficient as a function of frequency. Comparison with [24].

narrow wall, which can be used for tunable filters [14], the (higher) attenuation in the reverse direction of propagation is plotted versus frequency (Fig. 4(a)). The internal magnetic field was chosen as in [14]. For an R1 ferrite slab structure of length l = 74.9 mm within a R100 waveguide housing (22.860 mm × 10.160 mm), the propagation factors (Fig. 4(b)) calculated from the related eigenvalue problem are compared with the measured results of [33] as a function of frequency. The amplitudes and phases of the forward (S_{21}) and backward (S_{12}) transmission coefficients are presented in parts (c) and (d) of Fig. 4 and compared with measured results from [33].

Fig. 5 shows the comparison of the theory with our own measurements (Fig. 5(a) for a ferrite TTI-2800 slab and Fig. 5(b) for a ferrite TTVG-1200 slab) within an R140 waveguide housing (15.799 mm×7.899 mm). Because of the relatively small gap width of the biasing magnet available for the experiment, only relatively short slabs could be chosen; for small slab widths, this results in a relatively low forward-to-backward nonreciprocal differential phase shift ($\Delta \phi = \operatorname{arc}(S_{21})$ -arc(S_{12})). In Fig. 5(a), at f = 16.8 GHz, the higher order TE₂₀ mode cutoff frequency, there is a rapid phase change of 180°, and the return loss increases. For different separations d of the slab from the waveguide wall, increasing or decreasing values for $\Delta \phi$ as a function of frequency may be observed (Fig. 5(b)). A suitably chosen parameter d, therefore, may be utilized to improve the bandwidth of the phase characteristic (cf. also Fig. 6). As may be observed from Fig. 5, our theory is found to be in good agreement with the measured results.

For the measurements, an HP 8410 network analyzer was used. The ferrite slab probes have been fabricated by a grinding process with a deviation from the designed values



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Fig. 4. Uniform ferrite slab of finite length in waveguide. (a) Attenuation in the reverse direction of a slab of polycrystalline YIG as a function of frequency. Comparison with [14]. (b) Propagation factors in forward (f) and reverse (r) direction calculated for a ferrite R1 slab structure of finite length l = 74.9 mm within a R100 waveguide. Comparison with experimental results from [33]. (c) Amplitudes and (d) phases of the forward S_{21} and backward S_{12} transmission coefficients for a ferrite R1 slab structure of l = 74.9 mm within a R100 waveguide. Comparison with experimental results from [33].



Fig. 5. Uniform ferrite slab of finite length in waveguide. (a) Nonreciprocal differential phase shift $\Delta \varphi = \varphi_{21} - \varphi_{12}$ and input reflection coefficient in decibels as a function of frequency. Ferrite TTI-2800 slab within a R140 waveguide (15.799 mm×7.898 mm), l = 20 mm, d = 0.7 mm, w = 0.7 mm, $H_0 = 1.2 \cdot 10^5$ A/m. Comparison with measurements (x). (b) Nonreciprocal differential phase shift $\Delta \varphi$ as a function of frequency with displacement d as a parameter. Curve 1: d = 1 mm; curve 2: d = 2 mm. Ferrite TTVG-1200 slab within a R140 waveguide, l = 37.5 mm, w = 0.5 mm, $H_0 = 1.2 \cdot 10^5$ A/m. Comparison with measurements (x).



Fig. 6. Optimized nonreciprocal phase shifters with one-step ferrite impedance transformer sections. Nonreciprocal differential phase shift and input reflection coefficient in decibels as a function of frequency. Ferrite TTVG-1200 slab within R140 waveguide. Curve 1: with impedance transformers at both ends; curve 2: without impedance transformers. (a) Design for $\Delta \varphi = 45^{\circ} \pm 2^{\circ}$. Curve 1: $w_1 = 1.2$ mm, $w_2 = 0.6$ mm, $l_1 = 13.2$ mm, $l_2 = 7.3$ mm, d = 13.55 mm, $H_0 = 1.2 \cdot 10^5$ A/m. Curve 2: $w_1 = 1.2$ mm, $l_1 = 14$ mm, d = 13.55 mm, $H_0 = 1.2 \cdot 10^5$ A/m. (b) Design for $\Delta \varphi = 90^{\circ} \pm 2.5^{\circ}$. Curve 1: $w_1 = 1.2$ mm, $w_2 = 0.7$ mm, $l_1 = 21$ mm, $l_2 = 7.8$ mm, d = 13.55 mm, $H_0 = 1.2 \cdot 10^5$ A/m. Curve 2: $w_1 = 1.2$ mm, $l_1 = 28$ mm, d = 13.55 mm, $H_0 = 1.2 \cdot 10^5$ A/m.

of about 1-2 percent. The lateral displacement within the R140 waveguide housing was determined by appropriate measuring gauges. An electromagnet fixed at the waveguide housing yields the biasing dc magnetic field, which was measured by a gaussmeter. The internal magnetic field was calculated according to the procedure given in [35].



Fig. 7. Optimized nonreciprocal phase shifters with two-step ferrite impedance transformer sections. Nonreciprocal differential phase shift and input reflection coefficient in decibels as a function of frequency. Ferrite TTVG-1200 slab within R140 waveguide. (a) Design for $\Delta \varphi = 45^{\circ} \pm 1.7^{\circ}$: $w_1 = 0.7$ mm, $w_2 = 0.5$ mm, $w_3 = 0.3$ mm, $l_1 = 100$ mm, $l_2 = 9$ mm, $l_3 = 10$ mm, d = 14.4 mm, $H_0 = 1.2 \cdot 10^5$ A/m. (b) Design for $\Delta \varphi = 90^{\circ} \pm 2.5^{\circ}$: $w_1 = 0.8$ mm, $w_2 = 0.6$ mm, $w_3 = 0.4$ mm, $l_1 = 130$ mm, $l_2 = 9.5$ mm, $l_3 = 10.5$ mm, d = 14.25 mm, $H_0 = 1.2 \cdot 10^5$ A/m.

Design examples for optimized nonreciprocal phase shifters with one-step ferrite impedance transformer sections are presented in Fig. 6. To verify the improvement of the VSWR behavior by additional impedance transformer sections (curves 1), the corresponding uniform slab phase shifter behavior is included in the presentation (curves 2).



Fig. 8. Optimized compact nonreciprocal phase shifters with two-step dielectric impedance transformer sections. Nonreciprocal differential phase shift and input reflection coefficient in decibels as a function of frequency. Ferrite TTVG-1200 slab within R140 waveguide. Curve 1: with impedance transformers at both ends; curve 2: without impedance transformers. (a) Design for $\Delta \varphi = 45^{\circ} \pm 1^{\circ}$. Curve 1: $w_1 = 1.2 \text{ mm}$, $w_2 = 0.85 \text{ mm}$, $w_3 = 0.4 \text{ mm}$, $l_1 = 14 \text{ mm}$, $l_2 = 8.2 \text{ mm}$, $l_3 = 9 \text{ mm}$, d = 13.55 mm, $H_0 = 1.2 \cdot 10^5 \text{ A/m}$, $\epsilon_r = 14.5 - j0.002$. Curve 2: $w_1 = 1.2 \text{ mm}$, $u_1 = 14 \text{ mm}$, $u_2 = 0.85 \text{ mm}$, d = 13.55 mm, $H_0 = 1.2 \cdot 10^5 \text{ A/m}$, $\epsilon_r = 14.5 - j0.002$. Curve 2: $w_1 = 1.2 \text{ mm}$, $u_1 = 28 \text{ mm}$, $l_2 = 6.8 \text{ mm}$, $l_3 = 8.5 \text{ mm}$, d = 13.55 mm, $H_0 = 1.2 \cdot 10^5 \text{ A/m}$, $\epsilon_r = 14.5 - j0.002$. Curve 2: $w_1 = 1.2 \text{ mm}$, $w_2 = 0.85 \text{ mm}$, $u_3 = 0.45 \text{ mm}$, $u_1 = 28 \text{ mm}$, $l_2 = 6.8 \text{ mm}$, $l_3 = 8.5 \text{ mm}$, d = 13.55 mm, $H_0 = 1.2 \cdot 10^5 \text{ A/m}$, $\epsilon_r = 14.5 - j0.002$. Curve 2: $w_1 = 1.2 \text{ mm}$, $w_2 = 0.35 \text{ mm}$, $u_3 = 0.45 \text{ mm}$, $u_1 = 28 \text{ mm}$, $l_2 = 6.8 \text{ mm}$, $l_3 = 8.5 \text{ mm}$, d = 13.55 mm, $H_0 = 1.2 \cdot 10^5 \text{ A/m}$, $\epsilon_r = 14.5 - j0.002$. Curve 2: $w_1 = 1.2 \text{ mm}$, $u_1 = 28 \text{ mm}$, d = 13.55 mm, $H_0 = 1.2 \cdot 10^5 \text{ A/m}$.

Fig. 7 shows the results of optimized structures with a two-step ferrite impedance transformer section for small-slab-width design examples. This leads to relatively long structures.

A very compact design combined with good nonreciprocal differential phase shift and low VSWR character-



Fig. 9. Photograph of the realized prototypes: stepped ferrite structure (left) and compact ferrite nonreciprocal phase shifter with dielectric transformer sections at both ends (right), suitable for R140 waveguide housings (15.799 mm×7.899 mm). Ferrite material: TTVG-1200; dielectric material: D-15 (Trans. Tech Inc.).

istics is achieved by utilizing dielectric impedance transformer sections at both ports of a ferrite slab structure (Fig. 8). For comparison, the related curves 2 without transformer sections are included in the presentations.

In order to allow verification of the theory presented for stepped ferrite structures as well as for uniform ferrite phase shifters with dielectric transformer sections, two prototypes suitable for R140 waveguide housings and for the biasing magnet available have been fabricated (Fig. 9). The stepped-ferrite type was constructed using five commercially available TTVG-1200 ferrite slabs with standard widths (0.5 mm), but of different lengths, appropriately fastened together (Fig. 9, left picture). For the hybrid type, the dielectric impedance transformer sections fastened to the uniform ferrite slab of width 1.2 mm were fabricated using standard D-15 material from Trans-Tech Inc., with a permittivity of 15.

The differential phase shift and the magnitude of the input reflection coefficient of the fabricated stepped ferrite phase shifter type (Fig. 9, left) are presented in Fig. 10. Although the design is not optimum, the input reflection coefficient is better than -20 dB. The differential phase shift, however, is only about $10^{\circ}-15^{\circ}$. This is due to the fact that along the relatively thick middle section (2.5 mm), for the chosen frequency range of 16.2–16.8 GHz, three higher order modes propagate, which degrade the overall differential phase shift considerably, and to the fact that the length of the structure is limited by the biasing magnet gap. Fig. 10, therefore, may be regarded mainly from the viewpoint of verifying the theory for stepped ferrite slabs.

The compact nonreciprocal phase shifter design using a uniform ferrite slab (1.2 mm) together with a stepped dielectric transformer section at both ends (Fig. 9, right), however, achieves a differential phase shift of about 45° (cf. Fig. 11). Compared with the optimized design of Fig. 8(a), the data H_0 and d have been slightly modified in order to adapt the midband frequency range to the Ku-band measuring equipment available. The VSWR behavior, therefore, does not correspond to that which is possible



Fig. 10. Nonreciprocal differential phase shift and input reflection coefficient for the fundamental mode of the realized stepped ferrite structure (cf. Fig. 9, left). Dimensions: a = 15.799 mm, b = a/2, $w_1 = 2.5 \text{ mm}$, $w_2 = 1.5 \text{ mm}$, $w_3 = 0.5 \text{ mm}$, $l_1 = 25 \text{ mm}$, $l_2 = 3.5 \text{ mm}$, $l_3 = 3.5 \text{ mm}$, d = 12.8 mm, $H_0 = 1.2 \cdot 10^5 \text{ A/m}$.



Fig. 11. Nonreciprocal differential phase shift and input reflection coefficient of the realized compact hybrid phase shifter using a uniform ferrite slab together with stepped dielectric transformer sections (cf. Fig. 9, right). Dimensions same as Fig. 8(a); exceptions: d = 13.75 mm, $H_0 = 9 \cdot 10^4$ A/m.

with such structures (cf. Fig. 8(a)). As in Fig. 10, however, the measured results agree well with the theoretically predicted values.

IV. CONCLUSIONS

A rigorous field theory for the optimum design of ferrite-loaded waveguide nonreciprocal phase shifters is presented. Multisection ferrite or dielectric slab impedance transformers at both ends of the phase shifter achieve low VSWR values even for relatively thick ferrite middle sections. Therefore, compact phase shifter structures may be designed, as is demonstrated by numerically optimized examples for differential nonreciprocal phase shifts of 45° and 90°. Since higher order mode interaction effects are included in the design theory, the theoretically predicted values agree well with measured results.

Appendix

A. Scattering Coefficients in (7)

The coefficients are

$$(S_{11})^{0} = (D_{E})^{-1} (L_{E}^{(F)}) 2(M) - (U)$$

$$(S_{12})^{0} = (D_{E})^{-1} (L_{E}^{(F)}) [2(M)(D_{H})^{-1} (L_{H}^{(R)})$$

$$- (M) ((D_{E})^{-1} (L_{E}^{(R)}) + (D_{H})^{-1} (L_{H}^{(R)}))]$$

$$+ (D_{E})^{-1} (L_{E}^{(R)})$$

$$(S_{21})^{0} = 2(M)$$

$$(S_{22})^{0} = 2(M)(D_{H})^{-1}(L_{H}^{(\mathbb{R})}) - (M) \Big[(D_{E})^{-1} (L_{E}^{(\mathbb{R})}) \\ + (D_{H})^{-1} (L_{H}^{(\mathbb{R})}) \Big]$$

(M) = $\Big[(D_{E})^{-1} (L_{E}^{(\mathbb{F})}) + (D_{H})^{-1} (L_{H}^{(\mathbb{F})}) \Big]^{-1}$
(U) = unit matrix. (A1)

The diagonal matrix coefficients are

$$D_{Emm} = \frac{a}{2} T_m \quad D_{Hmm} = \frac{a}{2} T_m Y_m \tag{A2}$$

and the matrix coefficients are

$$L_{Emk}^{(F)} = \tilde{E}_{k}^{(IV)(F)} I_{mk}^{(I)(F)} + \tilde{E}_{k}^{(II)(F)} I_{mk}^{(II)(F)} + \tilde{F}_{k}^{(II)(F)} I_{mk}^{(III)(F)} + \tilde{E}_{k}^{(III)(F)} I_{mk}^{(IV)(F)} L_{Hmk}^{(F)} = \frac{j\gamma_{k}^{(F)}}{\omega\mu_{0}} \left(\tilde{E}_{k}^{(IV)(F)} I_{mk}^{(I)(F)} + \tilde{E}_{k}^{(III)(F)} I_{mk}^{(IV)(F)} \right) + H_{k}^{(II)(F)} I_{mk}^{(II)(F)} + G_{k}^{(II)(F)} I_{mk}^{(III)(F)}$$
(A3)

where

$$H_{k}^{(\mathrm{II})(\mathrm{F})} = \frac{j\gamma_{k}^{(\mathrm{F})}\tilde{E}_{k}^{(\mathrm{II})(\mathrm{F})}}{\omega\mu_{0}\mu_{2}} + \frac{\frac{\kappa}{\mu_{1}}k_{xk}^{(\mathrm{II})(\mathrm{F})}\tilde{F}_{k}^{(\mathrm{II})(\mathrm{F})}}{\omega\mu_{0}\mu_{2}}$$
$$G_{k}^{(\mathrm{II})(\mathrm{F})} = \frac{j\gamma_{k}^{(\mathrm{F})}\tilde{F}_{k}^{(\mathrm{II})(\mathrm{F})}}{\omega\mu_{0}\mu_{2}} - \frac{\frac{\kappa}{\mu_{1}}k_{xk}^{(\mathrm{II})(\mathrm{F})}\tilde{E}_{k}^{(\mathrm{II})(\mathrm{F})}}{\omega\mu_{0}\mu_{2}}$$
$$\left(k_{xk}^{(\mathrm{II})(\mathrm{F})}\right)^{2} = \left(\gamma_{k}^{(\mathrm{F})}\right)^{2} + k_{0}^{2} \cdot \epsilon_{r} \cdot \mu_{2}. \tag{A4}$$

...

The coupling integrals are given by

$$I_{mk}^{(\mathrm{ID}(\mathrm{F})} = \int_{x=-d-w/2}^{-w/2} \sin\left(k_{xk}^{(\mathrm{IV})(\mathrm{F})}(x+d+w/2)\right) u_m(x) \, dx$$

$$I_{mk}^{(\mathrm{II})(\mathrm{F})} = \int_{x=-w/2}^{w/2} \sin\left(k_{xk}^{(\mathrm{II})(\mathrm{F})}x\right) u_m(x) \, dx$$

$$I_{mk}^{(\mathrm{III})(\mathrm{F})} = \int_{x=-w/2}^{w/2} \cos\left(k_{xk}^{(\mathrm{II})(\mathrm{F})}x\right) u_m(x) \, dx$$

$$I_{mk}^{(\mathrm{IV})(\mathrm{F})} = \int_{x=w/2}^{a-d-w/2} \sin\left(k_{xk}^{(\mathrm{III})(\mathrm{F})}(a-d-w/2-x)\right) - u_m(x) \, dx$$
(A5)

with $u_m(x)$ given in (6), and the amplitude coefficients $E_k^{(\nu)}$ and $F_k^{(\nu)}$ of (2) in the normalized form $\tilde{E}_k^{(\nu)}, \tilde{F}_k^{(\nu)},$ thus the power carried by a given wave is proportional to the square of the absolute value of the amplitude coefficient [7]. The superior letter (F) denotes the relations of modes directed in the forward (+z) direction. Equations (A3)-(A5) hold also for the corresponding expressions denoted by (R) for modes in the reverse direction (-z) if $\gamma^{(F)}$ is replaced by $\gamma^{(R)}$; i.e., the medium is characterized by the transposed permeability tensor.

B. Scattering Coefficients in (8)

These coefficients are

$$(S_{11})^{g} = (S_{11})^{0} + (S_{12})^{0} (R)^{(R)}$$
$$\cdot [(U) - (S_{11})^{1} (R)^{(F)} (S_{22})^{0} (R)^{(R)}]^{-1}$$
$$\cdot (S_{11})^{1} (R)^{(F)} (S_{21})^{0}$$

$$(S_{12})^{g} = (S_{12})^{0} (R)^{(R)}$$

$$\cdot \left[(U) - (S_{11})^{1} (R)^{(F)} (S_{22})^{0} (R)^{(R)} \right]^{-1} (S_{12})^{1}$$

$$(S_{21})^{g} = (S_{21})^{1} (R)^{(F)}$$

 $\cdot [(U) - (S_{22})^{0} (R)^{(R)} (S_{11})^{1} (R)^{(F)}]^{-1} (S_{21})^{0}$

$$(S_{22})^{g} = (S_{22})^{1} + (S_{21})^{1} (R)^{(F)}$$

$$\cdot [(U) - (S_{22})^{0} (R)^{(R)} (S_{11})^{1} (R)^{(F)}]^{-1}$$

$$\cdot (S_{22})^{0} (R)^{(R)} (S_{12})^{1}.$$
(A6)

The diagonal matrix coefficients are

$$R_{nn}^{(\mathrm{F})} = \exp\left(-\gamma^{(\mathrm{F})}l\right) \quad R_{nn}^{(\mathrm{R})} = \exp\left(+\gamma^{(\mathrm{R})}l\right). \quad (\mathrm{A7})$$

The relation between the matrix elements, i.e.,

$$\begin{pmatrix} (S_{22})^1 & (S_{21})^1 \\ (S_{12})^1 & (S_{11})^1 \end{pmatrix} = \begin{pmatrix} (S_{11}')^0 & (S_{12}')^0 \\ (S_{21}')^0 & (S_{22}')^0 \end{pmatrix}$$
(A8)

may be utilized for calculating the elements of $(S)^1$ by the corresponding elements $(S')^0$, which are given by (A1) for the transposed permeability tensor.

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