#### Chapter 10 APPROXIMATIONS FOR ANALOG FILTERS 10.1 Introduction, 10.2 Realizability 10.3 to 10.7 Butterworth, Chebyshev, Inverse-Chebyshev, Elliptic, and Bessel-Thomson Approximations

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July 14, 2018

Frame # 1 Slide # 1

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  - elliptic, and
  - Bessel-Thomson approximations.
- This presentation deals with the basics of these approximations.

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- H(s) is the transfer function,
- N(s) and D(s) are polynomials in complex variable s.



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• The loss (or attenuation) is defined as

$$L(\omega^2) = \frac{|V_i(j\omega)|^2}{|V_o(j\omega)|^2} = \left|\frac{V_i(j\omega)}{V_o(j\omega)}\right|^2 = \frac{1}{|H(j\omega)|^2} = 10\log\frac{1}{H(j\omega)H(-j\omega)}$$

Hence the loss in dB is given by

$$A(\omega) = 10 \log L(\omega^2) = 10 \log \frac{1}{|H(j\omega)|^2}$$
$$= -20 \log |H(j\omega)|$$

In effect, the loss in dB is the negative of the gain in dB.

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• As a function of  $\omega$ ,  $A(\omega)$  is said to be the *loss characteristic*.

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$$heta(\omega) = \arg H(j\omega)$$
 and  $au(\omega) = -rac{d heta(\omega)}{d\omega}$ 

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Digital Signal Processing – Secs. 10.1-10.7

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• As functions of  $\omega$ ,  $\theta(\omega)$  and  $\tau(\omega)$  are the *phase response* and *delay characteristic*, respectively.

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• If we replace  $\omega$  by s/j in  $L(\omega^2)$ , we get the so-called *loss function* 

$$L(-s^2) = \frac{D(s)D(-s)}{N(s)N(-s)}$$

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$$L(-s^2) = \frac{D(s)D(-s)}{N(s)N(-s)}$$

• Thus if the transfer function of an analog filter is known, its loss function can be readily deduced.

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A. Antoniou Digital Signal Processing – Secs. 10.1-10.7

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• If

$$H(s) = \frac{N(s)}{D(s)} = \frac{\prod_{i=1}^{M} (s - z_i)}{\prod_{i=1}^{N} (s - p_i)}$$

then

$$L(-s^{2}) = \frac{D(s)D(-s)}{N(s)N(-s)} = \frac{\prod_{i=1}^{N}(s-p_{i})\prod_{i=1}^{N}(-s-p_{i})}{\prod_{i=1}^{M}(s-z_{i})\prod_{i=1}^{M}(-s-z_{i})}$$
$$= (-1)^{N-M}\frac{\prod_{i=1}^{N}(s-p_{i})\prod_{i=1}^{N}[s-(-p_{i})]}{\prod_{i=1}^{M}(s-z_{i})\prod_{i=1}^{M}[s-(-z_{i})]}$$

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- the zeros of the loss function are the poles of the transfer function and their negatives, and
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• Zero-pole plots for transfer function and loss function:



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• An *ideal lowpass* filter is one that will pass only low-frequency components. Its loss characteristic assumes the form shown in the figure.



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  - The frequency range 0 to  $\omega_c$  is the *passband*.
  - The frequency range  $\omega_c$  to  $\infty$  is the *stopband*.
  - The boundary between the passband and stopband, namely,  $\omega_c$ , is the *cutoff frequency*.



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- As in digital filters, the approximation step for the design of analog filters is the process of obtaining a realizable transfer function that would satisfy certain desirable specifications.
- In the classical solutions of the approximation problem, an ideal *normalized* lowpass loss characteristic is assumed with a cutoff frequency of order unity, i.e.,  $\omega_c \approx 1$ .
- A set of formulas are then derived that yield the *zeros and poles* or *coefficients* of the transfer function for a specified filter order.

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  - the loss is equal to or greater than  $A_a$  dB over the frequency range  $\omega_a$  to  $\infty$ .
- Parameters ω<sub>p</sub> and ω<sub>a</sub> are the *passband* and *stopband* edges,
  A<sub>p</sub> is the *maximum passband loss* (or *attenuation*), and A<sub>a</sub> is the *minimum stopband loss* (or *attenuation*), respectively.

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The quality of an approximation depends on the values of A<sub>p</sub> and A<sub>a</sub> for a given filter order, i.e., a lower A<sub>p</sub> and a larger A<sub>a</sub> correspond to a better filter.



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- These transformations will be discussed in the next presentation.

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# Realizability Constraints

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Otherwise, the transfer function would represent an unstable system.

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  - Formula for the loss as a function of the independent parameters.
  - Minimum filter order to achieve prescribed specifications.
  - Formulas for the parameters of the transfer function (e.g., zeros, poles, coefficients, multiplier constant).

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• The Butterworth approximation is derived on the assumption that the loss function  $L(-s^2)$  is a polynomial. Since

$$\lim_{s\to\infty} L(-s^2) = \lim_{\omega\to\infty} L(\omega^2) = a_0 + a_2\omega^2 + \cdots + a_{2n}\omega^{2n} \to \infty$$

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This is achieved by letting

$$L(0) = 1, \quad \frac{d^k L(x)}{dx^k}\Big|_{x=0} = 0 \text{ for } k \le n-1$$

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• Assuming that L(1) = 2, the loss function in dB can be expressed as

$$L(\omega^2) = 1 + \omega^{2n}$$
 and  $A(\omega) = 10\log(1 + \omega^{2n})$ 





Frame # 17 Slide # 54

• The loss function for the *normalized* Butterworth approximation (3-dB frequency at 1 rad/s) is given by

$$L(-s^2) = 1 + (-s^2)^n = \prod_{i=1}^{2n} (s - z_i)^n$$

where 
$$z_i = \begin{cases} e^{j(2i-1)\pi/2n} & \text{ for even } n \\ e^{j(i-1)\pi/n} & \text{ for odd } n \end{cases}$$

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Since |z<sub>k</sub>| = 1, the zeros of L(-s<sup>2</sup>) are located on the unit circle |s| = 1.

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• Zero-pole plots for loss function:



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Therefore, they are identical with the zeros of the loss function located in the left-half s plane.

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The *minimum* filter order that will satisfy the required specifications must be large enough to satisfy *both* of the following inequalities:

$$n \geq \frac{\left[-\log\left(10^{0.1A_p} - 1\right)\right]}{\left(-2\log\omega_p\right)} \quad \text{and} \quad n \geq \frac{\log\left(10^{0.1A_a} - 1\right)}{2\log\omega_a}$$

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(See textbook for derivations and examples.)

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As a result, the required specifications will usually be slightly oversatisfied.

Frame # 22 Slide # 67

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As a result, the required specifications will usually be slightly oversatisfied.

• Once the required filter order is determined, the actual maximum passband loss and minimum stopband loss can be calculated as

$$A_p = A(\omega_p) = 10\log(1+\omega_p^{2n})$$
 and  $A_a = A(\omega_a) = 10\log(1+\omega_a^{2n})$ 

respectively.

# Chebyshev Approximation

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# Chebyshev Approximation

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On the other hand, the stopband loss is very small at frequencies close to the stopband edge and very large at very high frequencies.

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# Chebyshev Approximation

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On the other hand, the stopband loss is very small at frequencies close to the stopband edge and very large at very high frequencies.

• A more balanced characteristic with respect to the passband can be achieved by employing the *Chebyshev* approximation.

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## Chebyshev Approximation Cont'd

• As in the Butterworth approximation, the loss function in the Chebyshev approximation is assumed to be a polynomial in *s*, which would assure a lowpass characteristic.

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On the basis of this assumption, a differential equation is constructed whose solution gives the zeros of the loss function.

• Then by neglecting the zeros of the loss function in the right-half *s* plane, the poles of the transfer function can be obtained.

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 In the case of a fourth-order Chebyshev filter the passband loss is assumed to be zero at ω = Ω<sub>01</sub>, Ω<sub>02</sub> and equal to A<sub>p</sub> at ω = 0, Ω<sub>1</sub>, 1 as shown in the figure:



Frame # 25 Slide # 76

Digital Signal Processing – Secs. 10.1-10.7

• On using all the information that can be extracted from the figure shown, a differential equation of the form

$$\left[\frac{dF(\omega)}{d\omega}\right]^2 = \frac{M_4[1-F^2(\omega)]}{1-\omega^2}$$

can be constructed.

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$$\left[\frac{dF(\omega)}{d\omega}\right]^2 = \frac{M_4[1-F^2(\omega)]}{1-\omega^2}$$

can be constructed.

• The solution of this differential equation gives the loss as

$$L(\omega^2) = 1 + \varepsilon^2 F^2(\omega)$$
  
where  $\varepsilon^2 = 10^{0.1A_p} - 1$   
and  $F(\omega) = T_4(\omega) = \cos(4\cos^{-1}\omega)$ 

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where

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• The function  $\cos(4\cos^{-1}\omega)$  is actually a polynomial known as the *4th-order Chebyshev* polynomial.

Frame # 26 Slide # 79

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• Similarly, for an *n*th-order Chebyshev approximation, one can show that

$$A(\omega) = 10 \log L(\omega^2) = 10 \log[1 + \varepsilon^2 T_n^2(\omega)]$$

where 
$$\varepsilon^2 = 10^{0.1A_p} - 1$$

and 
$$T_n(\omega) = egin{cases} \cos(n\cos^{-1}\omega) & \mbox{ for } |\omega| \leq 1 \ \cosh(n\cosh^{-1}\omega) & \mbox{ for } |\omega| > 1 \end{cases}$$

is the *nth-order* Chebyshev polynomial.

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• Typical loss characteristics for Chebyshev approximation:



Frame # 28 Slide # 81

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• The zeros of the loss function for a *normalized* nth-order Chebyshev approximation ( $\omega_p = 1 \text{ rad/s}$ ) are given by  $s_i = \sigma_i + j\omega_i$  where

$$\sigma_i = \pm \sinh\left(\frac{1}{n}\sinh^{-1}\frac{1}{\varepsilon}\right)\sin\frac{(2i-1)\pi}{2n}$$
$$\omega_i = \cosh\left(\frac{1}{n}\sinh^{-1}\frac{1}{\varepsilon}\right)\cos\frac{(2i-1)\pi}{2n}$$

for 
$$i = 1, 2, ..., n$$
.

Frame # 29 Slide # 82

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for 
$$i = 1, 2, ..., n$$
.

• From these equations, we note that

$$\frac{\sigma_i^2}{\sinh^2 u} + \frac{\omega_i^2}{\cosh^2 u} = 1 \quad \text{where} \quad u = \frac{1}{n} \sinh^{-1} \frac{1}{\varepsilon}$$

i.e., the zeros of  $L(-s^2)$  are located on an *ellipse*.

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Typical zero-pole plots for Chebyshev approximation:
(a) n = 5 A<sub>p</sub> = 1 dB;
(b) n = 6 A<sub>p</sub> = 1 dB.



Frame # 30 Slide # 84

A. Antoniou

Digital Signal Processing – Secs. 10.1-10.7

An *n*th-order normalized Chebyshev transfer function with a passband edge ω<sub>p</sub> = 1 rad/s and a maximum passband loss of A<sub>p</sub> dB can be determined as follows:

$$H_N(s) = \frac{H_0}{D_0(s) \prod_i^r (s - p_i)(s - p_i^*)} \\ = \frac{H_0}{D_0(s) \prod_i^r [s^2 - 2\text{Re}(p_i)s + |p_i|^2]}$$

where

$$r = \begin{cases} \frac{n-1}{2} & \text{for odd } n \\ \frac{n}{2} & \text{for even } n \end{cases} \quad \text{and} \quad D_0(s) = \begin{cases} s - p_0 & \text{for odd } n \\ 1 & \text{for even } n \end{cases}$$

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• The poles and multiplier constant,  $H_0$ , can be calculated by using the following formulas in sequence:

$$\begin{split} \varepsilon &= \sqrt{10^{0.1A_p} - 1} \\ p_0 &= \sigma_{(n+1)/2} \quad \text{with} \quad \sigma_{(n+1)/2} = -\sinh\left(\frac{1}{n}\sinh^{-1}\frac{1}{\varepsilon}\right) \\ p_i &= \sigma_i + j\omega_i \quad \text{for} \quad i = 1, 2, \dots, r \\ &\text{where} \quad \sigma_i = -\sinh\left(\frac{1}{n}\sinh^{-1}\frac{1}{\varepsilon}\right)\sin\frac{(2i-1)\pi}{2n} \\ \omega_i &= \cosh\left(\frac{1}{n}\sinh^{-1}\frac{1}{\varepsilon}\right)\cos\frac{(2i-1)\pi}{2n} \\ H_0 &= \begin{cases} -p_0\prod_{i=1}^r |p_i|^2 & \text{for odd } n \\ 10^{-0.05A_p}\prod_{i=1}^r |p_i|^2 & \text{for even } n \end{cases} \end{split}$$

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• The minimum filter order required to achieve a maximum passband loss of  $A_p$  and a minimum stopband loss of  $A_a$  must be large enough to satisfy the inequality

$$n \geq \frac{\cosh^{-1}\sqrt{D}}{\cosh^{-1}\omega_a} \quad \text{where} \quad D = \frac{10^{0.1A_a} - 1}{10^{0.1A_p} - 1}$$

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• As in the Butterworth approximation, the value at the right-hand side of the inequality must be rounded up to the next integer. As a result, the minimum stopband loss will usually be slightly oversatisfied.

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The actual minimum stopband loss can be calculated as

$$A_{a} = A(\omega_{a}) = 10 \log L(\omega_{a}^{2}) = 10 \log[1 + \varepsilon^{2} T_{n}^{2}(\omega_{a})]$$

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 In the Chebyshev approximation, the actual maximum passband loss will be exactly as specified, i.e., A<sub>p</sub>.

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# Inverse-Chebyshev Approximation

• The *inverse-Chebyshev* approximation is closely related to the Chebyshev approximation, as may be expected, and it is actually derived from the Chebyshev approximation.

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# Inverse-Chebyshev Approximation

- The *inverse-Chebyshev* approximation is closely related to the Chebyshev approximation, as may be expected, and it is actually derived from the Chebyshev approximation.
- The passband loss in the inverse-Chebyshev is very similar to that of the Butterworth approximation, i.e., it is an increasing monotonic function of  $\omega$ , while the stopband loss oscillates between infinity and a prescribed minimum loss  $A_a$ .

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 Typical loss characteristics for inverse-Chebyshev approximation:



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• The loss for the inverse-Chebyshev approximation is given by

$$A(\omega) = 10 \log \left[ 1 + rac{1}{\delta^2 T_n^2(1/\omega)} 
ight]$$

where

$$\delta^2 = \frac{1}{10^{0.1A_a} - 1}$$

and the stopband extends from  $\omega=1$  to  $\infty.$ 

Frame # 36 Slide # 94

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• The *normalized* transfer function for a specified order, *n*, stopband edge of  $\omega_a = 1$  rad/s, and minimum stopband loss,  $A_a$ , is given by

$$H_N(s) = \frac{H_0}{D_0(s)} \prod_{i=1}^r \frac{(s-1/z_i)(s-1/z_i^*)}{(s-1/p_i)(s-1/p_i^*)} \\ = \frac{H_0}{D_0(s)} \prod_{i=1}^r \frac{s^2 + \frac{1}{|z_i|^2}}{s^2 - 2\text{Re}\left(\frac{1}{|p_i}\right)s + \frac{1}{|p_i|^2}}$$

where

$$r = \begin{cases} \frac{n-1}{2} & \text{for odd } n \\ \frac{n}{2} & \text{for even } n \end{cases} \quad \text{and} \quad D_0(s) = \begin{cases} s - \frac{1}{p_0} & \text{for odd } n \\ 1 & \text{for even } n \end{cases}$$

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• The parameters of the transfer function can be calculated by using the formulas in the next slide.

$$\begin{split} \delta &= \frac{1}{\sqrt{10^{0.1A_s} - 1}}, \quad z_i = j \cos \frac{(2i - 1)\pi}{2n} \quad \text{for } 1, 2, \dots, r \\ p_0 &= \sigma_{(n+1)/2} \quad \text{with} \quad \sigma_{(n+1)/2} = -\sinh \left(\frac{1}{n} \sinh^{-1} \frac{1}{\delta}\right) \\ p_i &= \sigma_i + j\omega_i \quad \text{for } 1, 2, \dots, r \\ \text{with} \quad \sigma_i &= -\sinh \left(\frac{1}{n} \sinh^{-1} \frac{1}{\delta}\right) \sin \frac{(2i - 1)\pi}{2n} \\ \omega_i &= \cosh \left(\frac{1}{n} \sinh^{-1} \frac{1}{\delta}\right) \cos \frac{(2i - 1)\pi}{2n} \\ \omega_i &= \cosh \left(\frac{1}{n} \sinh^{-1} \frac{1}{\delta}\right) \cos \frac{(2i - 1)\pi}{2n} \\ \text{and} \quad H_0 &= \begin{cases} \frac{1}{-\rho_0} \prod_{i=1}^r \frac{|z_i|^2}{|\rho_i|^2} & \text{for odd } n \\ \prod_{i=1}^r \frac{|z_i|^2}{|p_i|^2} & \text{for even } n \end{cases} \end{split}$$

Frame # 38 Slide # 97

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for even n

• The minimum filter order required to achieve a maximum passband loss of  $A_p$  and a minimum stopband loss of  $A_a$  must be large enough to satisfy the inequality

$$n \geq rac{\cosh^{-1}\sqrt{D}}{\cosh^{-1}(1/\omega_p)}$$
 where  $D = rac{10^{0.1A_s} - 1}{10^{0.1A_p} - 1}$ 

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• The value of the right-hand side of the above inequality is rarely an integer and, therefore, it must be rounded up to the next integer. This will cause the actual maximum passband loss to be slightly oversatisfied.

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The actual maximum passband loss can be calculated as

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ho} &= \mathcal{A}(\omega_{
ho}) = 10\log\left[1 + rac{1}{\delta^2 \,\mathcal{T}_n^2(1/\omega_{
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ight] \quad ext{where} \quad \delta^2 = rac{1}{10^{0.1 \mathcal{A}_s} - 1} \end{aligned}$$

 In this approximation, the actual minimum stopband loss will be exactly as specified, i.e., A<sub>a</sub>.

Frame # 39 Slide # 101

• The Chebyshev approximation yields a much better *passband* and the inverse-Chebyshev approximation yields a much better *stopband* than the Butterworth approximation.

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- The Chebyshev approximation yields a much better *passband* and the inverse-Chebyshev approximation yields a much better *stopband* than the Butterworth approximation.
- A filter with improved *passband* and *stopband* can be obtained by using the *elliptic* approximation.

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- The Chebyshev approximation yields a much better *passband* and the inverse-Chebyshev approximation yields a much better *stopband* than the Butterworth approximation.
- A filter with improved *passband* and *stopband* can be obtained by using the *elliptic* approximation.
- The elliptic approximation is more efficient than all the other analog-filter approximations in that the transition between passband and stopband is steeper for a given approximation order.

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- The elliptic approximation is more efficient than all the other analog-filter approximations in that the transition between passband and stopband is steeper for a given approximation order.

In fact, this is the *optimal* approximation for a given piecewise constant approximation.

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# Elliptic Approximation Cont'd

• Loss characteristic for a 5th-order elliptic approximation:



Frame # 41 Slide # 106

A. Antoniou

Digital Signal Processing – Secs. 10.1-10.7

# Elliptic Approximation Cont'd

 The passband loss is assumed to oscillate between zero and a prescribed maximum A<sub>p</sub> and the stopband loss is assumed to oscillate between infinity and a prescribed minimum A<sub>a</sub>.

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# Elliptic Approximation Cont'd

- The passband loss is assumed to oscillate between zero and a prescribed maximum A<sub>p</sub> and the stopband loss is assumed to oscillate between infinity and a prescribed minimum A<sub>a</sub>.
- On the basis of the assumed structure of the loss characteristic, a differential equation is derived, as in the case of the Chebyshev approximation.

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- On the basis of the assumed structure of the loss characteristic, a differential equation is derived, as in the case of the Chebyshev approximation.
- After considerable mathematical complexity, the differential equation obtained is solved through the use of *elliptic functions*, and the parameters of the transfer function are deduced.

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- On the basis of the assumed structure of the loss characteristic, a differential equation is derived, as in the case of the Chebyshev approximation.
- After considerable mathematical complexity, the differential equation obtained is solved through the use of *elliptic functions*, and the parameters of the transfer function are deduced.

The approximation owes its name to the use of elliptic functions in the derivation.

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• The passband and stopband edges and cutoff frequency of a *normalized* elliptic approximation are defined as follows:

$$\omega_p = \sqrt{k}, \quad \omega_a = \frac{1}{\sqrt{k}}, \quad \omega_c = \sqrt{\omega_a \omega_p} = 1$$

Constants k and  $k_1$  given by

$$k = \frac{\omega_p}{\omega_a}$$
 and  $k_1 = \left(\frac{10^{0.1A_p} - 1}{10^{0.1A_a} - 1}\right)^{1/2}$ 

are known as the *selectivity* and *discrimination* constants.

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• A normalized elliptic lowpass filter with a selectivity factor k, passband edge  $\omega_p = \sqrt{k}$ , stopband edge  $\omega_a = 1/\sqrt{k}$ , a maximum passband loss of  $A_p$  dB, and a minimum stopband loss equal to or in excess of  $A_a$  dB has a transfer function of the form

$$H_N(s) = \frac{H_0}{D_0(s)} \prod_{i=1}^r \frac{s^2 + a_{0i}}{s^2 + b_{1i}s + b_{0i}}$$

where	$r = \int \frac{n-1}{2}$ for odd <i>n</i>
	$\left(\frac{n}{2}\right) = \left(\frac{n}{2}\right)$ for even $n$
and	$D_{1}(s) = \int s + \sigma_{0}$ for odd $n$
	$\mathcal{D}_0(s) = \begin{cases} 1 & \text{for even } n \end{cases}$

• (1) • (

• A normalized elliptic lowpass filter with a selectivity factor k, passband edge  $\omega_p = \sqrt{k}$ , stopband edge  $\omega_a = 1/\sqrt{k}$ , a maximum passband loss of  $A_p$  dB, and a minimum stopband loss equal to or in excess of  $A_a$  dB has a transfer function of the form

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- where  $r = \begin{cases} rac{n-1}{2} & ext{for odd } n \\ rac{n}{2} & ext{for even } n \end{cases}$  and  $D_0(s) = \begin{cases} s + \sigma_0 & ext{for odd } n \\ 1 & ext{for even } n \end{cases}$
- The parameters of the transfer function can be obtained by using the formulas in the next three slides in sequence in the order shown.

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$$\begin{split} k' &= \sqrt{1 - k^2} \\ q_0 &= \frac{1}{2} \left( \frac{1 - \sqrt{k'}}{1 + \sqrt{k'}} \right) \\ q &= q_0 + 2q_0^5 + 15q_0^9 + 150q_0^{13} \\ D &= \frac{10^{0.1A_a} - 1}{10^{0.1A_p} - 1} \\ n &\geq \frac{\log 16D}{\log(1/q)} \quad \text{(round up to the next integer)} \\ \Lambda &= \frac{1}{2n} \ln \frac{10^{0.05A_p} + 1}{10^{0.05A_p} - 1} \\ \sigma_0 &= \left| \frac{2q^{1/4} \sum_{m=0}^{\infty} (-1)^m q^{m(m+1)} \sinh[(2m+1)\Lambda]}{1 + 2 \sum_{m=1}^{\infty} (-1)^m q^{m^2} \cosh 2m\Lambda} \right| \end{split}$$

Frame # 45 Slide # 114

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$$W = \sqrt{\left(1 + k\sigma_0^2\right)\left(1 + \frac{\sigma_0^2}{k}\right)}$$

$$\Omega_i = \frac{2q^{1/4} \sum_{m=0}^{\infty} (-1)^m q^{m(m+1)} \sin \frac{(2m+1)\pi\mu}{n}}{1 + 2 \sum_{m=1}^{\infty} (-1)^m q^{m^2} \cos \frac{2m\pi\mu}{n}}$$

where 
$$\mu = \begin{cases} i & \text{for odd } n \\ i - \frac{1}{2} & \text{for even } n \end{cases}$$

$$i=1,2,\ldots,r$$

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$$V_i = \sqrt{\left(1 - k\Omega_i^2\right)\left(1 - rac{\Omega_i^2}{k}
ight)}$$

Frame # 46 Slide # 115

$$a_{0i}=rac{1}{\Omega_i^2}$$

$$b_{0i} = \frac{(\sigma_0 V_i)^2 + (\Omega_i W)^2}{(1 + \sigma_0^2 \Omega_i^2)^2}$$

$$b_{1i} = \frac{2\sigma_0 V_i}{1 + \sigma_0^2 \Omega_i^2}$$

$$H_0 = \begin{cases} \sigma_0 \prod_{i=1}^r \frac{b_{0i}}{a_{0i}} & \text{for odd } n \\ 10^{-0.05A_p} \prod_{i=1}^r \frac{b_{0i}}{a_{0i}} & \text{for even } n \end{cases}$$

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(See textbook for details.)

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- The last approximation in Chap. 10, namely, the *Bessel-Thomson approximation*, is derived on the assumption that the group delay is *maximally flat* at zero frequency.
- As in the Butterworth and Chebyshev approximations, the loss function is a polynomial. Hence the Bessel-Thomson approximation is essentially a *lowpass* approximation.

• The transfer function for a *normalized* Bessel-Thomson approximation is given by

$$H(s) = \frac{b_0}{\sum_{i=0}^{n} b_i s^i} = \frac{b_0}{s^n B(1/s)}$$
  
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- Function B(·) is a Bessel polynomial, and s<sup>n</sup>B(1/s) can be shown to have zeros in the left-half s plane, i.e., the Bessel-Thomson approximation represents stable analog filters.

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• Typical loss characteristics:



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• Typical delay characteristics:



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This slide concludes the presentation. Thank you for your attention.