Chapter 1 INTRODUCTION TO DIGITAL SIGNAL PROCESSING 1.1 Introduction 1.2 Signals

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> > July 14, 2018

Frame # 1 Slide # 1

A. Antoniou

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• Signal processing emerged soon after World War I in the form of electrical filtering.

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- To start with, a classification of the various types of signals encountered in today's technological world is provided.

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- To start with, a classification of the various types of signals encountered in today's technological world is provided.
- Then the *sampling process* is described as a means of converting analog into digital signals.

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Signals

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However, in DSP a signal is any quantity that depends on one or more independent variables.

A radio signal represents the strength of an electromagnetic wave that depends on one independent variable, namely, time.

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A video signal is made up of a series of images which change with time; thus a video signal is light intensity that depends on the distances along the x and y axes and also on the time; in effect, a video signal is a 3-dimensional signal.

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• Some signals arise naturally, others are man-made.

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Natural signals are found, for example, in:

• Acoustics, e.g., speech signals, sounds made by dolphins and whales

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- Physical sciences, e.g., signals produced by lightnings, the room temperature, the atmospheric pressure

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Man-made signals are found in:

• Audio systems, e.g., music signals

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- Control systems, e.g., feedback control signals

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- Space technology, e.g., the velocity of a space craft
- Politics, e.g., the popularity ratings of a political party
- Economics, e.g., the price of a stock at the TSX, the TSX index, the gross national product

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Two general classes of signals can be identified:

- Continuous-time signals
- Discrete-time signals

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• A *continuous-time signal* is a signal that is defined at each and every instant of time.

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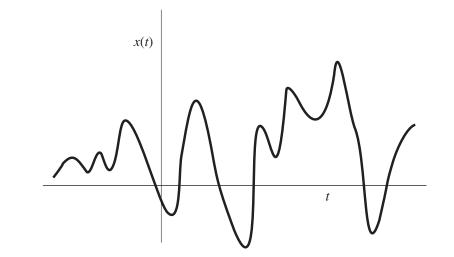
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- A *continuous-time signal* is a signal that is defined at each and every instant of time.
- Typical examples are:
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- A continuous-time signal can be represented by a function

x(t) where $-\infty < t < \infty$

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Continuous-Time Signals Cont'd



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Discrete-Time Signals

• A *discrete-time signal* is a signal that is defined at discrete instants of time.

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- Typical examples are:
 - The closing price of a particular commodity on the stock exchange
 - The daily precipitation
 - The daily temperature of a patient as recorded by a nurse

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and T is a constant.

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- The quantity x(nT) can represent a voltage or current level or any other quantity.
- In DSP, x(nT) always represents a series of numbers.

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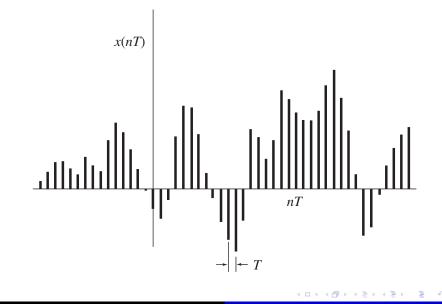
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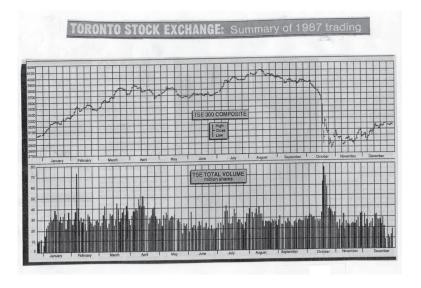
and T is a constant.

- The quantity x(nT) can represent a voltage or current level or any other quantity.
- In DSP, x(nT) always represents a series of numbers.
- Constant *T* usually represents time but it could be any other physical quantity depending on the application.

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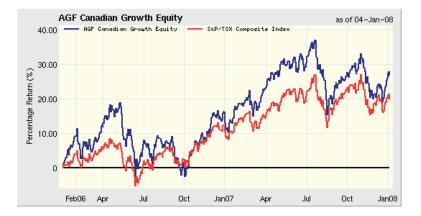


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A. Antoniou

Digital Signal Processing - Secs. 1.1, 1.2

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Note:

The signals in the previous two slides are discrete-time signals since a mutual fund or the TSX index has only one closing value per day.

They are plotted as if they were continuous-time signals for the sake of convenience.

Nonquantized and Quantized Signals

- Signals can also be classified as:
 - Nonquantized
 - Quantized

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Nonquantized and Quantized Signals

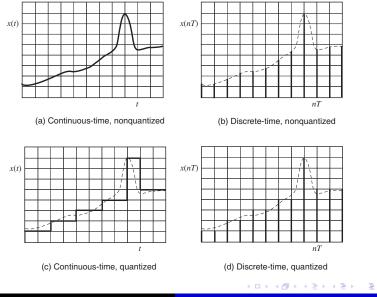
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Nonquantized and Quantized Signals

- Signals can also be classified as:
 - Nonquantized
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- A *nonquantized signal* is a signal that can assume any value within a given range, e.g., the ambient temperature.
- A *quantized signal* is a signal that can assume only a finite number of discrete values, e.g., the ambient temperature as measured by a digital thermometer.

Nonquantized and Quantized Signals Cont'd



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A. Antoniou

Digital Signal Processing – Secs. 1.1, 1.2

Alternative Notation

• A discrete-time signal x(nT) is often represented in terms of the alternative notations

x(n) and x_n

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 In the early presentations, x(nT) will be used most of the time to emphasize the fact that a discrete-time signal is typically generated by sampling a continuous-time signal x(t) at instant t = nT.

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- In the early presentations, x(nT) will be used most of the time to emphasize the fact that a discrete-time signal is typically generated by sampling a continuous-time signal x(t) at instant t = nT.
- In later presentations, the more economical notation x(n) will be used where appropriate.

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Sampling Process

To be able to process a nonquantized continuous-time signal by a digital system, we must first sample it to generate a discrete-time signal.

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- We must then quantize it to get a quantized discrete-time signal.

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Sampling Process

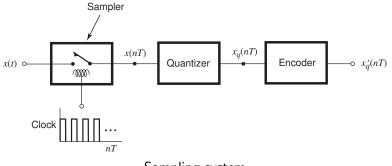
- To be able to process a nonquantized continuous-time signal by a digital system, we must first sample it to generate a discrete-time signal.
- We must then quantize it to get a quantized discrete-time signal.
- That way, we can generate a numerical representation of the signal that entails a finite amount of information.

A sampling system comprises three essential components:

- sampler
- quantizer
- encoder

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Sampling system

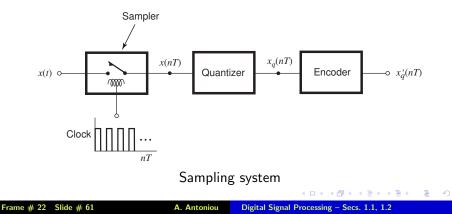
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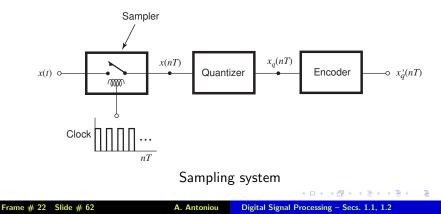
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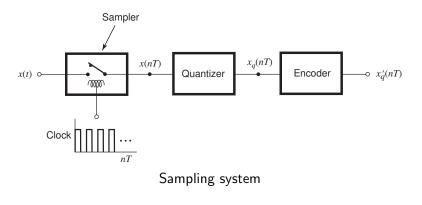
A sampler in its bare essentials is a switch controlled by a clock signal which closes momentarily every T seconds thereby transmitting the level of the input signal x(t) at instant nT, i.e., x(nT), to its output.



- A sampler in its bare essentials is a switch controlled by a clock signal which closes momentarily every T seconds thereby transmitting the level of the input signal x(t) at instant nT, i.e., x(nT), to its output.
- Parameter T is called the sampling period.

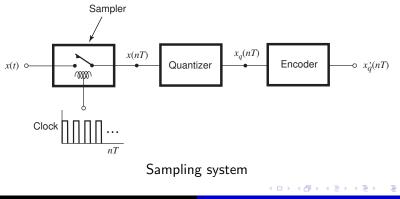


A quantizer is a device that will sense the level of its input and produce as output the nearest available level, say, xq(nT), from a set of allowed levels, i.e., a quantizer will produce a quantized continuous-time signal.

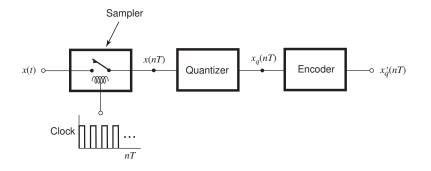


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An encoder is essentially a digital device that will sense the voltage or current level of its input and produce a corresponding binary number at its output, i.e., it will convert a quantized continuous-time signal into a corresponding discrete-time signal in binary form.

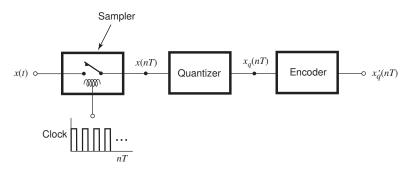


The sampling system described is essentially an analog-to-digital converter and its implementation can assume numerous forms.



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- The sampling system described is essentially an analog-to-digital converter and its implementation can assume numerous forms.
- These devices go by the acronym of A/D converter or ADC and are available in VLSI chip form as off-the-shelf devices.



A quantized discrete-time signal produced by an A/D converter is, of course, an approximation of the original nonquantized continuous-time signal.

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 - the sampling rate, and/or
 - the number of allowable quantization levels in the quantizer

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- The accuracy of the representation can be improved by increasing
 - the sampling rate, and/or
 - the number of allowable quantization levels in the quantizer
- The sampling rate is simply $1/T = f_s$ in Hz or $2\pi/T = \omega_s$ in radians per second (rad/s).

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Once a discrete-time signal is generated which is an accurate representation of the original continuous-time signal, any required processing can be performed by a digital system.

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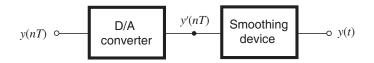
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- If the processed discrete-time signal is intended for a person, e.g., a music signal, then it must be converted back into a continuous-time signal.

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- If the processed discrete-time signal is intended for a person, e.g., a music signal, then it must be converted back into a continuous-time signal.
- Just like the sampling process, the conversion from a discreteto a continuous-signal requires a suitable *digital-to-analog interface*.

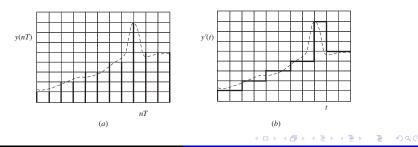
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 Typically, the digital-to-analog interface requires a series of two cascaded modules, a *digital-to-analog (or D/A) converter* and a *smoothing device:*

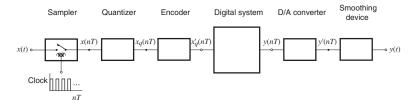


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- A D/A converter will receive an encoded digital signal in binary form like that in Fig. (a) as input and produce a corresponding quantized continuous-time signal such as that in Fig. (b).
- The stair-like nature of the quantized signal is, of course, undesirable and a D/A converter is normally followed by some type of smoothing device, typically a lowpass filter, that will eliminate the uneveness in the signal.



Complete DSP system



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- The quality of the conversion from a continuous- to a discrete-time signal and back to a continuous-time signal can be improved
 - by understanding the processes involved and/or
 - by designing the components of the sampling system carefully.

- The quality of the conversion from a continuous- to a discrete-time signal and back to a continuous-time signal can be improved
 - by understanding the processes involved and/or
 - $-\,$ by designing the components of the sampling system carefully.
- This subject will be treated at a higher level of sophistication in Chap. 6.

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Signal processing is the science of analyzing, synthesizing, sampling, encoding, transforming, decoding, enhancing, transporting, archiving, and generally manipulating signals in some way or another.

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- These presentations are concerned primarily with the branch of signal processing that entails the manipulation of the spectral characteristics of signals.

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- These presentations are concerned primarily with the branch of signal processing that entails the manipulation of the spectral characteristics of signals.
- If the processing of a signal involves modifying, reshaping, or transforming the spectrum of the signal in some way, then the processing involved is usually referred to as *filtering*.

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- If the processing of a signal involves modifying, reshaping, or transforming the spectrum of the signal in some way, then the processing involved is usually referred to as *filtering*.
- If the filtering is carried out by digital means, then it is referred to as *digital filtering*.

This slide concludes the presentation. Thank you for your attention.