
References

- AM78. Abraham, R., Marsden, J.: Foundations of Mechanics. Benjamin, Reading, (1978)
- AMR88. Abraham, R., Marsden, J., Ratiu, T.: Manifolds, Tensor Analysis and Applications. Springer, New York, (1988)
- AS92. Abraham, R., Shaw, C.: Dynamics: the Geometry of Behavior. Addison-Wesley, Reading, (1992)
- AGM97. Alekseevsky, D., Grabowski, J., Marmo, G., Michor, P.W.: Completely integrable systems: a generalization. *Mod. Phys. Let. A*, **12**(22), 1637–1648, (1997)
- AGM94. Alekseevsky, D.V., Grabowski, J., Marmo, G., Michor, P.W.: Poisson structures on the cotangent bundle of a Lie group or a principle bundle and their reductions. *J. Math. Phys.*, **35**, 4909–4928, (1994)
- AAM76. Anderson, B.D., Arbib, M.A., Manes, E.G.: Foundations of System Theory: Finitary and Infinitary Conditions. Lecture Notes in Economics and Mathematical Systems Theory, Springer, New York, (1976)
- Arb98. Arbib, M. (ed.): Handbook of Brain Theory and Neural Networks (2nd ed.). MIT Press, Cambridge, (1998)
- Arn89. Arnold, V.I.: Mathematical Methods of Classical Mechanics (2nd ed). Springer, New York, (1989)
- Bae97. Baez, J.: An introduction to n -categories. *7th Conference on Category Theory and Computer Science*, E. Moggi and G. Rosolini (eds), Lecture Notes in Computer Science, Springer, Berlin, (1997)
- BD98. Baez, J., Dolan, J.: Higher-Dimensional Algebra III: n -categories and the Algebra of Opetopes. *Adv. Math.* **135**(2), 145–206, (1998)
- BD95. Baez, J., Dolan, J.: Higher dimensional algebra and topological quantum field theory. *J. Math. Phys.* **36**, 6073–6105, (1995)
- Bah88. Bahri, A.: Pseudo-orbits of contact forms. Pitman Research Notes in Mathematics Series, **173**, Longman Scientific and Technical, (1988)

- BH96. Banaszuk, A., Hauser, J.: Approximate feedback linearization: a homotopy operator approach. *SIAM J. Cont. & Optim.*, **34**(5), 1533–1554, (1996)
- Bar93. Barry Jay, C. : Matrices, Monads and the Fast Fourier Transform. *Univ. Tech.*, Sidney, (1993)
- BO95. Basar, T., Olsder, G.J.: *Dynamic Noncooperative Game Theory* (2nd ed.), Academic Press, (1995)
- BGG89. Batlle, C., Gomis, J., Gràcia, X., Pons, J.M.: Noether's theorem and gauge transformations: application to the bosonic string and CP_2^{n-1} model. *J. Math. Phys.* **30**, 1345, (1989)
- Bau00. Baum, H.: Twistor and Killing spinors on Lorentzian manifolds and their relations to CR and Kaehler geometry. *International Congress on Differential Geometry in memory of Alfred Gray*, Bilbao, Spain, (2000)
- BK92. Berleant, D., Kuipers, B.: Qualitative–Numeric Simulation with Q3, in *Recent Advances in Qualitative Physics*. eds. Boi Faltings and Peter Struss, MIT Press, Cambridge, (1992)
- Ben67. Bénabou, J. : Introduction to bicategories. In: *Lecture Notes in Mathematics*. Springer, New York, (1967)
- BR78. Birkhoff, G., Rota, G.C.: *Ordinary Differential Equations* (3rd ed.) Wiley, New York, (1978)
- BL81. Bishop, R.L., Goldberg, S.I.: *Tensor Analysis on Manifolds*. Dover, (1981)
- BL92. Blackmore, D., Leu, M.C.: Analysis of swept volumes via Lie group and differential equations. *Int. J. Rob. Res.*, **11**(6), 516–537, (1992)
- BPS98. Blackmore, D.L., Prykarpatsky, Y.A., Samulyak, R.V.: The Integrability of Lie-invariant Geometric Objects Generated by Ideals in the Grassmann Algebra. *J. Nonlin. Math. Phys.*, **5**(1), 54–67, (1998)
- Bon95. Bontempi, G.: Modelling with uncertainty in continuous dynamical systems: the probability and possibility approach. IRIDIA - ULB Technical Report, 95–16, (1995)
- Boo86. Boothby, W.M.: *An Introduction to Differentiable Manifolds and Riemannian Geometry*, Academic Press, New York, (1986)
- Bro01. Brockett, R.: New Issues in the Mathematics of Control. In *Mathematics Unlimited – 2001 and Beyond*, Springer, New York, (2001)
- BGG03. Bryant, R., Griffiths, P., Grossman, D.: *Exterior Differential Systems and Euler–Lagrange Partial differential Equations*. Univ. Chicago Press, Chicago, (2003)
- CCC97. Caiani, L., Casetti, L., Clementi, C., Pettini,M.: Geometry of dynamics, Lyapunov exponents and phase transitions. *Phys. Rev. Lett.* **79**, 4361 (1997)
- CC99. Cao, H.D., Chow, B.: Recent Developments on the Ricci Flow. *Bull. Amer. Math. Soc.* **36**, 59–74, (1999)
- CHP96. Channon, P., Hopkins, S. and Pham, D.: A variational approach to the optimization of gait for a bipedal robot. *J. Mech. Eng. Sci.*, **210**, 177–186, (1996)

- CD98. Chen, G., Dong, X.: From Chaos to Order: Methodologies, Perspectives and Application. World Scientific, Singapore, (1998)
- CL84. Cheng, T.-P., Li, L.-F.: Gauge Theory of Elementary Particle Physics. Clarendon Press, Oxford, (1984)
- Che55. Chevalley, C.: Theorie differential equations groupes de Lie. vol. 1–3. Hermann D.C., Paris, (1955)
- BM82. Choquet-Bruhat, Y., DeWitt-Morette, C.: Analysis, Manifolds and Physics (2nd ed). North-Holland, Amsterdam, (1982)
- BM00. Choquet-Bruhat, Y., DeWitt-Morette, C.: Analysis, Manifolds and Physics, Part II: 92 Applications (rev. ed). North-Holland, Amsterdam, (2000)
- CP02. Clementi, C. Pettini, M.: A geometric interpretation of integrable motions. *Celest. Mech. & Dyn. Astr.*, **84**, 263–281, (2002)
- CH64. Conway, E.D., Hopf, E.: Hamilton’s Theory and Generalized Solutions of the Hamilton–Jacobi Equation. *J. Math. Mech.* **13**, 939–986, (1964)
- Cox92. Cox, E.: Fuzzy Fundamentals, IEEE Spectrum, 58–61, (1992)
- Cox94. Cox, E.: The Fuzzy Systems Handbook. AP Professional, (1994)
- CF94. Crane, L., Frenkel, I.: Four dimensional topological quantum field theory, Hopf categories, and the canonical bases. *Jour. Math. Phys.* **35**, 5136–5154, (1994)
- Dar. Darioush, B.: Forward dynamics solutions to multi-modal inverse dynamics problems. In Proc. ISB’03, Univ. Otago, Dunedin, NZ, (2003)
- Dav89. Davies, E.B.: Heat Kernels and Spectral Theory. Cambridge Univ. Press, Cambridge, (1989)
- Dav81. Davydov, A.S.: Biology and Quantum Mechanics, Pergamon Press, New York, (1981)
- Dav91. Davydov, A.S.: Solitons in Molecular Systems. (2nd ed), Kluwer, Dordrecht, (1991)
- DEF99. Deligne, P., Etingof, P., Freed, D.S., Jeffrey, L.C., Kazhdan, D., Morgan, J.W., Morrison, D.R., Witten, E.: Quantum Fields and Strings: A Course for Mathematicians, Am. Math. Soc., (1999)
- DRh84. De Rham, G.: Differentiable Manifolds. Springer, Berlin, (1984)
- Die69. Dieudonne, J.A.: Foundations of Modern Analysis (in four volumes). Academic Press, New York, (1969)
- Die88. Dieudonne, J.A.: A History of Algebraic and Differential Topology 1900-1960. Birkhäuser, Basel, (1988)
- Dir30. Dirac, P.A.M.: The Principles of Quantum Mechanics, Oxford Univ. Press, Oxford, (1930)
- Dir50. Dirac, P.A.M.: Generalized Hamiltonian dynamics. *Can. J. Math.*, **2**, 129–148, (1950)
- Dir58. Dirac, P.A.M.: Generalized Hamiltonian dynamics. *Proc. Roy. Soc. A* **246**, 326–332, (1958)

- DP97. Dodson, C.T.J., Parker, P.E.: A User's Guide to Algebraic Topology. Kluwer, Dordrecht, (1997)
- DG03. Dragovic, V., Gajic, B.: The Wagner Curvature Tensor in Nonholonomic Mechanics. *Reg. Chaot. Dyn.*, **8**(1), 105–124, (2003)
- DP80. Dubois, D., Prade, H.: Fuzzy Sets and Systems. Academic Press, New York, (1980)
- EG91. Eastwood, M.G., Graham, C.R.: Invariants of conformal densities. *Duke Math. Jour.* **63**, 633–671, (1991)
- Eas02. Eastwood, M.: Higher symmetries of the Laplacian. arXiv hep-th/0206233, (2002)
- Ecc64. Eccles, J.C.: The Physiology of Synapses. Springer, Berlin, (1964)
- EIS67. Eccles, J.C., Ito M., Szentagothai J.: The Cerebellum as a Neuronal Machine. Springer, Berlin, (1967)
- Elk99. Elkin, V.I.: Reduction of Nonlinear Control Systems. A Differential Geometric Approach, Kluwer, Dordrecht, (1999)
- Elw82. Elworthy, K.D. Stochastic Differential Equations on Manifolds. Cambridge Univ. Press, Cambridge, (1982)
- Fey48. Feynman, R.P.: Space-time Approach to Nonrelativistic Quantum Mechanics. *Rev. Mod. Phys.* **20**, 367–387, (1948)
- Fey51. Feynman, R.P.: An Operator Calculus having Applications in Quantum Electrodynamics. *Phys. Rev.* **84**, 108–128, (1951)
- FH65. Feynman, R.P., Hibbs, A.R.: Quantum Mechanics and Path Integrals. McGraw-Hill, New York, (1965)
- Fey72. Feynman, R.P.: Statistical Mechanics, A Set of Lectures. W.A. Benjamin, Inc., Reading, Massachusetts, (1972)
- Fey98. Feynman, R.P.: Quantum Electrodynamics. Advanced Book Classics, Perseus Publishing, (1998)
- Fla63. Flanders, H.: Differential Forms: with Applications to the Physical Sciences. Acad. Press, (1963)
- Flo88. Floer, A.: Morse theory for Lagrangian intersections. *J. Diff. Geom.*, **28**(9), 513–517, (1988)
- For60. Forsyth, A.R.: Calculus of Variations. Dover, New York, (1960)
- Gar85. Gardiner, C.W.: Handbook of Stochastic Methods for Physics, Chemistry and Natural Sciences (2nd ed). Springer, Berlin, (1985)
- Ghe90. Ghez, C.: Introduction to motor system. In: Kandel, E.K. and Schwarz, J.H. (eds.) Principles of neural science. 2nd ed. Elsevier, Amsterdam, 429–442, (1990)
- GM97. Giachetta, G., Mangiarotti, L., Sardanashvily, G.: New Lagrangian and Hamiltonian Methods in Field theory. World Scientific, Singapore, (1997)
- Gol80. Goldstein, H.: Classical mechanics. Addison-Wesley, Reading, (1980)
- Gom94. Gómez, J.C.: Using symbolic computation for the computer aided design of nonlinear (adaptive) control systems. Tech. Rep. EE9454, Dept. Electr. and Comput. Eng., Univ. Newcastle, Callaghan, NSW, AUS, (1994)

- Goo98. Goodwine, J.W.: Control of Stratified Systems with Robotic Applications. PhD thesis, California Institute of Technology, Pasadena, California, (1998)
- Gre96. Greene, B.R. : String Theory on Calabi-Yau Manifolds. Lectures given at the TASI-96 summer school on Strings, Fields and Duality, (1996)
- Gri83a. Griffiths, P.A.: Exterior Differential Systems and the Calculus of Variations, Birkhauser, Boston, (1983)
- Gri83b. Griffiths, P.A.: Infinitesimal variations of Hodge structure. III. Determinantal varieties and the infinitesimal invariant of normal functions. *Compositio Math.*, **50**(2-3), 267–324, (1983)
- GJ94. van Groesen, E., De Jager E.M.: (Editors) Mathematical Structures in Continuous Dynamical Systems. Studies in Mathematical Physics, vol. 6 North-Holland, Amsterdam, (1994)
- Gro82. Grossberg, S.: Studies of Mind and Brain. Dordrecht, Holland, (1982)
- Gun03. Gunion, J.F.: Class Notes on Path-Integral Methods. U.C. Davis, 230B, 2003.
- Hak93. Haken, H.: Advanced Synergetics: Instability Hierarchies of Self-Organizing Systems and Devices (3rd ed.). Springer, Berlin, (1993)
- Hak02. Haken, H.: Brain Dynamics, Synchronization and Activity Patterns in Pulse-Codupled Neural Nets with Delays and Noise, Springer, New York, (2002)
- Ham82. Hamilton, R.S.: Three-manifolds with positive Ricci curvature, *J. Differential Geom.* **17**, 255–306, (1982)
- Has98. Has, S.: Humanoid robots in Waseda University: Hadaly-2 and Wabian. In IARP First International Workshop on Humanoid and Human Friendly Robotics, 1–2, Waseda Univ., Waseda, (1998)
- Hat02. Hatcher, A. Algebraic Topology. Cambridge Univ. Press, Cambridge, (2002)
- Hat77a. Hatze, H.: A myocybernetic control model of skeletal muscle. *Biol. Cyber.* **25**, 103–119, (1977)
- Hat77b. Hatze, H.: A complete set of control equations for the human musculoskeletal system. *J. Biomech.* **10**, 799–805, (1977b)
- Hat78. Hatze, H.: A general myocybernetic control model of skeletal muscle. *Biol. Cyber.*, **28**, 143–157, (1978)
- HSK92. Hauser, J., Sastry, S., Kokotovic, P.: Nonlinear control via approximate input–output linearization: The ball and beam example, *IEEE Trans. Aut. Con.*, AC-37, 392–398, (1992)
- Heb49. Hebb, D.O.: The Organization of Behaviour. Wiley, New York, (1949)
- Hel01. Helgason, S.: Differential Geometry, Lie Groups and Symmetric Spaces. (2nd ed.) American Mathematical Society, Providence, RI, (2001)
- Hil38. Hill, A.V.: The heat of shortening and the dynamic constants of muscle, *Proc. R. Soc. B*, **76**, 136–195, (1938)

- Hir76. Hirsch, M.W.: *Differential Topology*. Springer, New York, (1976)
- HH52. Hodgkin, A.L., Huxley, A.F.: A quantitative description of membrane current and application to conduction and excitation in nerve. *J. Physiol.*, **117**, 500–544, (1952)
- Hod64. Hodgkin, A.L.: *The Conduction of the Nervous Impulse*. Liverpool Univ. Press, Liverpool, (1964)
- Hou79. Houk, J.C.: Regulation of stiffness by skeleto-motor reflexes. *Ann. Rev. Physiol.*, **41**, 99–114, (1979)
- HBB96. Houk, J.C., Buckingham, J.T., Barto, A.G.: Models of the cerebellum and motor learning. *Behavioral and Brain Sciences*, **19**(3), 368–383, (1996)
- Hux57. Huxley, A.F.: Muscle structure and theories of contraction. *Progr. Biophys. Chem.*, **7**, 255–328, (1957)
- HN54. Huxley, A.F., Niedergerke, R.: Changes in the cross-striations of muscle during contraction and stretch and their structural interpretation. *Nature*, **173**, 973–976, (1954)
- HT93. Hunt, L, Turi, J.: A new algorithm for constructing approximate transformations for nonlinear systems. *IEEE Trans. Aut. Con.*, AC-38, 1553–1556, (1993)
- Hur93. Hurmuzlu, Y.: Dynamics of bipedal gait. *J. Appl. Mech.*, **60**, 331–343, (1993)
- IN92. Igarashi, E., Nogai, T.: Study of lower level adaptive walking in the sagittal plane by a biped locomotion robot. *Advanced Robotics*, **6**, 441–459, (1992)
- Ing97. Ingber, L.: Statistical mechanics of neocortical interactions: Applications of canonical momenta indicators to electroencephalography, *Phys. Rev. E*, **55**(4), 4578–4593, (1997)
- Ing98. Ingber, L.: Statistical mechanics of neocortical interactions: Training and testing canonical momenta indicators of EEG, *Mathl. Computer Modelling* **27**(3), 33–64, (1998)
- Isi89. Isidori, A.: *Nonlinear Control Systems. An Introduction*, (2nd ed) Springer, Berlin, (1989)
- Ito60. Ito, K.: Wiener Integral and Feynman Integral. *Proc. Fourth Berkeley Symp. Math., Stat., Prob.*, **2**, 227–238, (1960)
- IS01. Ivancevic, V., Snoswell, M.: Fuzzy-stochastic functor machine for general humanoid-robot dynamics. *IEEE Trans. on Sys, Man, Cyber. B*, **31**(3), 319–330, (2001)
- Iva02. Ivancevic, V.: Generalized Hamiltonian biodynamics and topology invariants of humanoid robots. *Int. J. Mat. Mat. Sci.*, **31**(9), 555–565, (2002)
- Iva04. Ivancevic, V.: Symplectic Rotational Geometry in Human Biomechanics. *SIAM Rev.*, **46**(3), 455–474, (2004)
- IB05. Ivancevic, V., Beagley, N.: Brain-like functor control machine for general humanoid biodynamics. *Int. J. Math. Math. Sci.* (to appear) (2005)
- Iva05. Ivancevic, V.: *Dynamics of Humanoid Robots: Geometrical and Topological Duality*. To appear in *Biomathematics: Modelling and simulation* (ed. J.C. Misra), World Scientific, Singapore, (2005)

- IP01a. Ivancevic, V., Pearce, C.E.M.: Poisson manifolds in generalised Hamiltonian biomechanics. *Bull. Austral. Math. Soc.* **64**, 515–526, (2001)
- IP01b. Ivancevic, V., Pearce, C.E.M.: Topological duality in humanoid robot dynamics. *ANZIAM J.* **43**, 183–194, (2001)
- IP05b. Ivancevic, V., Pearce, C.E.M.: Hamiltonian dynamics and Morse topology of humanoid robots. *Gl. J. Mat. Math. Sci.* (to appear) (2005)
- Iva91. Ivancevic, V.: Introduction to Biomechanical Systems: Modelling, Control and Learning (in Serbian). Scientific Book, Belgrade, (1991)
- ILI95. Ivancevic, V., Lukman, L., Ivancevic, T.: Selected Chapters in Human Biomechanics. Textbook (in Serbian). Univ. Novi Sad Press, Novi Sad, (1995)
- IS00. Ivancevic, V., Snoswell, M.: Torson Sports Cybernetics. Torson Group. Inc., Adelaide, (2000)
- IJB99a. Ivancevic, T., Jain, L.C., Bottema, M.: New Two-feature GBAM–Neurodynamical Classifier for Breast Cancer Diagnosis, Proc. from KES'99, IEEE Press, (1999)
- IJB99b. Ivancevic, T., Jain, L.C., Bottema, M.: A New Two-Feature FAM-Matrix Classifier for Breast Cancer Diagnosis, Proc. from KES'99, IEEE Press, (1999)
- Kac51. Kac, M.: On Some Connection between Probability Theory and Differential and Integral Equations. Proc. 2nd Berkeley Sympos. Math. Stat. and Prob., 189-215, (1951)
- KE83. Kadic, A., Edelen, D.G.B.: A Gauge theory of Dislocations and Disclinations, New York, Springer, (1983)
- Kal60. Kalman, R.E.: A new approach to linear filtering and prediction problems. *Transactions of the ASME, Ser. D, J. Bas. Eng.*, **82**, 34–45, (1960)
- Kan58. Kan, D.M.: Adjoint Functors. *Trans. Am. Math. Soc.* **89**, 294–329, (1958)
- KV98. Katic, D., Vukobratovic, M.: A neural network-based classification of environment dynamics models for compliant control of manipulation robots. *IEEE Trans. Syst., Man, Cybern., B*, **28**(1), 58–69, (1998)
- KV03a. Katic, D., Vukobratovic, M.: Advances in Intelligent Control of Robotic Systems, Book series: Microprocessor-Based and Intelligent Systems Engineering, Kluwer Acad. Pub., Dordrecht, (2003)
- KV03b. Katic, D., Vukobratovic, M.: Survey of intelligent control techniques for humanoid robots. *J. Intel. Rob. Sys.*, **37**, 117-141, (2003)
- Kla97. Klauder, J.R.: Understanding Quantization. *Found. Phys.* **27**, 1467–1483, (1997)
- Kla00. Klauder, J.R.: Beyond Conventional Quantization, Cambridge Univ. Press, Cambridge, (2000)
- Koc81. Kock, A.: Synthetic Differential Geometry, London Math.Soc. Lecture Notes Series No. 51, Cambridge Univ. Press, Cambridge, (1981)

- KR03. Kock, A., Reyes, G.E.: Some calculus with extensive quantities: wave equation. *Theory and Applications of Categories*, **11**(14), 321–336, (2003)
- KMS93. Kolar, I., Michor, P.W., Slovak, J.: *Natural Operations in Differential Geometry*. Springer, Berlin, (1993)
- KM97. Koon, W.S., Marsden, J.E.: The Hamiltonian and Lagrangian approaches to the dynamics of nonholonomic systems. *Reports on Math Phys.* **40**, 21–62, (1997)
- Kos92. Kosko, B.: *Neural Networks and Fuzzy Systems, A Dynamical Systems Approach to Machine Intelligence*. Prentice-Hall, New York, (1992)
- Kos96. Kosko, B.: *Fuzzy Engineering*. Prentice Hall, New York, (1996)
- Kre84. Krener, A.: Approximate linearization by state feedback and coordinate change, *Systems Control Lett.*, 5, 181–185, (1984)
- LP94. Langer, J., Perline, R.: Local geometric invariants of integrable evolution equations, *J. Math. Phys.*, **35**(4), 1732–1737, (1994)
- LC03. Lebedev, L.P., Cloud, M.J.: *Tensor Analysis*. World Scientific, Singapore, (2003)
- Lee00. Lee, J.M.: *Introduction to Topological Manifolds*. Springer, New York, (2000)
- Lee02. Lee, J.M.: *Introduction to Smooth Manifolds*. New York, Springer, (2002)
- LR94. Leimkuhler, B.J., Reich, S.: Symplectic integration of constrained Hamiltonian systems. *Math. Comp.* **63**, 589–605, (1994)
- Lei02. Leinster, T.: A survey of definitions of n - category. *Theor. Appl. Categ.* **10**, 1–70, (2002)
- Lei03. Leinster, T.: *Higher Operads, Higher Categories*, London Mathematical Society Lecture Notes Series, Cambridge Univ. Press, Cambridge, (2003)
- Lei04. Leinster, T.: Operads in higher-dimensional category theory. *Theor. Appl. Categ.* **12**, 73–194, (2004)
- Lew95. Lewis, A.D.: Aspects of Geometric Mechanics and Control of Mechanical Systems. Technical Report CIT-CDS 95-017 for the Control and Dynamical Systems Option, California Institute of Technology, Pasadena, CA, (1995)
- LM97. Lewis, A. D. and Murray, R. M.: Controllability of simple mechanical control systems, *SIAM J. Con. Opt.*, **35**(3), 766–790, (1997)
- Lew98. Lewis, A.D.: Affine connections and distributions with applications to nonholonomic mechanics, *Reports on Mathematical Physics*, **42**(1/2), 135–164, (1998)
- Lew99. Lewis, A.D.: When is a mechanical control system kinematic?, in Proceedings of the 38th IEEE Conf. Decis. Con., 1162–1167, IEEE, Phoenix, AZ, (1999)
- LM99. Lewis, A. D. and Murray, R. M.: Configuration controllability of simple mechanical control systems, *SIAM Review*, **41**(3), 555–574, (1999)

- Lew00a. Lewis, A.D.: Simple mechanical control systems with constraints, *IEEE Trans. Aut. Con.*, **45**(8), 1420–1436, (2000)
- LM87. Libermann, P., Marle, C.M.: *Symplectic Geometry and Analytical Mechanics*, Reidel, Dordrecht, (1987)
- Lie94. Lieh, J.: Computer oriented closed-form algorithm for constrained multibody dynamics for robotics applications. *Mechanism and Machine Theory*, **29**, 357–371, (1994)
- LR89. Lovelock, D., Rund, H.: *Tensors, Differential Forms, and Variational Principles*. Dover, (1989)
- Lu90. Lu, J.-H.: Multiplicative and affine Poisson structures on Lie groups. PhD Thesis, Berkeley Univ., Berkeley, (1990)
- Lu91. Lu, J.-H.: Momentum mappings and reduction of Poisson actions. in *Symplectic Geometry, Groupoids, and Integrable Systems*, eds.: P. Dazord and A. Weinstein, 209–225, Springer, New York, (1991)
- MacK86. MacKay, R.S.: Stability of equilibria of Hamiltonian systems. In *Nonlinear Phenomena and Chaos* (S. Sarkar, ed.), 254–270, Hilger, Bristol, (1986)
- MacL71. MacLane, S.: *Categories for the Working Mathematician*. Springer, New York, (1971)
- MS98. Mangiarotti, L., Sardanashvily, G.: *Gauge Mechanics*. World Scientific, Singapore, (1998)
- Man98. Manikonda, V.: Control and Stabilization of a Class of Nonlinear Systems with Symmetry. PhD Thesis, Center for Dynamics and Control of Smart Structures, Harvard Univ., Cambridge, (1998)
- Mar98. Marieb, E.N.: *Human Anatomy and Physiology*. (4th ed.), Benjamin/Cummings, Menlo Park, CA, (1998)
- MS95. Marmo, G., Simoni, A., Stern, A.: Poisson Lie group symmetries for the isotropic rotator. *Int. J. Mod. Phys. A* **10**, 99–114, (1995)
- MR99. Marsden, J.E., Ratiu, T.S.: *Introduction to Mechanics and Symmetry: A Basic Exposition of Classical Mechanical Systems*. (2nd ed), Springer, New York, (1999)
- Mas02. Mascalchi, M. et al.: Proton MR Spectroscopy of the Cerebellum and Pons in Patients with Degenerative Ataxia, *Radiology*, **223**, 371 (2002)
- May81. Mayer, P.A.: *A Differential Geometric Formalism for the Ito Calculus*. Lecture Notes in Mathematics, vol. 851, Springer, New York, (1981)
- McC60. McConnell, A.J.: *Applications of Tensor Analysis* (2nd ed). Dover, (1960)
- MS00. Meyer, K.R., Schmidt, D.S.: From the restricted to the full three-body problem. *Trans. Amer. Math. Soc.*, **352**, 2283–2299, (2000)
- MH92. Meyer, K.R., Hall, G.R.: *Introduction to Hamiltonian Dynamical Systems and the N-body Problem*. Springer, New York, (1992)
- Mic01. Michor, P.W.: *Topics in Differential Geometry*. Lecture notes of a course in Vienna, (2001)

- Mil99. Milinković, D.: Morse homology for generating functions of Lagrangian submanifolds. *Trans. Amer. Math. Soc.* **351**(10), 3953–3974, (1999)
- Mil65. Milnor, J.: Lectures on the H–Cobordism Theorem. *Math. Notes*. Princeton Univ. Press, Princeton, (1965)
- Mil63. Milnor, J.: Morse Theory. Princeton Univ. Press, Princeton, (1963)
- MTW73. Misner, C.W., Thorne, K.S., Wheeler, J.A.: Gravitation. Freeman, San Francisco, (1973)
- MS78. Modugno, M., Stefani, G.: Some results on second tangent and cotangent spaces. *Quadernidell’ Instituto di Matematica dell’ Universit a di Lecce Q.*, **16**, (1978)
- MS03. Moroianu, A., Semmelmann, U.: Twistor forms on Kähler manifolds. *Ann. Scuola Norm. Sup. Pisa Cl. Sci.* **2**(4), 823–845, (2003)
- Mor34. Morse, M.: The Calculus of Variations in the Large. Amer. Math. Soc. Coll. Publ. No. 18, Providence, RI, (1934)
- Mou80. Mountcastle, V.N.: Medical physiology (XIV ed.), C.V. Mosby Comp., St. Louis, (1980)
- Mur97. Murray, R.M.: A Brief Introduction to Feedback Control, CDS 110, California Institute of Technology, San Diego, (1997)
- MLS94. Murray, R.M., Li, X., Sastry, S.: Robotic Manipulation, CRC Press, Boca Raton, Fl, (1994)
- Mus99. Mustafa, M.T.: Restrictions on harmonic morphisms. *Conformal Geometry and Dynamics (AMS)*, **3**, 102–115, (1999)
- Nas83. Nash, C., Sen, S.: Topology and Geometry for Physicists. Academic Press, London, (1983)
- Nay73. Nayfeh, A.H.: Perturbation Methods, Wiley, New York, (1973)
- NP77. Nicolis, G., Prigogine, I.: Self–Organization in Nonequilibrium Systems: From Dissipative Structures to Order through Fluctuations. Wiley Europe, (1977)
- NS90. Nijmeijer, H., Van der Schaft, A.J.: Nonlinear Dynamical Control Systems. Springer, New York, (1990)
- Nob62. Noble, D.: A modification of the Hodgkin–Huxley equations applicable to Purkinje fibre action and peace–maker potentials. *J. Physiol.*, **160**, 317–330, (1962)
- Olv86. Olver, P.J.: Applications of Lie Groups to Differential Equations (2nd ed.) Graduate Texts in Mathematics, vol. 107, Springer, New York, (1986)
- Pen67. Penrose, R.: Twistor algebra. *J. Math. Phys.*, **8**, 345–366, (1967)
- PR86. Penrose, R., Rindler, W.: Spinors and Space-time II. Cambr. Univ. Press, Cambridge, (1986)
- Pen89. Penrose, R.: The Emperor’s New Mind, Oxford Univ. Press, Oxford, (1989)
- Pet99. Petersen, P.: Aspects of Global Riemannian Geometry. *Bull. Amer. Math. Soc.*, **36**(3), 297–344, (1999)
- Pet98. Petersen, P.: Riemannian Geometry. Springer, New York, (1998)

- PI03. Pearce, C.E.M., Ivancevic, V.: A generalised Hamiltonian model for the dynamics of human motion. In Differential Equations and Applications, Vol. 2, Eds. Y.J. Cho, J.K. Kim and K.S. Ha, Nova Science, New York, (2003)
- PI04. Pearce, C.E.M., Ivancevic, V.: A qualitative Hamiltonian model for the dynamics of human motion. In Differential Equations and Applications, Vol. 3, Eds. Y.J. Cho, J.K. Kim and K.S. Ha, Nova Science, New York, (2004)
- PSS96. Pons, J.M., Salisbury, D.C., Shepley, L.C.: Gauge transformations in the Lagrangian and Hamiltonian formalisms of generally covariant theories. arXiv gr-qc/9612037, (1996)
- Pos86. Postnikov, M.M.: Lectures in Geometry V, Lie Groups and Lie Algebras, Mir Publ., Moscow, (1986)
- PV05. Potkonjak, V., Vukobratovic, M.: A generalized approach to modelling dynamics of human and humanoid motion, Int. J. Adv. Robot. Sys., **2**(1), pp. 21-45, (2005)
- PP98. Pratt, J., Pratt, G.: Exploiting natural dynamics in the control of a planar bipedal walking robot. In Proceedings of the 36 Annual Allerton Conference on Communication, Control, and Computing, 739–748, Allerton, (1998)
- Pry96. Prykarpatsky, A.K.: Geometric models of the Blackmore's swept volume dynamical systems and their integrability, In: Proc. of the IMACS-95, Hamburg 1995, ZAMP, **247**(5), 720–724, (1996)
- Put93. Puta, M.: Hamiltonian Mechanical Systems and Geometric Quantization, Kluwer, Dordrecht, (1993)
- Ram90. Ramond, P.: Field Theory: a Modern Primer. Addison-Wesley, Reading, (1990)
- REB03. Rani, R., Edgar, S.B., Barnes, A.: Killing Tensors and Conformal Killing Tensors from Conformal Killing Vectors. Class.Quant.Grav., **20**, 1929–1942, (2003)
- Ric93. Ricca, R.L.: Torus knots and polynomial invariants for a class of soliton equations, Chaos, **3**(1), 83–91, (1993)
- RV05. Rodic A., Vukobratovic M.: Contribution to the Integrated Control of Biped Locomotion Mechanisms Interacting With Dynamic Environment, Int. J. Adv. Robot. Sys., (in press), (2005)
- Ryd96. Ryder, L.: Quantum Field Theory. Cambridge Univ. Press, (1996)
- SRB99. Sardain, P. Rostami, M., Bessonnet, G.: An anthropomorphic biped robot: dynamic concepts and technological design. IEEE Trans. Syst. Man, Cyber. A, **28**, 823–838, (1999)
- SI89. Sastry, S.S., Isidori, A.: Adaptive control of linearizable systems. IEEE Trans. Aut. Con., **34**(11), 1123–1131, (1989)
- LGS. Lygeros, J., Godbole, D.N., Sastry, S.: Verified hybrid controllers for automated vehicles, IEEE Trans. Aut. Con., **43**, 522-539, (1998)
- Sch98. Schaal, S.: Robot learning. In M. Arbib (ed). Handbook of Brain Theory and Neural Networks (2nd ed.), MIT Press, Cambridge, (1998)

- SA98. Schaal, S., Atkeson, C.G.: Constructive incremental learning from only local information. *Neural Comput.*, **10**, 2047–2084, (1998)
- Sch99. Schaal, S.: Is imitation learning the route to humanoid robots?. *Trends Cogn. Sci.*, **3**, 233–242, (1999)
- Sch93. Schwarz, M.: Morse Homology, Birkhäuser, Basel, (1993)
- ST95. Seiler, W.M., Tucker, R.W.: Involution and constrained dynamics I: The Dirac approach, *J. Phys. A*, **28**, 4431–4451, (1995)
- Sei95. Seiler, W.M.: Involution and constrained dynamics II: The Faddeev-Jackiw approach, *J. Phys. A*, **28**, 7315–7331, (1995)
- Sei99. Seiler, W.M.: Numerical integration of constrained Hamiltonian systems using Dirac brackets. *Math. Comp.*, **68**, 661–681, (1999)
- Sem02. Semmelmann, U.: Conformal Killing forms on Riemannian manifolds. arXiv math.DG/0206117, (2002)
- Ser89. Seraji, H.: Configuration control of redundant manipulators: theory and implementation. *IEEE Trans. Rob. Aut.*, **5**, 437–443, (1989)
- SBM96. Seward, D., Bradshaw, A. and Margrave, F.: The anatomy of a humanoid robot. *Robotica*, **14**, 437–443, (1996)
- SK98. Shabanov, S.V., Klauder, J.R.: Path Integral Quantization and Riemannian-Symplectic Manifolds. *Phys.Lett. B* **435**, 343–349, (1998)
- SGL93. Shih, C.L., Gruver, W. and Lee, T.: Inverse kinematics and inverse dynamics for control of a biped walking machine. *J. Robot. Syst.*, **10**, 531–555, (1993)
- SK93. Shih, C.L. and Klein, C.A.: An adaptive gait for legged walking machines over rough terrain. *IEEE Trans. Syst. Man, Cyber. A*, **23**, 1150–1154, (1993)
- SM71. Siegel, C.L., Moser, J.K.: Lectures on Celestial Mechanics, Springer, Berlin, (1971)
- Sma60. Smale, S.: The generalized Poincaré conjecture in higher dimensions, *Bull. Amer. Math. Soc.*, **66**, 373–375, (1960)
- Sma67. Smale, S.: Differentiable dynamical systems, *Bull. Amer. Math. Soc.*, **73**, 747–817, (1967)
- SMO02. Spooner, J.T., Maggiore, M., Ordonez, R., Passino, K.M.: Stable Adaptive Control and Estimation for Nonlinear Systems: Neural and Fuzzy Approximator Techniques. Wiley, New York, (2002)
- Sti51. Steenrod, N.: The Topology of Fibre Bundles. Princeton Univ. Press, Princeton, (1951)
- Sto68. Stong, R.E.: Notes on Cobordism Theory. Princeton Univ. Press, Princeton, (1968)
- Stu99. Stuart, J.: Calculus (4th ed.). Brooks/Cole Publ., Pacific Grove, CA, (1999)
- Sun82. Sundermeyer, K.: Constrained Dynamics. Lecture Notes in Physics 169, Springer, New York, (1982)

- SW72. Sulanke, R., Wintgen P.: Differential geometry und faserbundel; bound 75, Veb. Deutscher Verlag der Wissenschaften, Berlin, (1972)
- Sus83. Sussmann, H.J.: Lie brackets and local controllability: a sufficient condition for scalar–input systems, SIAM J. Con. Opt., **21**(5), 686–713, (1983)
- Sus87. Sussmann, H.J.: A general theorem on local controllability, SIAM J. Con. Opt., **25**(1), 158–194, (1987)
- Swi75. Switzer, R.K.: Algebraic Topology – Homology and Homotopy. (in Classics in Mathematics), Springer, New York, (1975)
- SS78. Synge, J.L., Schild, A.: Tensor Calculus. Dover, (1978)
- Thi79. Thirring, W.: A Course in Mathematical Physics (in four volumes). Springer, New York, (1979)
- Tho79. Thorpe, J.A.: Elementary Topics in Differential Geometry. Springer, New York, (1979)
- TPS98. Tomlin, C., Pappas, G.J., Sastry, S.: Conflict resolution for air traffic management: A case study in multi-agent hybrid systems, IEEE Trans. Aut. Con., **43**, 509–521, (1998)
- Sma99. Van der Smagt, P.: (ed.) Self-Learning Robots. Workshop: Brainstyle Robotics, IEE, London, (1999)
- Voi02. Voisin, C.: Hodge Theory and Complex Algebraic Geometry I. Cambridge Univ. Press, Cambridge, (2002)
- VJ69. Vukobratovic, M., Juricic, D.: Contribution to the synthesis of biped gait. IEEE Trans. Biom. Eng., **16**(1), (1969)
- VJF70. Vukobratovic, M., Juricic, D., Frank, A.: On the control and stability of one class of biped locomotion systems. ASME J. Basic Eng., **3**, 328–332, (1970)
- VFJ70. Vukobratovic, M., Juricic, D., Frank, A.: On the stability of biped locomotion. IEEE Trans. Biom. Eng., **17**(1), 25–36, (1970)
- VS72. Vukobratovic, M., Stepanenko, Y.: On the stability of anthropomorphic systems. Math. Biosci. **15**, 1–37, (1972)
- VS73. Vukobratovic, M., Stepanenko, Y.: Mathematical models of general anthropomorphic systems. Math. Biosci. **17**, 191–242, (1973)
- Vuk75. Vukobratovic, M.: Legged Locomotion Robots and Anthropomorphic Mechanisms (in English). Mihailo Pupin, Belgrade, (1975); also published in Japanese, Nikkan Shimbun Ltd. Tokyo, (1975); in Russian, “MIR”, Moscow, (1976); in Chinese, Beijing, (1983)
- Vuk78. Vukobratovic, M.: Dynamics of Robots (in Japanese). Nikkan Shimbun Ltd, Tokyo, (1978)
- VP82. Vukobratovic, M., Potkonjak, V.: Scientific Fundamentals of Robotics, Vol. 1, Dynamics of Manipulation Robots: Theory and Application (in English), Springer-Verlag, (1982); also published in Japanese, extended version, Japanese Springer-Verlag, (1986); and in Chinese, Beijing, (1991)
- VS82. Vukobratovic, M., Stokic, D.: Scientific Fundamentals of Robotics, Vol. 2, Control of Manipulation Robots: Theory and

- Application (in English), Springer-Verlag, (1982); also published in Russian, "Nauka", Moskow, (1985); and in Chinese, Beijing, (1991)
- VK85a. Vukobratovic, M., Kircanski, M.: Scientific Fundamentals of Robotics, Vol. 3, Kinematics and Trajectories Synthesis of Manipulation Robots (in English), Springer-Verlag, (1985); also published in Chinese, Beijing, (1992)
- VK85b. Vukobratovic, M., Kircanski, N.: Scientific Fundamentals of Robotics, Vol. 4, Real-Time Dynamics of Manipulation Robots (in English), Springer-Verlag, (1985); also published in Chinese, Beijing, (1992)
- VSK85. Vukobratovic, M., Stokic, D., Kircanski, N.: Scientific Fundamentals of Robotics, Vol. 5, Non-Adaptive and Adaptive Control of Manipulation Robots (in English), Springer-Verlag, (1985); also published in Russian, "Mir", Moskow, (1988); and in Chinese, Beijing, (1993)
- VP85. Vukobratovic, M., Potkonjak, V.: Scientific Fundamentals of Robotics, Vol. 6, Applied Dynamics and CAD of Manipulation Robots, Springer-Verlag, (1985)
- VHI87. Vukobratovic, M., Hristic, D., Ivancevic, V.: DC-muscular hybrid joint control system. Proc. IX Int. Symp. External Control of Human Extremities, Dubrovnik, (1987)
- VBS89. Vukobratovic, M., Borovac, B., Surla, D., Stokic, D.: Scientific Fundamentals of Robotics, Vol. 7, Biped Locomotion: Dynamics, Stability, Control, and Applications. Springer-Verlag, Berlin, (1989)
- VPM03. Vukobratovic, M., Potkonjak, V., Matijevic, V.: Dynamics of Robots in Contact Tasks, Book series: Microprocessor-Based and Intelligent Systems Engineering, Kluwer Acad. Pub., Dordrecht, (2003)
- VB04. Vukobratovic, M., Borovac, B.: Zero-Moment Point – Thirty Five Years of its Life, Int. J. Humanoid Robotics, **1**(1), 157–173, (2004)
- VPR. Vukobratovic, M., Potkonjak, V., Rodic, A.: Contribution to the Dynamic Study of Humanoid Robots Interacting with Dynamic Environment. Int. J. Robotica, **22**, 439–447, (2004)
- VPT04. Vukobratovic, M., Potkonjak, V., Tzafestas, S.: Human and Humanoid Dynamics – From the Past to the Future, J. Intel. Robot. Sys., **41**, 65–84, (2004)
- VAB04. Vukobratovic, M., Andric, D., Borovac, B.: How to achieve various gait patterns from single nominal, Int. J. Adv. Robot. Sys., **1**(2), 99–108, (2004)
- VBB05. Vukobratovic M., Borovac B., Babkovic K.: Contribution to the Study of Anthropomorphism of Humanoid Robots, International Journal of Advanced Robotic Systems, in press, Int. J. Adv. Robot. Sys., (in press), (2005)
- Wei90. Weinstein, A.: Affine Poisson structures. Internat. J. Math., **1**, 343–360, (1990)

- WF45. Wheeler, J.A., Feynman, R.P.: Interaction with the Absorber as the Mechanism of Radiation. *Rev. Mod. Phys.* **17**, 157–181 (1945)
- WF49. Wheeler, J.A., Feynman, R.P.: Classical Electrodynamics in Terms of Direct Interparticle Action. *Rev. Mod. Phys.* **21**, 425–433, (1949)
- WZ98. Whiting, W.C., Zernicke, R.F.: Biomechanics of Musculoskeletal Injury, Human Kinetics, Champaign, IL, (1998)
- Whi87. Whitney, D.E.: Historical perspective and state of the art in robot force control. *Int. J. Robot. Res.*, **6**(1), 3–14, (1987)
- Wig90. Wiggins, S.: Introduction to Applied Dynamical Systems and Chaos. Springer, New York, (1990)
- Wil56. Wilkie, D.R.: The mechanical properties of muscle. *Brit. Med. Bull.*, **12**, 177–182, (1956)
- Wil93. Willmore, T.J.: Riemannian Geometry. Oxford Univ. Press, Oxford, (1993)
- Wil00. Wilson, D.: Nonlinear Control, Advanced Control Course (Student Version), Karlstad Univ., (2000)
- Wit82. Witten, E.: Supersymmetry and Morse theory. *J. Diff. Geom.*, **17**, 661–692, (1982)
- XH94. Xu, Z., Hauser, J.: Higher order approximate feedback linearization about a manifold, *J. Math. Sys. Est. Con.*, **4**, 451–465, (1994)
- XH95. Xu, Z., Hauser, J.: Higher order approximate feedback linearization about a manifold for multi-input systems, *IEEE Trans. Aut. Con.*, AC-40, 833–840, (1995)
- Yag87. Yager, R.R.: Fuzzy Sets and Applications: Selected Papers by L.A. Zadeh, Wiley, New York, (1987)
- Yan52. Yano, K.: Some remarks on tensor fields and curvature. *Ann. of Math.* **55**(2), 328–347, (1952)
- Yos84. Yoshikawa, T.: Analysis and Control of Robot Manipulators with Redundancy. In Robotics Research, Eds. M. Brady and R. Paul, 735–747, MIT Press, Cambridge, (1984)

Index

- 1-form–field, 405
Abelian category, 60
Abelian group, 39
absolute covariant derivative, 158, 164
absolute derivative, 401
abstract functor machine, 279
abstract scalar field, 432
acceleration, 83, 158, 294, 402
achieved, 378
actin, 409
action, 419
action functional, 19
action potential, 413
action principle, 18, 19, 21
action principle – path integral, 19
action-angle system of canonical coordinates, 226
action-angle variables, 202
activated, 353
activation heat, 411
active joints, 354
active state, 413
actually are, 30
adaptive control, 316
adaptive neural measure, 353
adaptive path measure, 378
adaptive sensory–motor transition amplitude, 353
adaptive signal tracking, 349
additive functor, 61
adenosine diphosphate, 418
adenosine triphosphate, 408
adjoint group action, 123
adjoint map, 114
adjunction, 52
adjustable pattern generator, 355
admissible controls, 333
admissible variation, 275
affine, 340, 386
affine connection, 160, 196, 384
affine control system, 340
affine Hamiltonian control action, 356
affine Hamiltonian control function, 354
affine Hamiltonian servo–system, 354
affine Levi–Civita connection, 219
algebra, 109
algebra homomorphism, 109
algebra of classical observables, 197
almost complex structure, 179
alpha, 30, 417
Ambrose–Singer theorem, 155
amplitude, 353
analogous, 421
antagonistic muscle–pairs, 28
anthropomorphic product–tree, 134
anti–holomorphic, 178
antiderivation, 93
approximate feedback linearization, 330
arc, 13
arc–element, 160
area functional, 242
arrows, 43
associated tensors, 395
associative composition, 42
associativity of morphisms, 43
asymptotically stable, 199, 323

- atlas, 64
- ATPase, 419
- attracting set, 200
- autogenetic, 30, 416
- autogenetic motor servo, 30, 416
- autogenetic–reflex action, 353
- autonomous dynamical systems, 11
 - back adjunction, 52
 - ball-and-socket joints, 119
 - Banach manifold, 65
 - Banach space, 65
 - base space, 72
 - basic formula of feedback control, 313
 - basin of attraction, 200
 - Bendixon’s criterion, 201
 - Betti, 46
 - Betti numbers, 46, 98, 292
 - bi-invariant differential forms, 116
 - Bianchi covariant derivative, 194, 219
 - Bianchi symmetry condition, 163
 - biholomorphism, 176
 - bijection, 44
 - bijective, 33
 - bilinear map, 185
 - binormal, 402
 - biological images, 378
 - biomechanical action, 235
 - biomechanical bundles, 66
 - biomechanics functor machine, 279
 - biomechanics homology group, 311
 - body–fixed frame, 211
 - bone fractures, 286
 - Bott periodicity, 73
 - boundary, 15, 62
 - boundary operator, 298
 - brain–like control functor, 357
 - brain–motor–controller, 136
 - Brouwer degree, 168
 - Brownian dynamics, 278
 - bundle of cellular electrodynamic flux tubes, 381
 - Burgers dynamical system, 155
 - calculus of variations, 18
 - Campbell–Baker–Hausdorff, 105
 - canonical coordinates, 196
 - canonical formulation, 427
 - canonical transformation, 186
 - Cartan magic formula, 107
 - Cartan theorem, 152
 - Cartesian axes, 8
 - Cartesian coordinate basis, 397
 - Cartesian product, 33, 38
 - Casimir form, 228
 - Casimir functions, 260
 - categorification, 55
 - category, 43, 276
 - category of Lie groups, 66, 306
 - category of smooth manifolds, 309
 - category of vector bundles, 309
 - Cauchy’s theorem, 208
 - Cauchy–Riemann equations, 176
 - cerebellar electrical potential, 357
 - cerebellar level, 352
 - cerebellar models, 358
 - cerebellar sensory–motor amplitude, 356
 - cerebellar sensory–motor transition probability, 356
 - cerebellum, 136, 352, 354
 - chain complex, 61
 - chain rule, 32, 68, 95
 - Chapman–Kolmogorov law, 79, 86
 - characteristic distribution, 330
 - charge, 380
 - Chern–Simons quantum mechanics, 259
 - Christoffel symbols, 160, 219, 386, 399
 - class of objects, 43
 - classical biomechanical action, 235
 - classical muscular mechanics, 383
 - closed, 15
 - closed form, 62, 95
 - closed path, 36
 - closed-loop nonlinear system, 327
 - coadjoint group action, 123
 - cobasis, 90
 - coboundary, 62
 - coboundary operators, 289
 - cochain complex, 62
 - cocomplete category, 52
 - cocycle, 62
 - cocycle condition, 70
 - codifferential, 101
 - codomain, 33, 43
 - coframing, 90
 - cofunctor, 46
 - cohomologous, 70

- cohomology class, 18
- cohomology exact sequence, 290
- cohomology object, 62
- coimage, 60
- cokernel, 60
- colimit, 51, 52
- collision detection, 151
- commensurate, 202
- commutative diagram, 43
- commutative diagrams of arrows, 37
- commutative flow, 38
- commutator, 220
- compact, 35
- compactness, 35
- complete subcategory, 44
- completely integrable Hamiltonian system, 151
- complex, 95
- complex manifold, 176
- complex phase-space manifold, 205
- complex structure, 176
- complex vector bundle, 178
- complexified tangent space, 177
- components, 36
- composition, 32
- conatural projection, 68
- concave–hyperbolic, 389
- configuration manifold, 9, 63, 407
- configuration space, 191
- conflict resolution manœuvres, 126
- conformal Killing forms, 182
- conformal Killing tensor–field, 183
- conformal Killing vector–fields, 181
- conformal Killing–Riemannian geometry, 181
- conformal Landau–Ginzburg model, 381
- conformal symmetry of the manifold, 181
- conformal twistor, 181
- conformal vector, 183
- conformal vector–field, 182
- conformal vector–fields, 182
- conformally covariant twistor equation, 181
- Conley’s continuation principle, 298
- connected, 36
- connectedness, 35
- connection, 158, 159, 386
- connection homotopy, 163
- conservation law, 22, 243
- conservation of angular momentum, 22
- conservation of electric charge, 24
- conservation of energy, 22
- conservation of linear momentum, 22
- conservative Hamiltonian biomechanics, 407
- conservative particle, 7
- constant of motion, 198
- constrained Hamilton–d’Alembert equations, 253
- constrained variational calculus, 257
- constrained variational principle, 251
- contact
 - form, 244
 - manifold, 245, 246
- contact manifold, 244
- contact transformations, 243
- continual time systems, 318
- continual–sequential state equation, 279
- continuity, 34
- continuous deformation, 34
- continuous–time regularization, 426
- contractile elements, 408
- contraction, 5, 28, 89
- contraction dynamics, 413
- contravariant acceleration functor, 189
- contravariant functor, 46
- contravariant Hom–functor, 48
- contravariant Lagrangian dynamics, 276
- contravariant vector, 393
- control, 128
- control Hamiltonian function, 29, 407
- control outputs, 407
- control strategies, 128
- controlled Van der Pol oscillator, 329
- convergence factor, 432
- convex–ecliptic, 388
- cooperating, 133
- coordinate chart, 64
- coordinate transformation, 392
- cost of a trajectory, 129
- cotangent bundle, 68, 135, 407
- cotangent Lie algebra, 122
- cotangent map, 68
- cotangent space, 68
- counit natural transformation, 52
- coupling Hamiltonians, 354
- covariant, 391

- covariant components, 8
 covariant derivative, 387, 400
 covariant differentiation, 157
 covariant Euler–Lagrange equations, 275
 covariant force equation, 239
 covariant force functor, 188, 272, 313
 covariant force functor, 357
 covariant force law, 5, 63, 188, 191, 272, 286, 289, 313, 357, 406
 covariant form, 391, 401
 covariant functor, 46
 covariant Hom–functor, 48
 covariant inertia tensor, 10
 covariant Lagrangian equations, 12
 covariant muscular forces, 371
 covariant vector, 393
 covector, 393
 covector–field, 87
 cover, 35
 covering, 35, 66
 creatine kinase, 418
 creatine phosphate, 418
 critical path, 294
 critical point, 297
 critical points, 172
 cross bridges, 410
 cross striations, 408
 curl, 14
 curvature, 384
 curvature operator, 157, 163
 curve, 7, 63
 curve on a manifold, 66
 cycle, 62
- D’Alambert–Lagrange principle, 91
 D’Alembert’s Principle of virtual displacement, 11
 De Rham cohomology group, 18, 97, 291
 De Rham complex, 95
 De Rham differential complexes, 290
 De Rham theorem, 96, 97, 100, 291
 decomposable system, 280
 defuzzification, 369
 degree of symmetry, 182
 derivation, 14, 74
 derivative map, 85
 desired, 378
- desired response, 328
 deterministic biomechanical jerk function, 287
 deterministic chaos, 278
 diagonal functor, 48
 diffeomorphism, 44, 66
 difference, 329
 differential, 102
 differential algebraic equation, 265
 diffusion processes, 415
 dimensional neural network, 353
 dinatural transformations, 50
 Dirac bracket, 259
 Dirac equation, 182
 Dirac matrices, 109
 Dirac operator, 182
 Dirac quantum commutator, 383
 direct system, 42
 directional derivative, 102
 discrete time systems, 318
 dissipation function, 269
 dissipative Hamiltonian biomechanics, 28
 dissipative structures, 27
 distribution, 91, 336
 disturbance, 128
 divergence, 14
 domain, 31, 33, 43
 driving torque one–forms, 25, 27
 dual, 68, 87
 dual $(n - p)$ –forms, 17
 dual picture, 46
 dummy index, 391
 dynamic force–velocity relation, 411
 dynamics of the relative configuration, 127
- Eccles model of synaptic activation, 384, 415
 effective action, 114
 Einstein’s summation convention, 1
 electric current, 380
 electrical current, 379
 electrical field, 379
 electrical muscular stimulation, 372
 electrical potential, 380
 electrodynamic field action principle, 379
 electrodynamic flux tubes, 381

- element, 13
- ellipsoid of inertia, 10
- Embden–Meyerhoff pathway, 418
- endomysium, 408
- endpoint conditions, 275
- energy conservation, 24
- ensemble average, 375
- epic, 61
- epimorphism, 44
- epimorphisms, 33
- equal, 421
- equation of continuity, 403
- equation of geodesic deviation, 388
- equilibrium point, 322
- equilibrium solution, 199
- equivalence relation, 33
- equivalent muscular actuator, 417
- equivalent muscular actuators, 28, 352
- ergodic hypothesis, 375
- error function, 29
- essence of feedback control, 321
- Euclidean 3D metric tensor, 10
- Euclidean 3D space, 7, 8
- Euclidean metrics, 394
- Euler, 46
- Euler characteristics, 390
- Euler’s vector equation, 222
- Euler–Lagrange equation, 162, 192, 242, 243, 302
- Euler–Lagrange functional derivative, 148
- Euler–Lagrangian equations, 19, 21, 376
- Euler–Poincaré characteristics, 98, 292
- Euler–Poincaré equations, 195
- evolution operator, 79
- exact, 16, 60
- exact form, 62, 95
- excitation, 5, 28
- excitation dynamics, 413
- excitation model, 384
- excitation–contraction dynamics, 352
- existence of identity morphism, 43
- exponential map, 112, 120, 139
- exponentially stable, 323
- exponentially stable in the large, 323
- exponentiation, 138
- extended Hamiltonian, 261
- extended Pfaffian system , 274
- extension principle, 284
- exterior algebra, 88
- exterior derivative, 14, 93, 128
- exterior differential forms, 13
- exterior differential system, 243, 405
- exterior differential systems, 90
- exterior Maxwell equation, 380
- exterior product, 17
- external coordinates, 134
- faithful functor, 48
- Faraday, 380
- fasciculus, 408
- feedback torque one–forms, 354
- Feynman path integral, 18, 248, 375, 377
- Feynman propagator, 248
- fiber derivative, 252
- fiber–derivative, 149
- fibrations, 71
- fibre, 68, 72
- fibre bundle, 71
- fibre derivative, 306
- field, 41
- field theory, 20
- field–generated solitons, 381
- fifth–order transmission cascade, 415
- filamentary–overlap function, 413
- final object, 43
- Finsler metric, 380
- first integral, 198
- first variation, 243, 294
- first variation formula, 162, 294
- fisherman’s derivative, 102
- fixed, 435
- fixed point, 199
- flag, 91
- flow, 85, 405
- flow line, 82, 86
- flow property, 85
- fluctuating noisy uncertainty, 377
- flux, 415
- flux tubes, 381
- foliation, 337
- force, 402
- force equation, 219
- force generator, 415
- force plates, 7
- forced dissipative Hamiltonian biomechanics, 29

- forced Hamiltonian biomechanics, 407
- forced Lagrangian equation, 91
- forced transition amplitude, 21
- forgetful, 48
- form commutator, 17
- formal exponential, 86
- forward dynamics, 7
- forward kinematics, 134
- Fréchet derivative, 220
- Fredholm kernels, 382
- free Ca -ion concentration, 413
- free action, 114
- free index, 391
- Frenet–Serret formulae, 402
- Frobenius–Cartan criterion, 152
- front adjunction, 52
- full embedding, 48
- full functor, 48
- fully nonlinear control system, 321
- function, 31
- function space, 36
- functional, 242, 243, 245
- functional derivative, 19, 21, 220
- functional electrical stimulation, 371
- functional integral, 429
- functional manifold, 155
- functional of the path, 19
- functor, 46
- functor category, 49
- functor machine, 280
- functor morphism, 48
- fundamental group, 47
- fundamental groupoid, 45
- fusiform, 408
- fuzzy differential equation, 283
- fuzzy inference system, 368
- fuzzy numbers, 283
- fuzzy region of uncertainty, 284
- fuzzy set, 284
- fuzzy–stochastic biomechanical jerk function, 287
- fuzzy–stochastic transformation, 285
- Galilei group, 117
- gamma, 30, 417
- gauge fixing, 433
- gauge invariant, 433
- gauge symmetries, 259
- gauge symmetry, 24
- gauge theory, 381, 433
- Gauss map, 168
- Gauss–Bonnet formula, 157
- Gauss–Bonnet theorem, 98
- Gaussian curvature, 13, 157
- general functional transformation, 391
- general linear Lie algebra, 105
- general theory of systems, 279
- generalized chain complexes, 290
- generalized cochain complexes, 289
- generalized coordinates, 11, 63
- generalized force vector, 12
- generalized Hamiltonian biomechanics, 407
- generalized Hamiltonian control system, 407
- generalized infinitesimal symmetry, 148
- generalized Kronecker–delta symbol, 394
- generalized momenta, 22
- generalized vector–field, 147
- generalized velocity vector, 11
- generating function, 433
- geodesic, 83, 160, 162, 399
- geodesic action, 384
- geodesic deviation, 165, 387
- geodesic equation, 163, 384, 399
- geodesic flow, 194, 219, 308
- geodesically generated distribution, 345
- geodesically invariant, 345
- geometric action principle, 384, 386
- geometric isomorphism, 71
- geometrical dual, 405
- geometrodynamics, 6, 9
- global complex analysis, 205
- global geodesics problems, 292
- global solution, 86
- glucose–1–phosphate, 419
- glycolysis, 418
- goal of a control system, 315
- Godement product, 49
- Golgi tendon organs, 30, 354, 416
- gradient, 14, 85, 161
- gradient conformal Killing tensor, 183
- gradient flow, 297
- gradient force 1-forms, 276
- gradient force vector–fields, 276

- Grassmann algebra, 88
- Grassmann planes, 403
- Green's functions, 382
- Green's operator, 304
- Green's theorem, 243
- group, 39, 45
- group action, 40, 119
- group conjugation, 123
- group homomorphism, 40
- group monomorphism, 40
- groupoid, 45
- growth condition, 283
- Haar measure, 114
- Hamel equations, 195
- Hamilton's equations, 196
- Hamilton's principle, 18, 192
- Hamilton–Dirac equations, 260
- Hamilton–Poisson biomechanical system, 221
- Hamiltonian, 130
- Hamiltonian action, 187
- Hamiltonian biomechanics, 69
- Hamiltonian energy function, 196
- Hamiltonian flow, 199
- Hamiltonian function, 218
- Hamiltonian mechanical system, 196
- Hamiltonian phase–flow, 308
- Hamiltonian vector–field, 196, 217
- Hamiltonian way, 420
- harmonic, 101
- harmonic exterior differential form, 301
- harmonic oscillator, 388
- harmonic projection, 304
- harmonic representative, 304
- Hartman–Grobman theorem, 263
- heat bath, 278
- heat equation, 140, 146, 169, 303, 411
- Hebbian–like learning, 353
- Heisenberg commutation relations, 427
- Heisenberg picture, 383, 428
- hemodynamics, 404
- Hermitian metric, 178
- Hermitian position operator, 21
- Hessian, 149, 161
- hidden symmetries, 233
- Hilbert, 41
- Hilbert 19th problem, 234
- Hilbert 23rd problem, 234
- Hilbert 4th problem, 160
- Hilbert manifold, 65
- Hilbert space, 65
- hinge joints, 119
- hiper–cube \equiv neuro–muscular control space, 416
- Hodge Laplacian, 302
- Hodge star, 17, 89, 100
- Hodge theory, 302
- Hodge's theorem, 181
- Hodge–De Rham decomposition, 302
- Hodge–De Rham Laplacian, 298
- Hodgkin–Huxley HH–neuron model, 413
- Hodgkin–Huxley neural, 384
- holomorphic cotangent space, 178
- holomorphic tangent space, 178
- holonomic atlas, 74
- holonomic coframes, 75
- holonomic frames, 74
- holonomous frame field, 74
- Hom–bifunctor, 48
- homeomorphism, 44
- homeostatic neuro–muscular feedbacks, 378
- homoclinic orbits, 201
- homogenous quadratic form, 11
- homological algebra, 46
- homologous in, 208
- homology group, 46, 47
- homology object, 61
- homothetic Killing tensor, 183
- homotopic, 35
- homotopies of homotopies, 58
- homotopy, 34, 35
- homotopy axiom, 292
- homotopy classes, 36
- homotopy lifting property, 71
- homotopy of loops, 37
- homotopy operators, 96, 332
- Human Biodynamics Engine, 369
- hybrid dynamics, 278
- hyperbolic force–velocity , 29
- hyperbolic force–velocity curve, 411
- hyperbolic force–velocity relation, 270
- hyperbolic point, 199
- ideal, 41
- differential, 245

- identity, 42
- identity functor, 48
- image, 16, 60
- imprecision of measurement, or estimation, 278
- impulse torque–time relation, 270
- inclusion functor, 48
- incommensurate, 202
- independence condition, 245
- index, 90, 172
- index theorem, 296
- indirect adaptive control, 317
- inertia matrix, 403
- inertia tensor, 10
- infinite prolongation, 148
- infinitesimal generator, 120
- initial object, 43, 44
- injection, 33, 44
- inorganic phosphate, 418
- input map, 280
- input process, 280
- insertion operator, 89
- integrability, 233
- integrable mechanical systems, 381
- integrable systems, 188
- integral curve, 82, 86
- integral curves, 405
- integral element, 90
- integral manifold, 244, 245, 275, 336
- integral over all possible paths, 428
- integrands, 14
- interactions, , 432
- interior product, 89
- internal acceleration vector–field, 406
- internal force 1-form field, 406
- internal joint coordinates, 134, 405
- internal velocity vector–field, 405
- intervertebral disclinations, 286
- intervertebral dislocations, 286
- invariant, 393
- invariant tori, 201
- invariants of the dynamical system, 22
- inverse kinematics, 134
- inverse kinematics problem, 319
- inverse loop, 37
- inverse system, 42
- inverted pendulum, 313
- involution, 71, 138
- involutive closure, 336
- irreversible processes, 27
- iso–energetic paths, 240
- isolated equilibrium point, 322
- isometric steady–state contraction, 410
- isometry group, 182
- isomorphism, 44
- isotropy group, 115
- Ito quadratic cotangent bundle, 283
- Ito quadratic tangent bundle, 282
- Jacobi equation, 387
- Jacobi equation of geodesic deviation, 13, 165
- Jacobi fields, 165, 295, 387
- Jacobi flows, 387
- Jacobi identity, 109, 220
- Jacobi operator, 243
- Jacobian, 32
- Jacobian determinant, 392
- jet bifunctor, 78
- jet prolongation, 78
- jet space, 141
- jets, 244
- Kähler condition, 303
- Kähler form, 179
- Kähler manifold, 302
- Kähler metric, 179
- Kähler potential, 180
- Kähler structure, 179
- Kalman filter, 318
- Kalman regulator, 318
- kernel, 15, 60
- kernel of the operator, 434
- Killing equation, 181
- Killing form, 211
- Killing spinor–field, 182
- Killing tensor–field, 183, 233
- Killing vector–field, 232
- Killing–Yano equation, 182
- kinematic constraint distribution, 256
- kinematic singularities, 134
- kinetic energy, 11
- kinetic energy of muscular contraction, 382
- Kortevég–De Vries equation, 147, 223, 383
- Kronecker–delta, 394
- lack of memory, 278

- Lagrange multipliers, 251, 346
- Lagrange stability, 324
- Lagrange–d’Alembert principle, 251
- Lagrange–Poincaré equations, 196
- Lagrangian, 193, 242, 243, 430
- Lagrangian action formalism, 19
- Lagrangian biomechanics, 68
- Lagrangian density, 20, 376
- Lagrangian equations, 22
- Lagrangian flow, 308
- Lagrangian function, 13, 18, 19, 162
- Lagrangian–field structure, 376
- Langevin rate equations, 278
- Laplace equation, 142
- Laplace transform, 320
- Laplace–Beltrami operator, 161
- Laplacian, 18, 161
- Laplacian symmetry, 184
- latency relaxation, 411
- lateral cisternae, 408
- lattice regularization, 423
- laws of motion, 80
- Lax type representation, 151
- leaf space, 337
- least action principle, 375, 376
- Lefschetz theorem, 181
- left adjoint, 52
- left cancellable, 44
- left exact, 61
- left extension, 112
- left ideal, 109
- left invariant vector–field, 111
- left inverse, 44
- left–invariant Lagrangian, 195
- left–invariant Riemannian metric, 211
- Legendre map, 149, 230
- Legendre submanifold, 245, 246
 - transverse, 245, 246
- Legendre transformation, 252, 253, 306
- level curves, 201
- level set, 81
- Levi–Civita connection, 159
- Levi–Civita connections, 406
- Lie algebra, 105, 109, 127, 220
- Lie algebra homomorphism, 109
- Lie bracket, 104, 109
- Lie bracket property, 145
- Lie derivative, 76, 102, 131, 197
- Lie functor, 112
- Lie group, 110, 127
- Lie subalgebra, 109
- Lie–invariant geometric objects, 151
- Lie–Lagrangian biomechanics functor, 272
- Lie–Poisson bracket, 124, 220
- limit, 51, 52
- limit set, 199
- line, 13
- line bundle, 72
- line element, 385
- line integral, 14
- linear controllability, 330
- linear system, 329
- linearization, 199
- Liouville equation, 282
- Liouville measure, 269
- Liouville theorem, 224
- Liouville–Arnold theorem, 227
- Lipschitz condition, 84, 283
- local geodesic, 292
- locally accessible system, 340
- locally configuration accessible, 343
- locally configuration controllable, 343
- locally exact, 95
- loop, 36
- Lorentz force, 380
- Lorentzian spin geometry, 183
- Lyapunov criterion, 349
- Lyapunov exponent, 217
- Lyapunov function, 324
- Lyapunov function candidate, 316
- Möbius bundle, 72
- machine learning, 348
- macro–level averaging lift, 381
- macroscopic force–velocity model, 384
- macroscopic muscle–load dynamics, 411
- magnetic field, 379
- maintenance heat, 411
- Mamdani inference, 368
- manifold, 63
- manifold with boundary, 97
- manipulability measure, 134
- Markov chain, 278, 428
- Markov process, 278
- mass conservation principle, 404
- material covariant metric tensor, 238
- material metric tensor, 11, 403, 406

- matrix commutator, 105
 Maupertius action principle, 162
 Maurer–Cartan equations, 152
 maximal geodesic, 83
 maximal integral curve, 82
 maximal integral manifold, 336
 Maxwell, 380
 Maxwell electrodynamics, 379
 mean curvature, 242
 mechanical action, 382
 mechanical metric, 162
 Melnikov function, 205
 metric, 385
 metric tensor, 8, 158, 219
 microscopic sliding filament model, 383
 microscopic theory of muscular contraction, 410
 model space, 65
 module, 41
 molecular soliton model of muscular contraction, 383
 moment of inertia, 10
 momentum functions, 130
 momentum map, 120, 187, 211
 momentum map, 232
 momentum phase–space, 26, 135, 217, 406
 monic, 61
 monomorphism, 33, 44
 Moore–Penrose pseudoinverse, 392
 morphism of vector–fields, 86
 morphisms, 42
 Morse function, 172
 Morse index, 297
 Morse theory, 172
 motion capture, 7
 motion planning, 151
 motor servo, 353, 354
 multiindex, 88
 muscle fibers, 408
 muscle–fat manifold, 389
 muscular active–state element equation, 28
 muscular contraction action principle, 382
 muscular level, 352
 muscular Riemannian configuration manifold, 376
 muscular Riemannian metrics, 382
 myocybernetics, 413
 myofibrillar action propagators, 382
 myofibrils, 408
 myoglobin, 419
 myosin, 409
 n–categories, 53
 Nambu–Goto action, 436
 Nash strategies, 127
 natural equivalence, 49
 natural inclusion, 49
 natural isomorphism, 49
 natural projection, 67
 natural transformation, 48
 natural vector bundle, 75
 neural control inputs, 407
 neural path integral, 353
 neural pathways, 353
 neural phase–space path integral, 356
 neural–image coordinates, 358
 neural–image manifold, 364
 Newton’s second law, 7
 Newtonian equation of motion, 7, 382
 Noether, 46
 Noether Lagrangian symmetry, 148
 Noether symmetries, 148
 Noether theorem, 22, 243
 Noetherian module, 42
 Noetherian ring, 41
 noise, 378, 384
 non–anticipating solution, 283
 non–cooperative case, 133
 non–cooperative Nash equilibrium, 133
 non–degenerate 1–form, 244
 nondegenerate, 185
 nonholonomic rolling constraints, 254
 nonlinear affine control system, 321
 nonlinear control design, 316
 nonlinear controllability criterion, 336
 nonlinear decomposable system, 280
 nonlinear multivariate analysis, 391
 nonlinear process–functor, 280
 nonlinear Schrödinger equation, 222, 383
 nonlinear sigma model, 436
 nonlinear system behavior, 280
 nonwandering set, 200
 normal, 387
 normal bundle, 73

- normal subgroup, 40
- normal vector–field, 81
- normalization condition, 432
- normalized force across the series elastic element, 413
- normalized length of the contractile element, 413
- null object, 44
- nullity, 296
- number of degrees of freedom, 9
- numerical invariants of spaces, 46
- objects, 42
- observability map, 279
- one parameter subgroup, 112
- one–form, 14, 393
- one-to-one, 33, 44
- onto, 33, 44
- open cover, 35
- optimal cost, 130
- optimal Hamiltonian, 130
- orbit, 40, 115
- orbit space, 115
- orbitally stable, 263
- orientation, 97
- outer product, 394
- output map, 280
- output process, 280
- overall probability amplitude, 377
- overdetermined, 233
- parabolic Einstein equation, 169
- parabolic length–tension curve, 410
- parallel transport, 194, 308
- parameter update law, 349
- parameter variation, 294
- parking theorem, 335
- partial order, 33
- partially ordered set, 33
- partition functions, 357
- passive sarcomere tension, 413
- path, 36
- path components, 36
- path connected, 36
- path integral quantization, 427
- pennate, 408
- performance, 313
- perimysium, 408
- period, 98
- perturbation theory, 203
- perturbative expansion methods, 378
- Pfaff theorem, 244
- Pfaffian exterior differential system, 274
- Pfaffian system, 243
- phase space, 7
- phase trajectory, 199
- phase–space path integral, 424
- phase–space spreading effect, 269
- Philip Hall basis, 338
- piecewise smooth paths, 293
- planar rigid body, 341
- Planck constant, 375
- Poincaré, 46
- Poincaré lemma, 14, 95, 96, 291
- Poincaré–Cartan form, 246
- Poincaré–Hopf theorem, 98
- point particle, 19
- pointed set, 36
- pointed topological space, 36
- Poisson bracket, 131, 151, 197, 257
- Poisson evolution equation, 220
- Poisson manifold, 219
- Poisson tensor–field, 229
- Polyakov action, 436
- position, 420
- positional stiffness, 30, 416
- possibility distribution, 284
- potential, 7, 162
- potential energy, 12
- potential field, 19
- predecessor, 129
- principal axes of inertia, 10
- principal normal, 402
- principal planes of inertia, 10
- probabilistic transition micro–dynamics, 377
- probability, 435
- probability amplitude, 427
- prolongation, 141
- prolonged generalized vector–field, 147
- prolonged group action, 144
- pseudo–inverse, 134
- pull–back, 76
- pull–back diagram, 37
- pull–back vector bundle, 70
- push–forward, 76
- quantization, 19

- quantum biomechanical action, 235
 quantum electrodynamics, 381
 quantum evolution equation, 383
 quantum Hamiltonian operator, 383
 quantum-like adaptive control, 356
 quantum-mechanical transition
 amplitude, 430
 quantum-mechanics propagator, 428
 quotient space, 136
- radius of a circular protected zone, 128
 range, 31, 43
 rank condition, 333
 Rayleigh – Van der Pol’s dissipation
 function, 27
 reachability map, 279
 reachable set, 340
 reaction, 352
 realization problem, 280
 reciprocal activation, 354
 reciprocal inhibition, 354
 reciprocal innervation of agonists and
 inhibition of antagonists, 352
 recurrent, distributed parameter, 415
 recursive homotopy dynamics, 276
 red, 408
 reduced curvature 1-form, 156
 reduced phase-space, 188
 reduction equivalence relation, 136
 redundancy, 134
 redundant manipulator, 271
 redundant system, 392
 related vector-fields, 77
 relation, 33
 relative acceleration, 165, 387
 relative degree, 328
 relative order, 328
 representation of a category, 48
 representation of a group, 48
 representative point, 63, 405
 retraction, 44
 Ricci antisymmetric tensors, 394
 Ricci curvature, 158
 Ricci flow, 169
 Ricci tensor, 158, 163
 Riemann curvature tensor, 13, 157, 163,
 386, 395
 Riemannian kinetic energy form, 406
 Riemannian manifold, 8, 13, 89, 191
 Riemannian metric, 157, 219, 238, 394
 Riemannian metric tensor, 375
 right adjoint, 52
 right cancellable, 44
 right exact, 61
 right ideal, 109
 right inverse, 44
 rigid body, 211
 rigid body with a fixed point, 211
 ring, 40
 robotic leg, 340
 robust control, 316
 robustness, 313
 Rodrigues relation, 122
 rolling disk, 346
 rotational Hill’s parameters, 29
 rotational symplectic geome-
 try/mechanics, 25
- saddle, 127
 saddle solution, 129, 130
 safe operation, 128
 sarcolemma, 408
 sarcomere, 409
 sarcoplasm, 408
 sarcoplasmic reticulum, 408
 scalar curvature, 158, 165, 387
 scalar electrical potential, 379
 scalar function, 14
 scalar invariant, 393
 scalar potential field, 406
 scalar product, 8
 scalar-field, 396
 Schrödinger picture, 428
 Schwinger formalism, 381
 second tangent bundle, 71
 second variation, 243, 294
 second variation formula, 166, 295
 second vector bundle, 71
 second-order contravariant tensor, 394
 second-order covariant tensor, 394
 second-order mixed tensor, 394
 section, 44
 sectional curvature, 164
 sections of biomechanical bundles, 79
 self-organized, 378
 semidirect product, 125, 136
 sensory-motor integration, 352
 separatrix, 201

- servoregulatory loops, 30, 417
- set of morphisms, 43
- short exact sequence, 60
- shortening heat, 411
- shortest path, 384
- signal, 378
- similar in all animals, 355
- simple mechanical control systems, 338
- simple mechanical systems, 192
- simple statistical system, 390
- simplicial approximation, 390
- singularity, 199
- skew-symmetric, 185
- sliding filament mechanism, 410
- sliding filament model, 410
- slow fibers, 419
- small time locally controllable, 333
- small-time local controllability, 340
- smooth, 64
- smooth homomorphism, 110
- smooth manifold, 14
- smooth map, 65
- solitary model of muscular excitation-contraction, 381
- soliton, 222, 381
- source, 46, 356, 431
- space of all weighted paths, 382
- special Euclidean group in 3D space, 123
- special Euclidean group in the plane, 122
- special Euclidean group of motions, 271
- speed, 83
- spinal control level, 352
- spinal level, 352
- spindle receptors, 30, 354, 416
- spinor, 109
- spinor-fields, 181
- spray, 87
- spring constant, 388
- stability, 313
- stable, 199
- stable in the sense of Lyapunov, 322
- standard action, 430
- star-shaped, 96
- state feedback, 339
- state vector, 428
- state-space approach, 315
- stationary, 242, 243
- step size, 379
- stiffness-servo, 29
- stimulus-response-type, 372
- stochastic forces, 278
- stochastic influence, 278
- stochastic Taylor expansion, 283
- stochastic tensor bundle, 282
- stochastic transformation, 282
- Stokes formula, 14, 97
- stretch potentiation, 413
- string tension, 436
- structure equations, 171
- subgroup, 40
- submanifold immersion, 244
- sum over fields, 381
- sum over fractal geometries, 389
- sum over histories, 382
- sum-over-histories, 18
- supervising, 353
- surface integral, 14
- surjection, 33, 44
- swept volume, 151
- symmetric, 161
- symmetric affine connection, 159
- symmetric product, 344
- symmetrical load-lifting, 266
- symmetry, 243
- symmetry group, 140
- symplectic form, 185, 186
- symplectic group, 185
- symplectic Lie algebra, 125
- symplectic Lie group, 125
- symplectic manifold, 186, 196
- symplectic map, 186
- symplectic matrix, 125
- symplectomorphism, 185
- synaptic weights, 353, 378
- system dynamics, 279
- system's center of mass, 10
- T tubules, 408
- tangent, 402
- tangent bundle, 67, 72, 134
- tangent functor, 79
- tangent Lie algebra, 121
- tangent map, 66, 67
- tangent space, 66
- tangent vector, 9
- tangent vector-field, 81

- tangential, 387
- target, 46
- target set, 128
- tensor bundles, 75
- tensor contraction, 395
- tensor–field, 74, 396
- terminal object, 44
- the sectional curvature, 157
- theory of fluctuating geometries, 390
- thermodynamic partition function, 383
- thermodynamic relation, 411
- thermoelastic heat, 412
- three–form, 14
- time average, 375
- time ordered products, 433
- time–dependent flow, 80
- time–dependent Schrödinger equation, 423
- time–dependent vector–field, 86
- topological group, 111
- topological manifold, 63
- topological space, 34
- topologically dual functors, 309
- torque–jerk, 286
- torque–time, 28
- torsion, 160
- torsion free, 161
- total action, 375
- total derivative, 145
- total energy function, 407
- total space, 72
- total system’s response, 279
- trajectory, 84, 128
- transducer neurons, 414
- transformation
 - contact, 242
 - point, 242
- transformation classical, 242
- transformation gauge, 242
- transition amplitude, 19, 247, 377, 431, 435
- transition amplitude , 21
- transition entropy, 357, 383
- transition functor, 374
- transition maps, 64
- transition probability, 377
- transitive action, 114
- translational biomechanics, 7
- translational Hamiltonian equations of motion, 7
- translational vector geometry, 5
- trapping region, 200
- triad, 408
- triangular identities, 60
- trivial fibration, 72
- twistor forms, 182
- twistor operator, 182
- two–form, 14
- two–sided ideal, 109
- two–sided inverse, 44
- Tychonoff product–topology theorem, 367
- uniaxial rotational joint, 198
- uniformly asymptotically stable, 323
- uniformly bounded, 324
- uniformly stable, 323
- uniformly ultimately bounded, 324
- unique functorial relation, 304
- unique minimal geodesic, 293
- unit natural transformation, 52
- universal properties, 38, 51
- unsupervised, 378
- vacuum expectation, 433
- variation vector–field, 162
- vector bundle, 69
- vector bundle functor, 75
- vector bundle homomorphism, 69
- vector–field, 80, 396, 405
- velocity, 83, 158, 294, 420
- velocity phase–space, 26, 135, 193, 405
- vertical lift, 71, 343
- virtual displacement, 12
- virtual work, 12
- volume form, 101, 219
- volume integral, 14
- weak functorial inverse, 52
- wedge product, 88, 89
- well–posed variational problem, 274
- white muscle fibers, 408, 419
- Wick rotation, 378
- Wiener measure, 425, 426
- winding number, 207
- zero morphism, 44
- zero–sum dynamical game, 128

International Series on
**MICROPROCESSOR-BASED AND
INTELLIGENT SYSTEMS ENGINEERING**

Editor: Professor S. G. Tzafestas, National Technical University, Athens, Greece

1. S.G. Tzafestas (ed.): *Microprocessors in Signal Processing, Measurement and Control*. 1983 ISBN 90-277-1497-5
2. G. Conte and D. Del Corso (eds.): *Multi-Microprocessor Systems for Real-Time Applications*. 1985 ISBN 90-277-2054-1
3. C.J. Georgopoulos: *Interface Fundamentals in Microprocessor-Controlled Systems*. 1985 ISBN 90-277-2127-0
4. N.K. Sinha (ed.): *Microprocessor-Based Control Systems*. 1986 ISBN 90-277-2287-0
5. S.G. Tzafestas and J.K. Pal (eds.): *Real Time Microcomputer Control of Industrial Processes*. 1990 ISBN 0-7923-0779-8
6. S.G. Tzafestas (ed.): *Microprocessors in Robotic and Manufacturing Systems*. 1991 ISBN 0-7923-0780-1
7. N.K. Sinha and G.P. Rao (eds.): *Identification of Continuous-Time Systems. Methodology and Computer Implementation*. 1991 ISBN 0-7923-1336-4
8. G.A. Perdikaris: *Computer Controlled Systems. Theory and Applications*. 1991 ISBN 0-7923-1422-0
9. S.G. Tzafestas (ed.): *Engineering Systems with Intelligence. Concepts, Tools and Applications*. 1991 ISBN 0-7923-1500-6
10. S.G. Tzafestas (ed.): *Robotic Systems. Advanced Techniques and Applications*. 1992 ISBN 0-7923-1749-1
11. S.G. Tzafestas and A.N. Venetsanopoulos (eds.): *Fuzzy Reasoning in Information, Decision and Control Systems*. 1994 ISBN 0-7923-2643-1
12. A.D. Pouliezos and G.S. Stavrakakis: *Real Time Fault Monitoring of Industrial Processes*. 1994 ISBN 0-7923-2737-3
13. S.H. Kim: *Learning and Coordination. Enhancing Agent Performance through Distributed Decision Making*. 1994 ISBN 0-7923-3046-3
14. S.G. Tzafestas and H.B. Verbruggen (eds.): *Artificial Intelligence in Industrial Decision Making, Control and Automation*. 1995 ISBN 0-7923-3320-9
15. Y.-H. Song, A. Johns and R. Aggarwal: *Computational Intelligence Applications to Power Systems*. 1996 ISBN 0-7923-4075-2
16. S.G. Tzafestas (ed.): *Methods and Applications of Intelligent Control*. 1997 ISBN 0-7923-4624-6
17. L.I. Slutski: *Remote Manipulation Systems. Quality Evaluation and Improvement*. 1998 ISBN 0-7932-4822-2
18. S.G. Tzafestas (ed.): *Advances in Intelligent Autonomous Systems*. 1999 ISBN 0-7932-5580-6
19. M. Teshnehlab and K. Watanabe: *Intelligent Control Based on Flexible Neural Networks*. 1999 ISBN 0-7923-5683-7
20. Y.-H. Song (ed.): *Modern Optimisation Techniques in Power Systems*. 1999 ISBN 0-7923-5697-7
21. S.G. Tzafestas (ed.): *Advances in Intelligent Systems. Concepts, Tools and Applications*. 2000 ISBN 0-7923-5966-6

International Series on
**MICROPROCESSOR-BASED AND
INTELLIGENT SYSTEMS ENGINEERING**

22. S.G. Tzafestas (ed.): *Computational Intelligence in Systems and Control Design and Applications*. 2000 ISBN 0-7923-5993-3
23. J. Harris: *An Introduction to Fuzzy Logic Applications*. 2000 ISBN 0-7923-6325-6
24. J.A. Fernández and J. González: *Multi-Hierarchical Representation of Large-Scale Space*. 2001 ISBN 1-4020-0105-3
25. D. Katic and M. Vukobratovic: *Intelligent Control of Robotic Systems*. 2003 ISBN 1-4020-1630-1
26. M. Vukobratovic, V. Potkonjak and V. Matijevic: *Dynamics of Robots with Contact Tasks*. 2003 ISBN 1-4020-1809-6
27. M. Ceccarelli: *Fundamentals of Mechanics of Robotic Manipulation*. 2004 ISBN 1-4020-1810-X
28. V.G. Ivancevic and T.T. Ivancevic: *Human-Like Biomechanics. A Unified Mathematical Approach to Human Biomechanics and Humanoid Robotics*. 2005 ISBN 1-4020-4116-0
29. J. Harris: *Fuzzy Logic Applications in Engineering Science*. 2005 ISBN 1-4020-4077-6