

Reconstruction of Sparse Signals by Minimizing a Re-Weighted Approximate ℓ_0 -Norm in the Null Space of the Measurement Matrix

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- Comperssive Sensing

- Compressive Sensing
- Signal Recovery by ℓ_1 Minimization

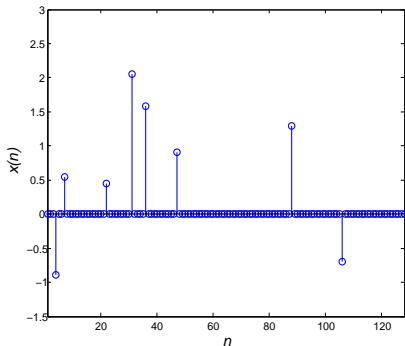
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- Performance Evaluation

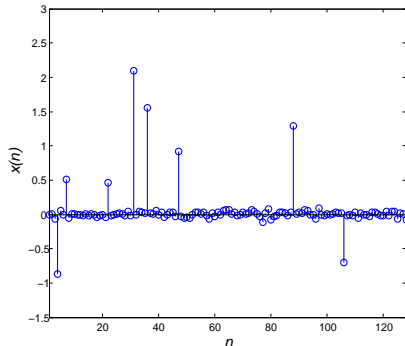
- A signal $\mathbf{x}(n)$ of length N is K -sparse if it contains K nonzero components with $K \ll N$.

Compressive Sensing

- A signal $\mathbf{x}(n)$ of length N is K -sparse if it contains K nonzero components with $K \ll N$.
- A signal is near K -sparse if it contains K significant components.



A sparse signal



A near sparse signal

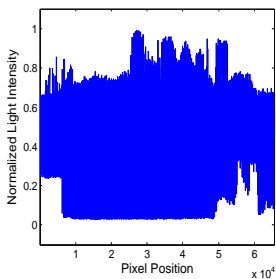
- Sparsity is a generic property of signals: A real-world signal always has a sparse or near-sparse representation with respect to an appropriate basis.

Compressive Sensing, cont'd

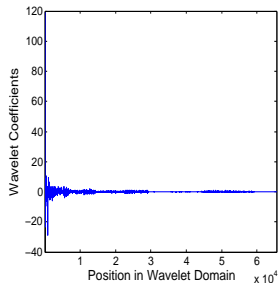
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An Image



An equivalent
1-D signal



A wavelet
representation of
the image

- Compressive sensing (CS) is a data acquisition process whereby a sparse signal $\mathbf{x}(n)$ represented by a vector \mathbf{x} of length N is determined using a small number of projections represented by a matrix Φ of dimension $M \times N$.

Compressive Sensing, cont'd

- Compressive sensing (CS) is a data acquisition process whereby a sparse signal $\mathbf{x}(n)$ represented by a vector \mathbf{x} of length N is determined using a small number of projections represented by a matrix Φ of dimension $M \times N$.
- In such a process, measurement vector \mathbf{y} and signal vector \mathbf{x} are interrelated by the equation

$$\begin{array}{ccc} \left[\begin{array}{c} \mathbf{y} \end{array} \right]_{M \times 1} & = & \left[\begin{array}{c} \Phi \end{array} \right]_{M \times N} \left[\begin{array}{c} \mathbf{x} \end{array} \right]_{N \times 1} \\ \text{measurements} & & \text{projection matrix} \quad \text{sparse signal of interest} \end{array}$$

The diagram illustrates the equation $\mathbf{y} = \Phi \cdot \mathbf{x}$. On the left, a yellow vertical bar represents the measurement vector \mathbf{y} with dimensions $M \times 1$, labeled "measurements". In the center, a green rectangle represents the projection matrix Φ with dimensions $M \times N$, labeled "projection matrix". On the right, a blue vertical bar represents the sparse signal vector \mathbf{x} with dimensions $N \times 1$, labeled "sparse signal of interest". The equation is shown as $\mathbf{y} = \Phi \cdot \mathbf{x}$ above the matrices.

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$$M \geq c \cdot K \cdot \log(N/K)$$

where c is a small constant.

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- Typically,

$$K < M < N$$

Signal Recovery by ℓ_1 Minimization

- Recovering signal vector \mathbf{x} from measurement vector \mathbf{y} such that

$$\underset{M \times N}{\Phi} \cdot \underset{N \times 1}{\mathbf{x}} = \underset{M \times 1}{\mathbf{y}}$$

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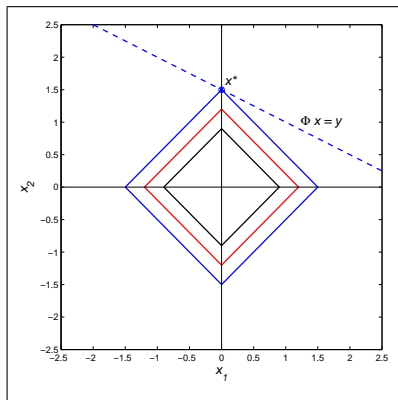
- Given that \mathbf{x} is sparse, \mathbf{x} can be reconstructed by solving the ℓ_1 -minimization problem

$$\begin{array}{ll} \underset{\mathbf{x}}{\text{minimize}} & ||\mathbf{x}||_1 \\ \text{subject to} & \Phi \mathbf{x} = \mathbf{y} \end{array}$$

$$\text{where } ||\mathbf{x}||_1 = \sum_{i=1}^N |x_i|.$$

- Why ℓ_1 -norm minimization?

■ Why ℓ_1 -norm minimization?



Contours for $\|\mathbf{x}\|_1 = c$

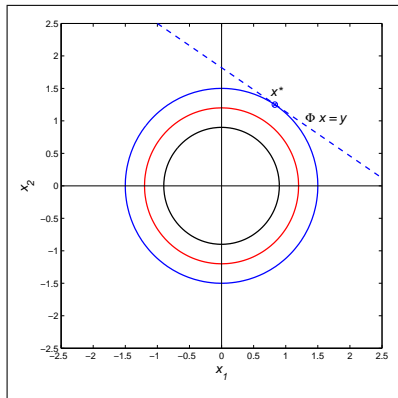
As c increases, the contour of $\|\mathbf{x}\|_1 = c$ grows and touches the hyperplane $\Phi \mathbf{x} = \mathbf{y}$, yielding a sparse solution

$$\mathbf{x}^* = \begin{bmatrix} 0 \\ c \end{bmatrix}$$

- Why ℓ_2 -norm minimization fails to work?

Signal Recovery by ℓ_1 Minimization, cont'd

- Why ℓ_2 -norm minimization fails to work?



As r increases, the contour of $\|\mathbf{x}\|_2 = r$ grows and touches the hyperplane $\Phi \mathbf{x} = \mathbf{y}$.

The solution \mathbf{x}^* obtained is not sparse.

Contours of $\|\mathbf{x}\|_2 = r$

Theorem

If $\Phi = \{\phi_{ij}\}$ where ϕ_{ij} are independent and identically distributed random variables with zero-mean and variance $1/N$ and $M \geq cK \log(N/K)$, the solution of the ℓ_1 -minimization problem would recover exactly a K -sparse signal with high probability.

Theorem

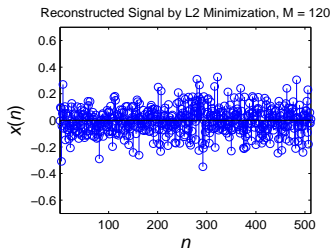
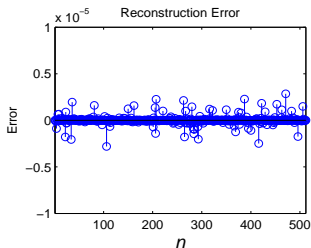
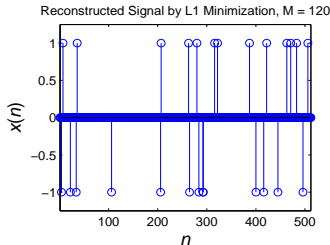
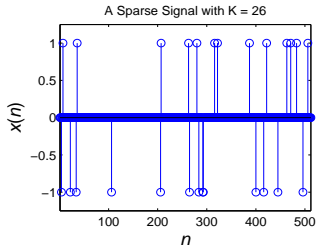
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- For real-valued data $\{\Phi, \mathbf{y}\}$, the ℓ_1 -minimization problem is a linear programming problem.

- Example: $N = 512$, $M = 120$, $K = 26$

Signal Recovery by ℓ_1 Minimization, cont'd

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- The sparsity of a signal can be measured by using its ℓ_0 pseudonorm

$$||\mathbf{x}||_0 = \sum_{i=1}^N |x_i|^0$$

Signal Recovery by ℓ_p Minimization

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- Hence the sparsest solution of $\Phi\mathbf{x} = \mathbf{y}$ can be obtained by solving the ℓ_0 -norm minimization problem

$$\begin{array}{ll} \underset{\mathbf{x}}{\text{minimize}} & ||\mathbf{x}||_0 \\ \text{subject to} & \Phi\mathbf{x} = \mathbf{y} \end{array}$$

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- Unfortunately, the ℓ_0 -norm minimization problem is nonconvex with combinatorial complexity.

- An effective signal recovery strategy is to solve the ℓ_p -minimization problem

$$\begin{array}{ll} \underset{\mathbf{x}}{\text{minimize}} & \|\mathbf{x}\|_p^p \quad \text{with} \quad 0 < p < 1 \\ \text{subject to} & \Phi \mathbf{x} = \mathbf{y} \end{array}$$

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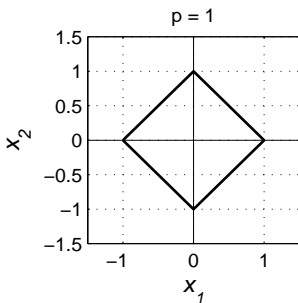
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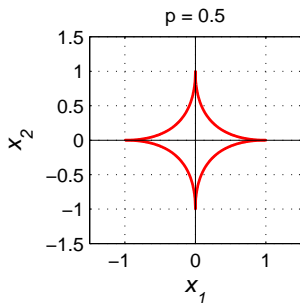
- The ℓ_p -norm minimization problem is nonconvex.

Signal Recovery by ℓ_p Minimization, cont'd

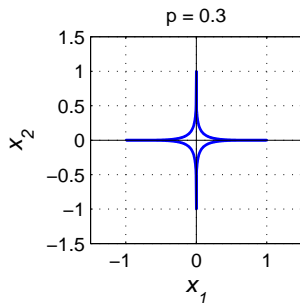
- Contours of $\|\mathbf{x}\|_p = 1$ with $p < 1$



$$\|\mathbf{x}\|_1 = 1$$



$$\|\mathbf{x}\|_{0.5} = 1$$

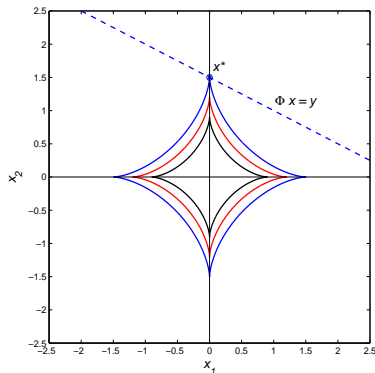


$$\|\mathbf{x}\|_{0.3} = 1$$

- Why ℓ_p minimization with $p < 1$?

Signal Recovery by ℓ_p Minimization, cont'd

- Why ℓ_p minimization with $p < 1$?



Contours of $\|\mathbf{x}\|_p^p = c$ with $p < 1$

As c increases, the contour $\|\mathbf{x}\|_p^p = c$ grows and touches the hyperplane $\Phi\mathbf{x} = \mathbf{y}$, yielding a sparse solution

$$\mathbf{x}^* = \begin{bmatrix} 0 \\ c \end{bmatrix}.$$

The possibility that the contour will touch the hyperplane at another point is eliminated.

- We propose to minimize an approximate ℓ_0 -norm

$$||\mathbf{x}||_{0,\sigma} = \sum_{i=1}^N \left(1 - e^{-x_i^2/2\sigma^2}\right)$$

where \mathbf{x} lies in the solution space of $\Phi\mathbf{x} = \mathbf{y}$, namely,

$$\mathbf{x} = \mathbf{x}_s + \mathbf{V}_r \boldsymbol{\xi}$$

where \mathbf{x}_s is a solution of $\Phi\mathbf{x} = \mathbf{y}$ and \mathbf{V}_r is an orthonormal basis of the null space of Φ .

Signal Recovery by ℓ_p Minimization, cont'd

- Why norm $\|\mathbf{x}\|_{0,\sigma}$ works?

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With σ small,

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Therefore, for a K -sparse signal,

$$\|\mathbf{x}\|_{0,\sigma} = \sum_{i=1}^N \left(1 - e^{-x_i^2/2\sigma^2}\right) \approx K = \|\mathbf{x}\|_0$$

- Improved recovery rate can be achieved by using a re-weighting technique.

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- This involves solving the optimization problem

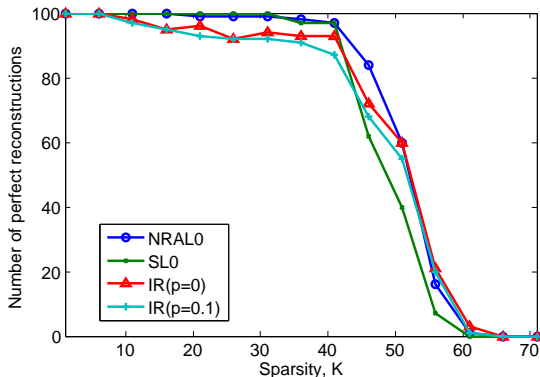
$$\underset{\xi}{\text{minimize}} \sum_{i=1}^n w_i \left\{ 1 - e^{-[x_s(i) + \mathbf{v}_i^T \xi]^2 / 2\sigma^2} \right\}$$

where

$$w_i^{(k+1)} = \frac{1}{|x_i^{(k)}| + \epsilon}$$

Performance Evaluation

Number of perfectly recovered instances versus sparsity K by various algorithms with $N = 256$ and $M = 100$ over 100 runs.



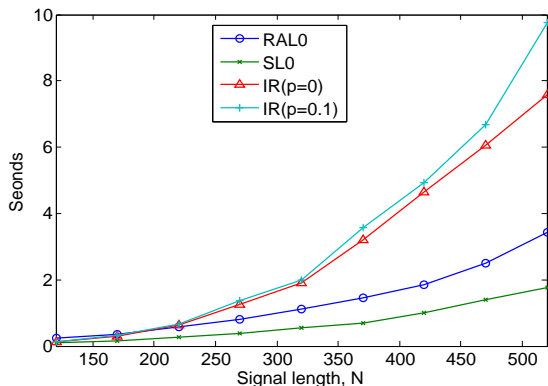
IR: Iterative re-weighting (Chartrand and Yin, 2008)

SL0: Smoothed ℓ_0 -norm minimization (Mohimani et. al., 2009)

NRAL0: Proposed

Performance Evaluation, cont'd

Average CPU time versus signal length for various algorithms with $M = N/2$ and $K = M/2.5$.



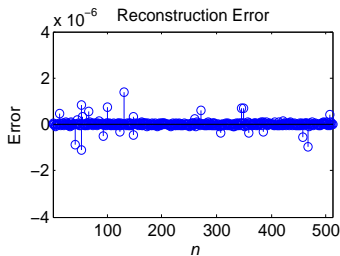
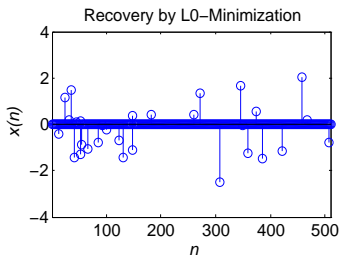
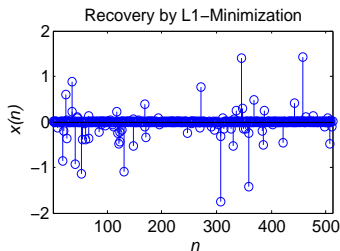
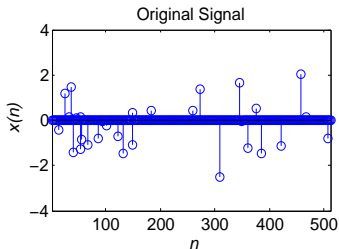
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NRAL0: Proposed

Performance Evaluation, cont'd

Performance comparison of ℓ_1 minimization with approximate ℓ_0 minimization for $N = 512$, $M = 80$, $K = 30$.



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- ℓ_1 minimization works in general for the reconstruction of sparse signals.
- ℓ_p minimization with $p < 1$ can improve the recovery performance for signals that are less sparse.
- Approximate ℓ_0 -norm minimization offers good performance with improved complexity.

Thank you for your attention.

This presentation can be downloaded from:

<http://www.ece.uvic.ca/~andreas/RLectures/MWSCAS2010-Jeevan-Web.pdf>