# Design of Frequency-Response-Masking FIR Filters Using SOCP with Coefficient Sensitivity Constraint

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# **Outline**

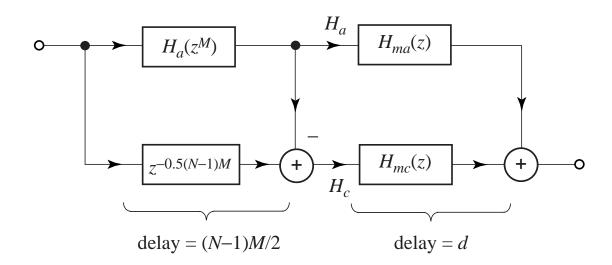
- Early and Recent Work on FRM Filters
- Coefficient Sensitivity (CS) Performance of an Second-Order Cone Programming (SOCP) Algorithm for FRM Filters
- An Enhanced SOCP Algorithm with a CS Constraint
- Experimental Results

## Early and Recent Work on FRM Filters

- Lim, 1986.
- Rajan, Neuvo and Mitra, 1988.
- Lim and Lian, 1993.
- Lee and Chen, 1993.
- Lim and Lian, 1994.
- Bellanger, 1996.
- Barcellos, Netto, and Diniz, 2003.
- Saramaki and Lim, 2003.
- Lu and Hinamoto, 2003. (SDP and SOCP techniques)
- Lian and Yang, 2003.
- Lian, 2003.
- Saramaki, Yli-Kaakinen, and Johansson, 2003.
- Lee, Rehbock, and Teo, 2003.
- Gustafsson, Johansson, and Wanhammar, 2003.
- Yu, Teo, Lim, and Zhao, 2005.
- Rodrigues and Pai, 2005.
- Cen and Lian, 2005.
- Lim, Yu, Teo, and Saramaki, 2007. (Coefficient Sensitivity)

#### CS Performance of an SOCP Algorithm for FRM Filters

• Reference: W.-S. Lu and T. Hinamoto, "Optimal design of frequency-response masking filters using second-order cone programming," *ISCAS*' 2003, vol. 3, pp. 878-881, May 2003.



$$H(\omega, x) = \left[a^{T} c(\omega)\right] \left[a_{a}^{T} c_{a}(\omega)\right] + \left[1 - a^{T} c(\omega)\right] \left[a_{c}^{T} c_{c}(\omega)\right], \qquad x = \begin{vmatrix} a \\ a_{a} \\ a_{c} \end{vmatrix}$$

$$x_{k+1} = x_k + \delta_k \quad \text{with } \delta_k \quad \text{"small"}$$

$$H(\omega, x_{k+1}) \approx H(\omega, x_k) + g_k^T(\omega) \delta_k \quad \text{with } g_k(\omega) = \nabla H(\omega, x_k)$$

• SOCP Formulation for an optimal  $\delta_k$ :

minimize 
$$\eta$$
 subject to:  $W(\omega) \Big| H(\omega, x_k) + g_k^T(\omega) \delta - H_d(\omega) \Big| \le \eta$  
$$\|\delta\| \le \beta$$

• The coefficient vector of the optimal FRM filter is given

by 
$$x^* = x_0 + \sum_{k=0}^{K-1} \delta_k$$

Hence 
$$||x^*|| \le ||x_0|| + \sum_{k=0}^{K-1} ||\delta_k|| \le ||x_0|| + K\beta$$

and

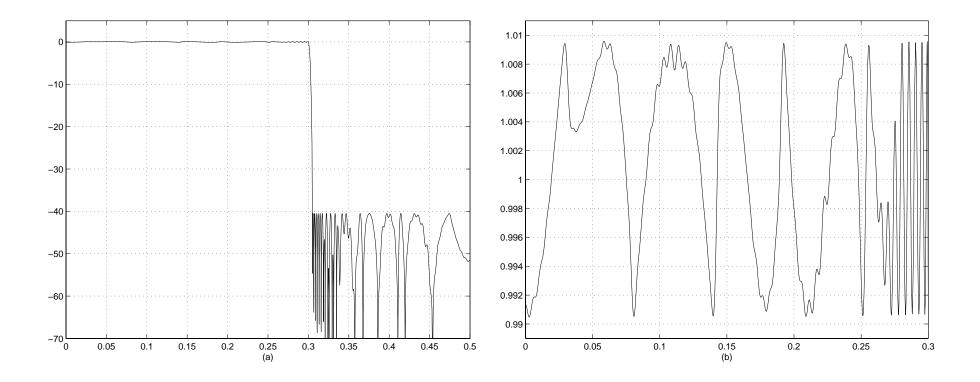
$$\|x^* - x_0\| \le \sum_{k=0}^{K-1} \|\delta_k\| \le K\beta$$

Typically K is in the range of 8 to 15 (regardless of filter length).

- $\Rightarrow \blacklozenge \|x^*\|$  remains small as long as  $\|x_0\|$  is small.
  - ♦ Because a small  $||x^*||$  implies a low CS, the CS of an SOCP-based solution is low as long as the CS of the initial FRM filter is low.
  - ♦ Using SOCP, one can always find an optimal FRM filter *in a small vicinity* of a reasonable initial design (obtained e.g. using the method of Lim 1986).

- Example N = 45,  $N_a = 27$ ,  $N_c = 19$ , M = 9,  $\omega_p = 0.3$ , and  $\omega_a = 0.305$ 
  - CS of the initial FRM filter (Lim 1986):  $S_1^2 = 24.4532$
  - $\beta$  was set to 0.1533 (problem size: 44)
  - ♦ the SOCP algorithm converges in 8 iterations
  - step size for coefficient quantization was set to  $2^{-14}$
  - CS of the optimal FRM filter:  $S_1^2 = 38.9035$
  - ♦ peak ripple magnitude in passband: 0.009586
  - ♦ minimum stopband attenuation: 40.4179 dB
  - coefficient differences in 2-norm:

$$||h^* - h^{(0)}|| = 0.5394, \quad ||h_a^* - h_a^{(0)}|| = 0.0816, \quad ||h_c^* - h_c^{(0)}|| = 0.1052$$



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## An Enhanced SOCP Algorithm with a CS Constraint

The CS measure defined in Lim et al 2007 is given by

$$S_1^2 = \begin{bmatrix} \sqrt{N_c}h \\ \sqrt{N_a}h \\ \sqrt{N}(h_a - \hat{h}_c) \end{bmatrix} - \hat{e}$$

with

$$h = \begin{bmatrix} J & 0 & 0 \end{bmatrix} x$$
,  $h_a = \begin{bmatrix} 0 & J_a & 0 \end{bmatrix} x$ ,  $h_c = \begin{bmatrix} 0 & 0 & \hat{J}_c \end{bmatrix} x$ 

Hence we can write

$$\begin{bmatrix} \sqrt{N_c} h \\ \sqrt{N_a} h \\ \sqrt{N} (h_a - \hat{h}_c) \end{bmatrix} = A^T x \quad \text{with} \quad A^T = \begin{bmatrix} \sqrt{N_c} J & 0 & 0 \\ \sqrt{N_a} J & 0 & 0 \\ 0 & \sqrt{N} J_a & -\sqrt{N} \hat{J}_c \end{bmatrix}$$

If  $d_{FWL}$  is the desired upper bound for  $S_1$ , then the constraint that  $S_1$  be bound above by  $d_{FWL}$  can be cast as

$$\left\| A^T x - \hat{e} \right\| \le d_{FWL}$$

In the *k*th iteration,  $x = x_k + \delta$ , the CS constraint becomes

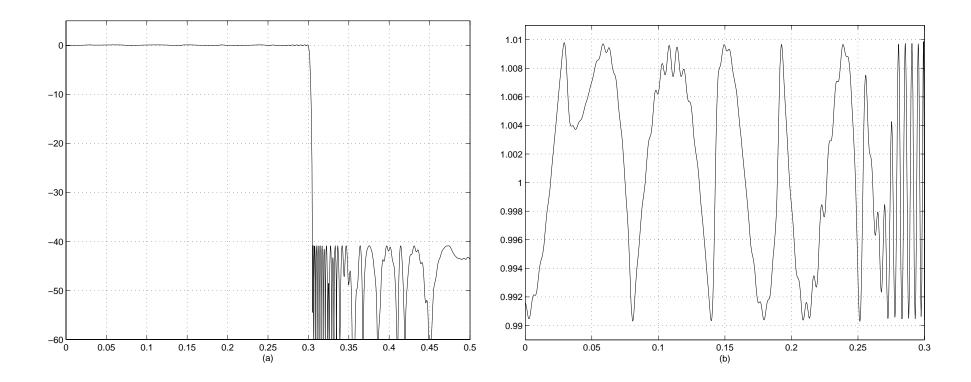
$$||A^T \delta + b_k|| \le d_{FWL}$$
 with  $b_k = Ax_k - \hat{e}$ 

• Incorporating above constraint on CS into our early SOCP formulation leads an enhanced SOCP problem:

minimize 
$$\eta$$
  
subject to:  $W(\omega) | H(\omega, x_k) + g_k^T(\omega) \delta - H_d(\omega) | \le \eta$   
 $\| \delta \| \le \beta$   
 $\| A^T \delta + b_k \| \le d_{FWL}$ 

## **Experimental Results**

- Design of an FRM filter with N = 45,  $N_a = 27$ ,  $N_c = 19$ , M = 9,  $\omega_p = 0.3$ , and  $\omega_a = 0.305$  (same as that in Lim et al, 2007).
- Other design parameters:  $\beta = 0.2168$ ,  $d_{FWL} = 5.4 \Leftrightarrow S_1^2 \le 29.16$
- quantization step-size: 2<sup>-14</sup>
- number of freq. grids in passband and stopband: 2000
- Results: ♦ 8 iterations to converge
  - ♦ peak ripple magnitude in passband: 0.009874
  - ♦ minimum stopband attenuation: 40.6479 dB
  - CS of the FRM filter:  $S_1^2 = 28.2468$
  - ♦ CPU time (3.4 GHz, Pentium 4): 26.91 seconds



FRM Filter	Peak passband	Minimum stopband	$S_1^2$
	ripple	attenuation (dB)	
Filter in Table I of	0.009949	40.0674	6.7797
Lim et al, 2007			$\times 10^9$
Filter in Table II of	0.010041	39.9628	26.4288
Lim et al, 2007			
SOCP-based design	0.009586	40.4187	38.9035
without CS constraint			
SOCP-based design	0.009874	40.6479	28.2468
with CS constraint			