

Chapter 6

THE SAMPLING PROCESS

6.3 The Sampling Theorem

6.4 Aliasing

6.5 Interrelations

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July 10, 2018

Introduction

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Introduction

- ▶ In order to process a continuous-time signal using digital signal processing methodologies, it is first necessary to convert the continuous-time signal into a discrete-time signal by applying sampling.
- ▶ Sampling obviously entails discarding part of the continuous-time signal and the question will immediately arise as to whether the sampling process will corrupt the signal.
- ▶ It turns out that under a certain condition that is part of the *sampling theorem*, the information content of the continuous-time signal can be fully preserved.

The Sampling Theorem

- ▶ The sampling theorem states:
A bandlimited signal $x(t)$ for which

$$X(j\omega) = 0 \quad \text{for } |\omega| \geq \frac{\omega_s}{2}$$

where $\omega_s = 2\pi/T$, can be uniquely determined from its values $x(nT)$.

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- ▶ Alternatively, in what amounts to the same thing, a continuous-time signal whose spectrum is zero outside the baseband (i.e., $-\omega_s/2$ to $\omega_s/2$) can, in theory, be recovered completely from an impulse-modulated version of the signal.

The Sampling Theorem *Cont'd*

- ▶ Consider a two-sided bandlimited signal whose spectrum satisfies the condition of the sampling theorem.

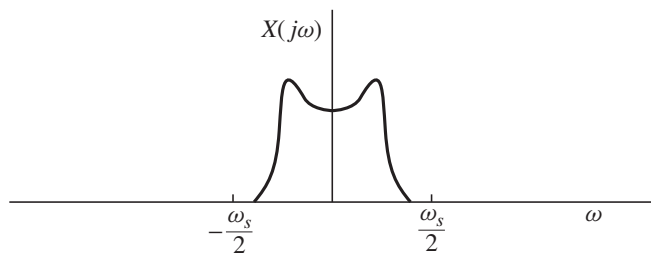
The Sampling Theorem *Cont'd*

- ▶ Consider a two-sided bandlimited signal whose spectrum satisfies the condition of the sampling theorem.
- ▶ By virtue of Poisson's summation formula, i.e.,

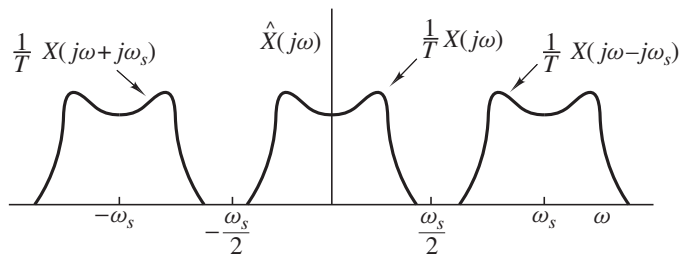
$$\hat{X}(j\omega) = \frac{1}{T} \sum_{n=-\infty}^{\infty} X(j\omega + jn\omega_s)$$

impulse modulation will produce sidebands that are well separated from one another.

The Sampling Theorem *Cont'd*



(a)



(b)

The Sampling Theorem *Cont'd*

- ▶ Now if we pass the impulse-modulated signal through an ideal lowpass filter with a frequency response

$$H(j\omega) = \begin{cases} T & \text{for } \omega < \omega_s/2 \\ 0 & \text{otherwise} \end{cases}$$

then frequencies in the sidebands will be rejected and we will be left with the frequencies in the baseband, which constitute the original continuous-time signal.

The Sampling Theorem *Cont'd*

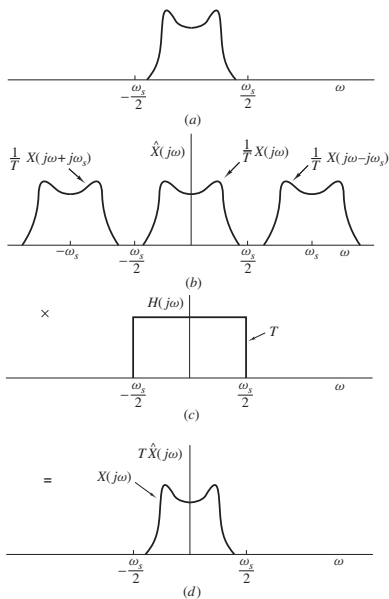
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- ▶ A baseband gain of T is used to cancel out the scaling constant $1/T$ introduced by Poisson's summation formula.

The Sampling Theorem *Cont'd*



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- ▶ What has been done through a graphical illustration can now be repeated with mathematics.

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- ▶ What has been done through a graphical illustration can now be repeated with mathematics.
- ▶ If the impulse-modulated signal is passed through a lowpass filter with a frequency response $H(j\omega)$ as defined before, then the Fourier transform of the output of the filter will be

$$Y(j\omega) = H(j\omega)\hat{X}(j\omega)$$

where

$$H(j\omega) = \begin{cases} T & \text{for } \omega < \omega_s/2 \\ 0 & \text{otherwise} \end{cases}$$

and

$$\hat{X}(j\omega) = \frac{1}{T} \sum_{n=-\infty}^{\infty} X(j\omega + jn\omega_s)$$

...

$$Y(j\omega) = H(j\omega)\hat{X}(j\omega)$$

- If we apply the inverse Fourier transform, we get

$$\begin{aligned} y(t) &= \mathcal{F}^{-1} \left[H(j\omega) \sum_{n=-\infty}^{\infty} x(nT) e^{-j\omega nT} \right] \\ &= \sum_{n=-\infty}^{\infty} x(nT) \mathcal{F}^{-1} [H(j\omega) e^{-j\omega nT}] \end{aligned} \quad (\text{A})$$

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- ▶ The frequency response of a lowpass filter is actually a frequency-domain pulse of height T and base ω_s , i.e., $H(j\omega) = T p_{\omega_s}(\omega)$ and hence from the table of Fourier transforms, we have

$$\frac{T \sin(\omega_s t/2)}{\pi t} \leftrightarrow H(j\omega) \quad (\text{B})$$

The Sampling Theorem *Cont'd*

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- From the time-shifting theorem of the Fourier transform

$$\frac{T \sin[\omega_s(t - nT)/2]}{\pi(t - nT)} \leftrightarrow H(j\omega)e^{-j\omega nT} \quad (\text{C})$$

The Sampling Theorem *Cont'd*

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- ▶ Therefore, from Eqs. (A) and (C), we conclude that

$$y(t) = \sum_{n=-\infty}^{\infty} x(nT) \frac{\sin[\omega_s(t - nT)/2]}{\omega_s(t - nT)/2}$$

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- ▶ For $t = nT$, we have $y(nT) = x(nT)$ for $n = 0, 1, \dots, kT$, and for all other values of t the output of the lowpass filter is an interpolated version of $x(t)$ according to the sampling theorem.

Aliasing

- ▶ If the spectrum of the continuous-time signal does *not* satisfy the condition imposed by the sampling theorem, i.e., if

$$X(j\omega) \neq 0 \quad \text{for } |\omega| \geq \frac{\omega_s}{2}$$

then sideband frequencies will be aliased into baseband frequencies.

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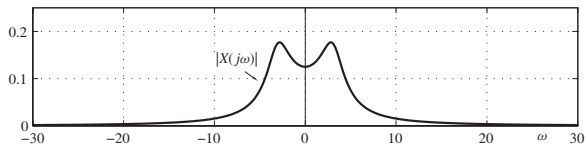
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then sideband frequencies will be aliased into baseband frequencies.

- ▶ As a result, $\hat{X}(j\omega)$ will not be equal to $X(j\omega)/T$ within the baseband.
- ▶ Under these circumstances, the use of an ideal lowpass filter will yield a distorted version of $x(t)$ at best.

- ▶ Aliasing can be illustrated by examining an impulse-modulated signal generated by sampling the continuous-time signal

$$x(t) = u(t)e^{-at} \sin \omega_0 t$$

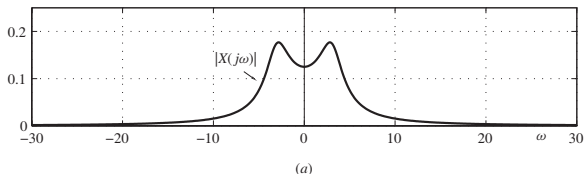


(a)

- ▶ Aliasing can be illustrated by examining an impulse-modulated signal generated by sampling the continuous-time signal

$$x(t) = u(t)e^{-at} \sin \omega_0 t$$

- ▶ The frequency spectrum of $x(t)$, $X(j\omega)$, extends over the infinite range $-\infty < \omega < \infty$.



- ▶ The frequency spectrum of impulse-modulated signal $\hat{x}(t)$ can be obtained as

$$\hat{X}(j\omega) = \frac{1}{T} \sum_{n=-\infty}^{\infty} X(j\omega + jn\omega_s)$$

by using Poisson's summation formula.

...

$$\hat{X}(j\omega) = \frac{1}{T} \sum_{n=-\infty}^{\infty} X(j\omega + jn\omega_s)$$

- ▶ The shifted copies of $X(j\omega)$ or sidebands, namely, \dots , $X(j\omega - j2\omega_s)$, $X(j\omega - j\omega_s)$, $X(j\omega + j\omega_s)$, $X(j\omega + j2\omega_s)$, \dots overlap with the baseband $-\omega_s/2 < \omega < \omega_s/2$ and, therefore, the above sum can be expressed as

$$\hat{X}(j\omega) = \frac{1}{T} [X(j\omega) + E(j\omega)]$$

where

$$E(j\omega) = \sum_{\substack{k=-\infty \\ k \neq 0}}^{\infty} X(j\omega + jk\omega_s)$$

is the contribution of the sidebands to the baseband.

- ▶ Now if we filter the impulse-modulated signal, $\hat{x}(t)$, using an ideal lowpass filter with a frequency response

$$H(j\omega) = \begin{cases} T & \text{for } -\omega_s/2 < \omega < \omega_s/2 \\ 0 & \text{otherwise} \end{cases}$$

we will get a signal $y(t)$ whose frequency spectrum is given by

$$\begin{aligned} Y(j\omega) &= H(j\omega)\hat{X}(j\omega) \\ &= H(j\omega) \cdot \frac{1}{T} \sum_{n=-\infty}^{\infty} X(j\omega + jn\omega_s) \\ &= X(j\omega) + E(j\omega) \end{aligned}$$

...

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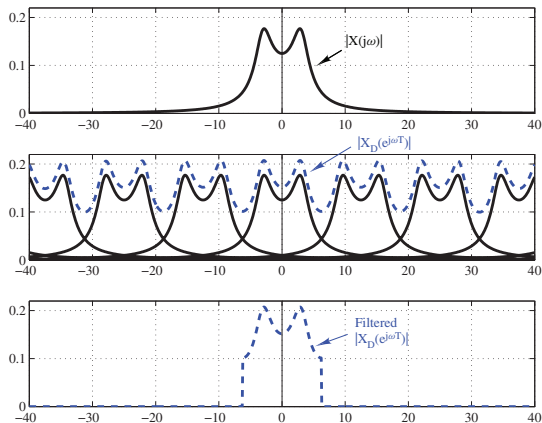
- ▶ In other words, the output of the filter will be signal $x(t)$ plus an error

$$e(t) = \mathcal{F}^{-1}E(j\omega)$$

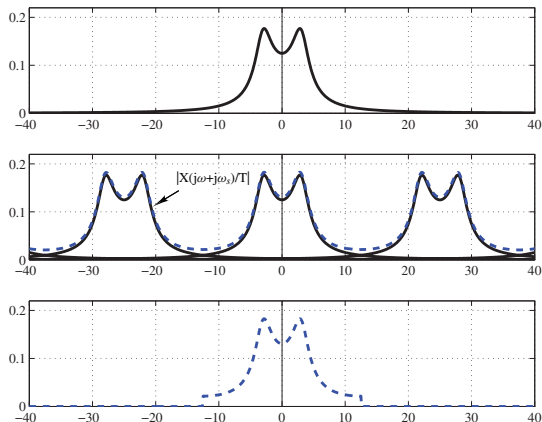
which is commonly referred to as the *aliasing error*.

Aliasing *Cont'd*

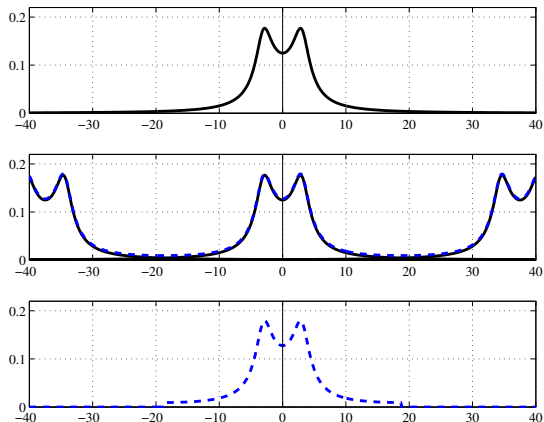
- ▶ With a sampling frequency of 12.5 rad/s, $|E(j\omega)|$, i.e., the discrepancy between the solid and dashed curves in the figure is quite large.



- ▶ As the sampling frequency is increased to 25, the sidebands are spread out and $|E(j\omega)|$ will be decreased quite a bit as shown.



- ▶ A further increase to 40 rad/s will render $|E(j\omega)|$ for all practical purposes negligible as can be seen.



Summary of Interrelations

- ▶ Impulse-modulated signal:

$$\hat{x}(t) = \sum_{n=-\infty}^{\infty} x(nT)\delta(t - nT) \quad (6.1e)$$

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- ▶ Impulse-modulated signal:

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- ▶ Spectrum of impulse-modulated signal or discrete-time signal in terms of the spectrum of the original continuous-time signal:

$$\hat{X}(j\omega) = X_D(e^{j\omega T}) = \frac{1}{T} \sum_{n=-\infty}^{\infty} X(j\omega + jn\omega_s) \quad (6.4a)$$

where

$$X_D(e^{j\omega T}) = \sum_{n=-\infty}^{\infty} x(nT)e^{-j\omega nT}$$

- ▶ Spectrum of impulse-modulated signal (or discrete-time signal) in terms of the spectrum of the original continuous-time signal for a *right-sided signal*:

$$\hat{X}(j\omega) = X_D(e^{j\omega T}) = \frac{x(0+)}{2} + \frac{1}{T} \sum_{n=-\infty}^{\infty} X(j\omega + jn\omega_s) \quad (6.4b)$$

Summary of Interrelations *Cont'd*

- ▶ Spectrum of impulse-modulated signal (or discrete-time signal) in terms of the spectrum of the original continuous-time signal for a *right-sided signal*:

$$\hat{X}(j\omega) = X_D(e^{j\omega T}) = \frac{x(0+)}{2} + \frac{1}{T} \sum_{n=-\infty}^{\infty} X(j\omega + jn\omega_s) \quad (6.4b)$$

- ▶ Laplace transform of impulse-modulated signal in terms of the Laplace transform of the original continuous-time signal for a *right-sided signal*:

$$\hat{X}(s) = X_D(z) = \frac{x(0+)}{2} + \frac{1}{T} \sum_{n=-\infty}^{\infty} X(s + jn\omega_s) \quad (6.5a)$$

where $z = e^{sT}$.

Summary of Interrelations *Cont'd*

- ▶ Recovery of a continuous-time signal by lowpass filtering an impulse-modulated signal – *frequency domain*:

$$Y(j\omega) = H(j\omega)\hat{X}(j\omega) \quad (6.7)$$

where

$$H(j\omega) = \begin{cases} T & \text{for } |\omega| < \omega_s/2 \\ 0 & \text{for } |\omega| \geq \omega_s/2 \end{cases}$$

- ▶ Recovery of a continuous-time signal by lowpass filtering an impulse-modulated signal – *frequency domain*:

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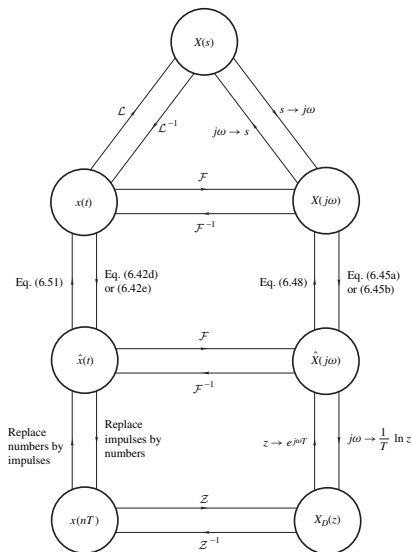
where

$$H(j\omega) = \begin{cases} T & \text{for } |\omega| < \omega_s/2 \\ 0 & \text{for } |\omega| \geq \omega_s/2 \end{cases}$$

- ▶ Recovery of a continuous-time signal by lowpass filtering an impulse-modulated signal – *time-domain*:

$$y(t) = \sum_{n=-\infty}^{\infty} x(nT) \frac{\sin[\omega_s(t - nT)/2]}{\omega_s(t - nT)/2} \quad (6.10)$$

Graphical Representation of Interrelations



*This slide concludes the presentation.
Thank you for your attention.*